# **SYSMAC CP Series**

CP1E-E□□D□-A

# **CP1E CPU Unit Hardware**

# **USER'S MANUAL**

OMRON

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# SYSMAC CP Series CP1E-E DD-A CP1E-NDD-D CP1E CPU Unit Hardware

**User's Manual** 

Revised March 2009

# Introduction

Thank you for purchasing a SYSMAC CP-series CP1E Programmable Controller.

This manual contains information required to use the CP1E. Read this manual completely and be sure you understand the contents before attempting to use the CP1E.

### **Intended Audience**

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- · Personnel in charge of installing FA systems
- · Personnel in charge of designing FA systems
- · Personnel in charge of managing FA systems and facilities

### **Applicable Products**

### CP-series CP1E CPU Units

- Basic Models CP1E-E□□D□-A
   A basic model of CPU Unit that support basic control applications using instructions such as basic, movement, arithmetic, and comparison instructions.
- Application Models CP1E-N□□D□-□
   An application model of CPU Unit that supports connections to Programmable Terminals, inverters, and servo drives.

The CP Series is centered around the CP1H, CP1L, and CP1E CPU Units and is designed with the same basic architecture as the CS and CJ Series.

Always use CP-series Expansion Units and CP-series Expansion I/O Units when expanding I/O capacity. I/O words are allocated in the same way as for the CPM1A/CPM2A PLCs, i.e., using fixed areas for inputs and outputs.

# **CP1E CPU Unit Manuals**

Information on the CP1E CPU Units is provided in the following manuals.

Refer to the appropriate manual for the information that is required.

Mounting and Setting Hardwa	CP1E CPU Unit Hardware User's Manual(Cat. No. W479)	CP1E CPU Unit Software User's Manual(Cat. No. W480	CP1E CPU Unit Instructions Reference Manual(Cat. No. W483)
	Names and specifications of the parts of all Units     Basic system configuration for each CPU Unit     Connection methods for Expansion I/O Units     and Expansion Units		
2 Wiring	· Wiring methods for the power supply		
Connecting Online to the F	Wiring methods between external I/O devices and Expansion I/O Units or Expansion Units     PLC		
4 Software Setup	Connecting Cables for CX-Programmer Support Software	Procedures for connecting the CX-Programmer Support Software	
		Software setting methods for the CP Units (PLC Setup)	U
5 Creating the P	rogram		
		Program types and basic information     CPU Unit operation     Internal memory     Built-in CPU functions     Settings	on Detailed information on programming instructions
Checking and Debugging Op	eration		
7 Maintenance a Troubleshootin		Checking I/O wiring, setting the Au settings, and performing trial opera     Monitoring and debugging with the CX-Programmer	tion
	Error codes and remedies if a problem occurs		

### **Manual Configuration**

The CP1E CPU manuals are organized in the sections listed in the following tables. Refer to the appropriate section in the manuals as required.

# **CP1E CPU Unit Hardware User's Manual (Cat. No. W479)** (This Manual)

Section	Contents
Section 1 Overview and Specifications	This section gives an overview of the CP1E, describes its features, and provides its specifications.
Section 2 Basic System Configuration and Devices	This section describes the basic system configuration and unit models of the CP1E.
Section 3 Part Names and Functions	This section describes the part names and functions of the CPU Unit, Expansion I/O Units, and Expansion Units in a CP1E PLC.
Section 4 Programming Device	This section describes the features of the CX-Programmer used for programming and debugging PLCs, as well as how to connect the PLC with the Programming Device by USB.
Section 5 Installation and Wiring	This section describes how to install and wire CP1E Units.
Section 6 Troubleshooting	This section describes how to troubleshoot problems that may occur with a CP1E PLC, including the error indications provided by the CP1E Units.
Section 7 Maintenance and Inspection	This section describes periodic inspections, the service life of the Battery, and how to replace the Battery.
Section 8 Using Expansion Units and Expansion I/O Units	This section describes application methods for Expansion Units.
Appendices	The appendices provide information on dimensions, wiring diagrams, and wiring serial communications for the CP1E.

# CP1E CPU Unit Software User's Manual (Cat. No. W480)

Section	Contents
Section 1 Overview	This section gives an overview of the CP1E, describes its application procedures.
Section 2 CPU Unit Memory	This section describes the types of internal memory in a CP1E CPU Unit and the data that is stored.
Section 3 CPU Unit Operation	This section describes the operation of a CP1E CPU Unit.
Section 4 Programming Concepts	This section provides basic information on designing ladder programs for a CP1E CPU Unit.
Section 5 I/O Memory	This section describes the types of I/O memory areas in a CP1E CPU Unit and the details.
Section 6 I/O Allocation	This section describes I/O allocation used to exchange data between the CP1E CPU Unit and other units.
Section 7 PLC Setup	This section describes the PLC Setup, which are used to perform basic settings for a CP1E CPU Unit.
Section 8 Overview and Allocation of Built-in Functions	This section lists the built-in functions and describes the overall application flow and the allocation of the functions.
Section 9 Quick-response Inputs	This section describes the quick-response inputs that can be used to read signals that are shorter than the cycle time.
Section 10 Interrupts	This section describes the interrupts that can be used with CP1E PLCs, including input interrupts and scheduled interrupts.

Section	Contents	
Section 11 High-speed Counters	This section describes the high-speed counter inputs, high-speed counter interrupts, and the frequency measurement function.	
Section 12 Serial Communications	This section describes communications with Programmable Terminals (PTs) without using communications programming, no-protocol communications with general components, and connections with a Modbus-RTU Easy Master, Serial PLC Link, and host computer.	
Section 13 Built-in Functions	This section describes PID temperature control, clock functions, DM backup functions, security functions.	
Section 14 Operating the Programming Device	This section describes basic functions of the CX-Programmer for CP1E, such as using the CX-Programmer for CP1E to write ladder programs to control the CP1E CPU Unit, to transfer the programs to the CP1E CPU Unit, and to debug the programs.	
Appendices	The appendices provide lists of the Auxiliary Area, cycle time response performance, PLC performance at power interruption.	

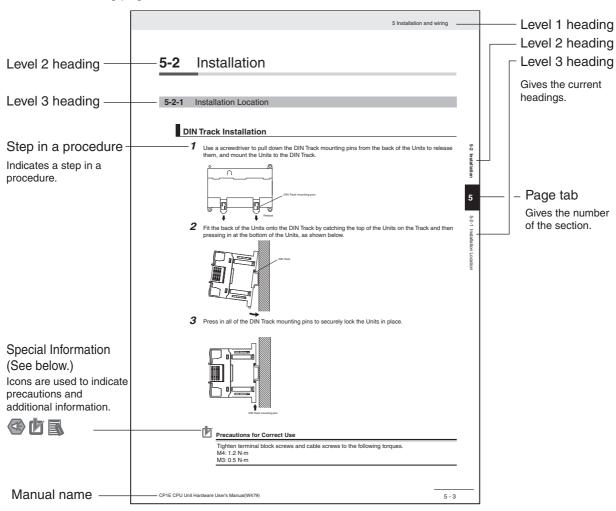
# CP1E CPU Unit Instructions Reference Manual(Cat. No. W483)

Section	Contents	
Section 1 Summary of Instructions	This section provides a summary of instructions used with a CP1E CPU Unit.	
Section 2 Instruction	This section describes the functions, operands and sample programs of the instructions that are supported by a CP1E CPU Unit.	
Section 3 Instruction Execution Times and Number of Steps	This section provides the execution times for all instructions used with a CP1E CPU Unit.	
Section 4 Monitoring and Computing the Cycle Time	This section describes how to monitor and calculate the cycle time of a CP1E CPU Unit that can be used in the programs.	
Appendices	The appendices provide a list of instructions by Mnemonic and ASCII code table for the CP1E CPU Unit.	

# **Manual Structure**

### **Page Structure and Icons**

The following page structure and icons are used in this manual.



This illustration is provided only as a sample and may not literally appear in this manual.

# **Special Information**

Special information in this manual is classified as follows:

- Precautions for Safe Use
  Precautions on what to do and what not to do to ensure using the product safely.
- Precautions for Correct Use
  Precautions on what to do and what not to do to ensure proper operation and performance.
- Additional Information

  Additional information to increase understanding or make operation easier.

# **Terminology and Notation**

Term	Description
E-type CPU Unit	A basic model of CPU Unit that support basic control applications using instructions such as basic, movement, arithmetic, and comparison instructions.
	Basic models of CPU Units are called "E-type CPU Units" in this manual.
N-type CPU Unit	An application model of CPU Unit that supports connections to Programmable Terminals, inverters, and servo drives.
	Application models of CPU Units are called "N-type CPU Units" in this manual.
CX-Programmer A programming device that applies for programming and debugging PLCs.	
	The CX-Programmer includes the CX-Programmer for CP1E and the CX-Programmer (CX-One).
	This manual describes the unique applications and functions of the CX-Programmer for CP1E.
	"CX-Programmer" refers to the CX-Programmer for CP1E in this manual.

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### Read and Understand this Manual

Please read and understand this manual before using the product. Please consult your OMRON representative if you have any questions or comments.

# Warranty and Limitations of Liability

### WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

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OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT LIABILITY.

In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

IN NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING THE PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, INSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

### **Application Considerations**

### SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

At the customer's request, OMRON will provide applicable third party certification documents identifying ratings and limitations of use that apply to the products. This information by itself is not sufficient for a complete determination of the suitability of the products in combination with the end product, machine, system, or other application or use.

The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this manual.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical
  equipment, amusement machines, vehicles, safety equipment, and installations subject to separate
  industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

### PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

### **Disclaimers**

### CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

### PERFORMANCE DATA

Performance data given in this manual is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

### **ERRORS AND OMISSIONS**

The information in this manual has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

# **Safety Precautions**

### **Definition of Precautionary Information**

The following notation is used in this manual to provide precautions required to ensure safe usage of a CP-series PLC. The safety precautions that are provided are extremely important to safety. Always read and heed the information provided in all safety precautions.



Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury. Additionally, there may be severe property damage.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

- Precautions for Safe Use Indicates precautions on what to do and what not to do to ensure using the product safely.
- Precautions for Correct Use Indicates precautions on what to do and what not to do to ensure proper operation and performance.

### **Symbols**



The triangle symbol indicates precautions (including warnings). The specific operation is shown in the triangle and explained in text. This example indicates a precaution for electric shock.



The circle and slash symbol indicates operations that you must not do. The specific operation is shown in the circle and explained in text.



The filled circle symbol indicates operations that you must do. The specific operation is shown in the circle and explained in text. This example shows a general precaution for something that you must do.



The triangle symbol indicates precautions (including warnings). The specific operation is shown in the triangle and explained in text. This example indicates a general precaution.



The triangle symbol indicates precautions (including warnings). The specific operation is shown in the triangle and explained in text. This example indicates a precaution for hot surfaces.

# **MWARNING**

Do not attempt to take any Unit apart while the power is being supplied.

Doing so may result in electric shock.



Do not touch any of the terminals or terminal blocks while the power is being supplied.

Doing so may result in electric shock.



Provide safety measures in external circuits (i.e., not in the Programmable Controller), including the following items, to ensure safety in the system if an abnormality occurs due to malfunction of the PLC or another external factor affecting the PLC operation.



Not doing so may result in serious accidents.

- Emergency stop circuits, interlock circuits, limit circuits, and similar safety measures must be provided in external control circuits.
- The PLC will turn OFF all outputs when its self-diagnosis function detects any error
  or when a severe failure alarm (FALS) instruction is executed. As a countermeasure
  for such errors, external safety measures must be provided to ensure safety in the
  system.
- The PLC outputs may remain ON or OFF due to deposition or burning of the output relays or destruction of the output transistors. As a countermeasure for such problems, external safety measures must be provided to ensure safety in the system.
- When the 24-VDC output (service power supply to the PLC) is overloaded or short-circuited, the voltage may drop and result in the outputs being turned OFF. As a countermeasure for such problems, external safety measures must be provided to ensure safety in the system.

Fail-safe measures must be taken by the customer to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes.



Serious accidents may result from abnormal operation if proper measures are not provided.

Do not apply the voltage/current outside the specified range to this unit. It may cause a malfunction or fire.



# **⚠** Caution

Be sure to sufficiently confirm the safety at the destination when you transfer the program or I/O memory or perform procedures to change the I/O memory.

Devices connected to PLC outputs may incorrectly operate regardless of the operating mode of the CPU Unit.



With an E-type CPU Unit or with an N-type CPU Unit without a Battery, the contents of the DM Area (D) \*, Holding Area (H), the Counter Present Values (C), the status of Counter Completion Flags (C), and the status of bits in the Auxiliary Area (A) related to clock functions may be unstable when the power supply is turned ON.



\*This does not apply to areas backed up to EEPROM using the DM backup function. If the DM backup function is being used, be sure to use one of the following methods for initialization.

- 1. Clearing All Areas to All Zeros
  Select the *Clear Held Memory (HR/DM/CNT) to Zero* Check Box in the *Startup Data Read* Area in the PLC Setup.
- 2. Clearing Specific Areas to All Zeros or Initializing to Specific Values Make the settings from a ladder program.

If the data is not initialized, the unit or device may operate unexpectedly because of unstable data.

Execute online edit only after confirming that no adverse effects will be caused by extending the cycle time.

Otherwise, the input signals may not be readable.



Tighten the screws on the terminal block of the AC power supply section to the torque specified in the user's manual.

The loose screws may result in burning or malfunction.



Do not touch the power supply section when power is being supplied or immediately after the power supply is turned OFF.

The power supply section and I/O terminal blocks will be hot and you may be burned.





Pay careful attention to the polarities (+/-) when wiring the DC power supply.

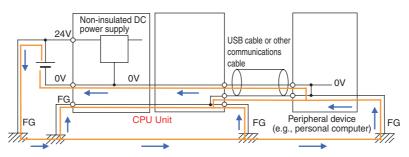
A wrong connection may cause malfunction of the system.



When connecting the PLC to a computer or other peripheral device, either ground the 0-V side of the external power supply or do not ground the external power supply at all.



Otherwise the external power supply may be shorted depending on the connection methods of the peripheral device. DO NOT ground the 24 V-side of the external power supply, as shown in the following diagram.





Use the Battery Error Flag or other measures to stop outputs if external outputs are performed from a ladder program based on the contents of the DM Area or other I/O memory areas.

Sufficiently check safety if I/O bit status or present values are monitored in the Ladder Section Pane or present values are monitored in the Watch Pane.



If bits are set, reset, force-set, or force-reset by inadvertently pressing a shortcut key, devices connected to PLC outputs may operate incorrectly regardless of the operating mode.

# Program so that the memory area of the start address is not exceeded when using a word address or symbol for the offset.



For example, write the program so that processing is executed only when the indirect specification does not cause the final address to exceed the memory area by using an input comparison instruction or other instruction.

If an indirect specification causes the address to exceed the area of the start address, the system will access data in other area, and unexpected operation may occur.

# **A** Caution

Set the temperature range according to the type of temperature sensor connected to the Unit.

Temperature data will not be converted correctly if the temperature range does not match the sensor.



Do not set the temperature range to any values other than those for which temperature ranges are given in the following table.

An incorrect setting may cause operating errors.



# **Precautions for Safe Use**

Observe the following precautions when using a CP-series PLC.

### Power Supply

- Always use the power supply voltages specified in the user's manuals. An incorrect voltage may result in malfunction or burning.
- Take appropriate measures to ensure that the specified power with the rated voltage and frequency is supplied. Be particularly careful in places where the power supply is unstable. An incorrect power supply may result in malfunction.
- Double-check all wiring and switch settings before turning ON the power supply. Incorrect wiring
  may result in burning.
- Always turn OFF the power supply to the PLC before attempting any of the following. Not turning OFF the power supply may result in malfunction or electric shock.
  - Mounting or dismounting Expansion Units or Expansion I/O Units
  - · Mounting or dismounting Option Boards
  - · Setting rotary switches
  - · Connecting cables or wiring the system
  - · Connecting or disconnecting the connectors

### Installation

- Before touching a Unit, be sure to first touch a grounded metallic object in order to discharge any static build-up. Not doing so may result in malfunction or damage.
- Be sure that the terminal blocks, connectors, Option Boards, and other items with locking devices are properly locked into place. Improper locking may result in malfunction.

### Wiring

- Wire correctly according to specified procedures in this manual.
- Always use the following size wire when connecting I/O terminals: AWG22 to AWG18 (0.32 to 0.82 mm<sup>2</sup>).
- Install external breakers and take other safety measures against short-circuiting in external wiring. Insufficient safety measures against short-circuiting may result in burning.
- Always connect to a ground of 100  $\Omega$  or less when installing the Units. Not connecting to a ground of 100  $\Omega$  or less may result in electric shock.
- Leave the label attached to the top of the Unit when wiring to prevent the entry of foreign matter. Removing the label may result in malfunction if foreign matter enters the Unit.
- Remove the label after the completion of wiring to ensure proper heat dissipation. Leaving the label attached may result in malfunction.
- Use crimp terminals for wiring. Do not connect bare stranded wires directly to terminals. Connection of bare stranded wires may result in burning.
- Do not apply voltages to the input terminals in excess of the rated input voltage. Excess voltages
  may result in burning.
- Do not apply voltages or connect loads to the output terminals in excess of the maximum switching capacity. Excess voltage or loads may result in burning.
- Disconnect the functional ground terminal when performing withstand voltage tests. Not disconnecting the functional ground terminal may result in burning.

- Be sure that all the PLC terminal screws and cable connector screws are tightened to the torque specified in the relevant manuals. The tightening torque for the terminals on the CP1W-CIF11/CIF12 terminal block is 0.28 N·m Incorrect tightening torque may result in malfunction.
- The following devices can be connected to pin 6 (+5V) on the built-in RS-232C port on the CPU
  Unit or the RS-232C Option Board (CP1W-CIF01) mounted to the CPU Unit. Do not connect pin 6
  to any other device.
  - RS-422A CJ1W-CIF11 Conversion Adapter
  - RS-232C / RS-422A NT-AL001 Conversion Adapter
- Use the cables that are specified in the manual for each device. External devices or the CPU Unit may be damaged if a commercially available RS-232C computer cable is used.
- Do not pull on the cables or bend the cables beyond their natural limit. Doing either of these may break the cables.
- Do not place objects on top of the cables or other wiring lines. Doing so may break the cables.

### Handling

- To initialize the DM Area, back up the initial contents for the DM Area to backup memory using one of the following methods.
  - Set the number of words of the DM Area to be backed up starting with D0 in the *Number of CH* of *DM for backup* Box in the *Startup Data Read* Area.
  - Include programming to back up specified words in the DM Area to built-in EEPROM by turning ON A751.15 (DM Backup Save Start Bit).
- Check the ladder program for proper execution before actually running it on the Unit. Not checking the program may result in an unexpected operation.
- The ladder program and parameter area data in the CP1E CPU Units are backed up in the built-in EEPROM backup memory. The BKUP indicator will light on the front of the CPU Unit when the backup operation is in progress. Do not turn OFF the power supply to the CPU Unit when the BKUP indicator is lit. The data will not be backed up if power is turned OFF and a memory error will occur the next time the power supply is turned ON.
- With a CP1E CPU Unit, data memory can be backed up to the built-in EEPROM backup memory.
  The BKUP indicator will light on the front of the CPU Unit when backup is in progress. Do not turn
  OFF the power supply to the CPU Unit when the BKUP indicator is lit. If the power is turned OFF
  during a backup, the data will not be backed up and will not be transferred to the DM Area in RAM
  the next time the power supply is turned ON.
- Before replacing the battery, supply power to the CPU Unit for at least 30 minutes and then complete battery replacement within 5 minutes. Memory data may be corrupted if this precaution is not observed.
- The equipment may operate unexpectedly if inappropriate parameters are set. Even if the appropriate parameters are set, confirm that equipment will not be adversely affected before transferring the parameters to the CPU Unit.
- After replacing the CPU Unit, make sure that the required data for the DM Area, Holding Area, and other memory areas has been transferred to the new CPU Unit before restarting operation.
- Do not attempt to disassemble, repair, or modify any Units. Any attempt to do so may result in malfunction, fire, or electric shock.
- Confirm that no adverse effect will occur in the system before attempting any of the following. Not doing so may result in an unexpected operation.
  - Changing the operating mode of the PLC (including the setting of the startup operating mode).
  - Force-setting/force-resetting any bit in memory.
  - Changing the present value of any word or any set value in memory.
- When replacing parts, be sure to confirm that the rating of a new part is correct. Not doing so may result in malfunction or burning.

- Do not touch the Expansion I/O Unit Connecting Cable while the power is being supplied in order to prevent malfunction due to static electricity.
- Do not turn OFF the power supply to the Unit while data is being transferred.
- When transporting or storing Units or Board, static electricity can destroy LSIs or ICs. Cover the PCBs with a conductive material and maintain the specified storage temperature.
- Do not touch circuit boards or the components mounted to them with your bare hands. There are sharp leads and other parts on the boards that may cause injury if handled improperly.
- · Double-check the pin numbers when assembling and wiring the connectors.
- Never short-circuit the positive and negative terminals of a battery or charge, disassemble, heat, or incinerate the battery. Do not subject the battery to strong shocks or deform the battery by applying pressure. Doing any of these may result in leakage, rupture, heat generation, or ignition of the battery. Dispose of any battery that has been dropped on the floor or otherwise subjected to excessive shock. Batteries that have been subjected to shock may leak if they are used.
- Dispose of the product and batteries according to local ordinances as they apply.



- UL standards require that only an experienced engineer can replace the battery. Make sure that an experienced engineer is in charge of battery replacement. Follow the procedure for battery replacement given in this manual.
- The following precaution must be displayed on all products that contain a lithium primary battery (containing at least 6 ppb of perchlorate) and that will be exported to or transported through the State of California in the USA.

Perchlorate Material - special handling may apply. See http://www.dtsc.ca.gov/hazardouswaste/perchlorate

A CP1W-BAT01 or CJ1W-BAT01 lithium primary battery (containing at least 6 ppb of perchlorate) can be mounted in a CP1E-N□□□-□ CPU Unit. Display the precaution given above on your product's packaging box or shipping box if the product contains a CP1W-BAT01 or CJ1W-BAT01 Battery and is exported to or through the State of California in the USA.

- This product is EMC compliant when assembled in a complete PLC system. Refer to the applicable manual for grounding, cable selection, and any other conditions for EMC compliance.
- This is a Class A product for use in industrial environments. In residential environments it may
  cause radio interference, in which case the user may be required to take adequate measures to
  reduce interference.

### External Circuits

- Always configure the external circuits to turn ON power to the PLC before turning ON power to the
  control system. If the PLC power supply is turned ON after the control power supply, temporary
  errors may result in control system signals because the output terminals on DC Output Units and
  other Units will momentarily turn ON when power is turned ON to the PLC.
- Fail-safe measures must be taken by the customer to ensure safety in the event that outputs from output terminals remain ON as a result of internal circuit failures, which can occur in relays, transistors, and other elements.
- If the I/O Hold Bit is turned ON, the outputs from the PLC will not be turned OFF and will maintain
  their previous status when the PLC is switched from RUN or MONITOR mode to PROGRAM
  mode. Make sure that the external loads will not produce dangerous conditions when this occurs.
  (When operation stops for a fatal error, including those produced with the FALS instruction, all outputs from PLC will be turned OFF and only the internal output status in the CPU Unit will be maintained.)

# **Operating Environment Precautions**

### Perform installation following the instructions in this manual

Follow the instructions in this manual to correctly perform installation.

### Do not operate the control system in the following locations

- · Locations subject to direct sunlight
- Locations subject to temperatures or humidity outside the range specified in the specifications
- Locations subject to condensation as the result of severe changes in temperature
- · Locations subject to corrosive or flammable gases
- · Locations subject to dust (especially iron dust) or salts
- Locations subject to exposure to water, oil, or chemicals
- · Locations subject to shock or vibration

### Take countermeasures in the following locations

- · Locations subject to static electricity or other forms of noise
- · Locations subject to strong electromagnetic fields
- Locations subject to possible exposure to radioactivity
- · Locations close to power supplies

# Regulations and Standards

### Conformance to EC Directives

### **Applicable Directives**

- · EMC Directives
- Low Voltage Directive

### **Concepts**

### EMC Directives

OMRON devices are electrical components that are designed to be built into equipment and manufacturing systems. OMRON devices that comply with EMC Directives also conform to the related EMC standards\*, so that they can be more easily built into other devices or the overall machine. Whether the products conform to the standards in the system used by the customer, however, must be checked by the customer.

EMC-related performance of the OMRON devices that comply with EC Directives will vary depending on the configuration, wiring, and other conditions of the equipment or control panel on which the OMRON devices are installed. The customer must, therefore, perform the final check to confirm that devices and the overall machine conform to EMC standards.

\* The applicable EMC (Electromagnetic Compatibility) standard is EN61131-2.

### Low Voltage Directive

Always ensure that devices operating at voltages of 50 to 1,000 VAC and 75 to 1,500 VDC meet the required safety standards for the PLC (EN 61131-2).

### Conformance to EC Directives

The CP1E PLCs comply with EC Directives. To ensure that the machine or device in which the CP1E PLC is used complies with EC Directives, the PLC must be installed as follows:

- The CP-series PLC must be installed within a control panel.
- CP-series PLCs complying with EC Directives also conform to EN61131-2. Radiated emission characteristics (10-m regulations) may vary depending on the configuration of the control panel used, other devices connected to the control panel, wiring, and other conditions. You must therefore confirm that the overall machine or equipment complies with EC Directives.
- A SYSMAC CP-series PLC is a class A product (for an industrial environment). In residential
  areas it may cause radio interference, in which case the user may be required to take adequate
  measures to reduce interference.

### **Trademarks**

SYSMAC is a registered trademark for Programmable Controllers made by OMRON Corporation.

CX-One is a registered trademark for Programming Software made by OMRON Corporation.

Windows is a registered trademark of Microsoft Corporation.

Other system names and product names in this document are the trademarks or registered trademarks of their respective companies.

# **Related Manuals**

The following manuals are related to the CP1E. Use them together with this manual.

Manual name	Cat. No.	Model numbers	Application	Contents
SYSMAC CP Series CP1E CPU Unit Hard- ware User's Manual (this manual)	W479	CP1E-E□□D□-A CP1E-N□□D□-□	To learn the hard- ware specifications of the CP1E PLCs	Describes the following information for CP1E PLCs.  Overview and features Basic system configuration Part names and functions Installation and settings Troubleshooting
			Manual (Cat. No. W48 W483).	0) and Instructions Reference Manual (Cat. No.
SYSMAC CP Series CP1E CPU Unit Soft- ware User's Manual	W480	CP1E-E□□D□-A CP1E-N□□D□-□	To learn the software specifications of the CP1E PLCs	Describes the following information for CP1E PLCs.  CPU Unit operation  Internal memory  Programming  Settings  CPU Unit built-in functions  Interrupts  High-speed counter inputs  Serial communications  Other functions
				her with the CP1E CPU Unit Hardware User's 9) and Instructions Reference Manual (Cat. No.
SYSMAC CP Series CP1E CPU Unit Instruc- tions Reference Manual	W483	CP1E-E□□D□-A CP1E-N□□D□-□	To learn programming instructions in detail	Describes each programming instruction in detail.  When programming, use this manual together with the CP1E CPU Unit Software User's Manual (Cat. No. W480).
CS/CJ/CP/NSJ Series Communications Com- mands Reference Man- ual	W342	CS1G/H-CPU□□H CS1G/H-CPU□□-V1 CS1D-CPU□□H CS1D-CPU□□S CS1W-SCU□□-V1	To learn communications commands for CS/CJ/CP/NSJ-series Controllers in detail	Describes  1) C-mode commands and 2) FINS commands in detail.  Read this manual for details on C-mode and FINS commands addressed to CPU Units.  scribes commands addressed to CPU Units. It
		CS1W-SCB -V1 CJ1G/H-CPU -H CJ1G-CPU -P CJ1M-CPU - CJ1G-CPU - CJ1G-CPU - CJ1W-SCU -V1	does not cover co serial communication	ommands addressed to CPO Units. It ommands addressed to other Units or ports (e.g., ations ports on CPU Units, communications ports unications Units/Boards, and other Communica-

# **Overview and Specifications**

This section gives an overview of the CP1E, describes its features, and provides its specifications.

1_1	CD1E	Overview
1-1		
	1-1-1	Overview of Features
	1-1-2	Features
1-2	Basic	Operating Procedure 1-7
	Specif	fications
	1-3-1	General Specifications
	1-3-2	Characteristics
	1-3-3	Functional Specifications

### **CP1E Overview** 1-1

### 1-1-1 **Overview of Features**

The SYSMAC CP1E Programmable Controller is a package-type PLC made by OMRON that is designed for easy application. The CP1E includes E-type CPU Units (basic models) for standard control operations using basic, movement, arithmetic, and comparison instructions, and N-type CPU Units (application models) that supports connections to Programmable Terminals, Inverters, and Servo Drives.

	Basic Models (E-type CPU Units)		CP1E Application Models (N-type CPU Units)	
	CPU with 20 I/O	CPU Unit with 30 or 40 I/O	CPU with 20 I/O	CPU Unit with 30 or 40 I/O
	Points	Points	Points	Points
Appearance	51" 17			
Program capacity	2K steps		8K steps	
DM Area capacity	2K words Of these 1,500 words can be written to the built-in EEPROM.		8K words Of these 7,000 words can be written to the built-in EEPROM.	
Mounting Expan-	Not possible.	3 Units maximum	Not possible.	3 Units maximum
sion I/O Units and				
Expansion Units				
Model with transis-	Not available.		Available	
tor outputs	Net augustad		Our mant of (Mant of Livith America)	
Pulse outputs	Not supported.		Supported (Model with transistor outputs only)	
Built-in serial com- munications port	Not provided.		RS-232C port provided	
Option Board	Not supported.		Not supported.	Supported (for one port)
Connection port	USB port		USB port	
for Programming	COD point		COD point	
Device				
Clock	Not provided.		Provided	
Using a Battery	Cannot be used.		Can be used (sold separately).	
Backup time of	50 hours at 25°C		40 hours at 25°C	
built-in capacitor				
Battery-free opera-	Always battery-free operation.		Battery-free operation if no battery is attached.	
tion	Only data in the built-in EEPROM will be retained		Only data in the built-in EEPROM will be retained	
	if power is interrupted for longer than 50 hours.		if power is interrupted for longer than 40 hours.	



### **Precautions for Correct Use**

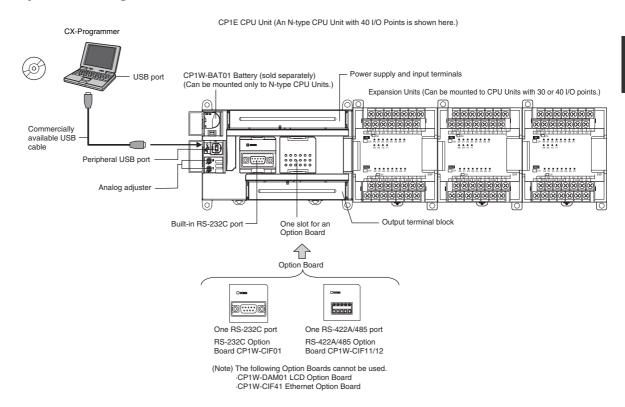
For CP1E CPU Units, the following I/O memory area will be unstable after a power interruption.

- DM Area (D) (excluding words backed up to the EEPROM using the DM function)
- Holding Area (H)
- Counter Present Values and Completion Flags (C)
- Auxiliary Area related to clock functions(A)

Mount the CP1W-BAT01 Battery (sold separately) to an N-type CPU Unit if data in the above areas need to be retained after a power interruption. A Battery cannot be mounted to an E-type CPU Unit.

### 1-1-2 Features

### System Configuration



### Programming, Setting, and Monitoring with the CX-Programmer

The CX-Programmer is used as the Programming Device for the CP1E.

# **Easy Connection with Computers Using Commercially Available USB Cables**

The CX-Programmer is connected using a commercially available USB cable between the computer's USB port and the built-in peripheral USB port of the CP1E.

### With CPU Units with 30 or 40 I/O Points, Add I/O by Connecting **Expansion I/O Units**

A total of up to three of the following Expansion I/O Units can be connected to a CPU Unit with 30 or 40 I/O points. (The total of three Units must also include Expansion Units.)

24-input/16-output Unit, 32-output Unit, 12-input/8-output Unit, 16-output Unit, 8-input Unit, or 8-output Unit

### With CPU Units with 30 or 40 I/O Points, Add Analog I/O or **Temperature Inputs by Connecting Expansion Units**

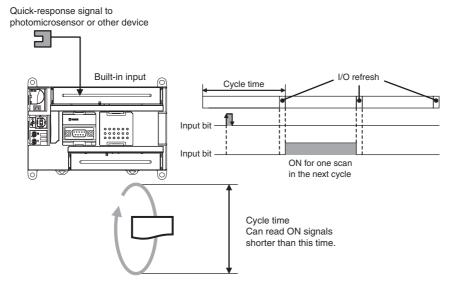
With a CPU Unit with 30 or 40 I/O points, a total of up to three of the following Expansion Units can be connected. (The total of three Units must also include Expansion I/O Units.)

Analog I/O Unit, Analog Input Unit, Analog Output Unit, Temperature Sensor Units, CompoBus/S I/O Link Unit

### **Quick-response Inputs**

By setting a built-in input to quick-response input operation, inputs with signal widths as small as 50 µs can be read with certainty regardless of the cycle time.

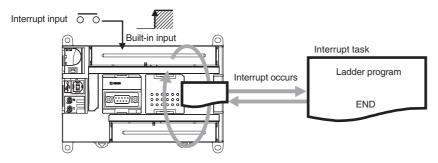
Up to six quick-response inputs can be used.



Note The user setting in the PLC Setup determines if each input is a quick-response input, normal input, interrupt input, or high-speed counter input.

### **Input Interrupts**

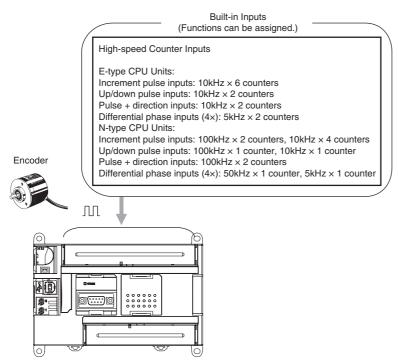
An interrupt task can be started when a built-in input turns ON or turns OFF . Up to six interrupt inputs can be used.



**Note** The user setting in the PLC Setup determines if each input is a quick-response input, normal input, interrupt input, or high-speed counter input.

### **Complete High-speed Counter Functionality**

A high-speed counter input can be used by connecting a rotary encoder to a built-in input. A CP1E CPU Unit is equipped with more than one high-speed counter input, making it possible to control devices for multiple axes with a single PLC.



**Note** The user setting in the PLC Setup determines if each input is a quick-response input, normal input, interrupt input, or high-speed counter input.

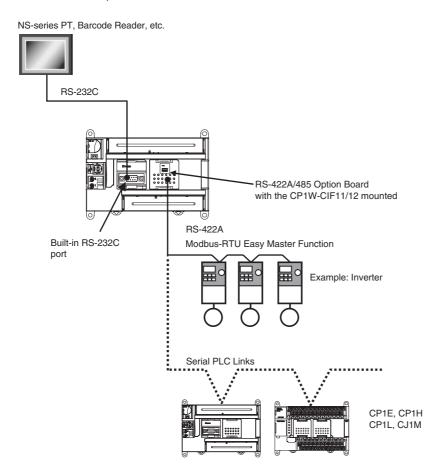
- High-speed counters can be used for high-speed processing, using either target value comparison or range comparison with the counter's PV to create interrupts.
   An interrupt task can be started when the count reaches a specified value or falls within a specified range.
- High-speed counter input frequency (speed) can be measured.
   The input pulse frequency can be measured using the PRV instruction (counter 0 only).

### **Built-in RS-232C Port for N-type CPU Units**

The N-type CPU Units have one built-in RS-232C port as a standard feature.

### Mounting Serial Option Boards to N-type CPU Units with 30 or 40 I/O **Points**

One Serial Communications Option Board with one RS-232C port or one RS-422A/485 port can be added to an N-type CPU Unit with 30 or 40 I/O points. With the serial communications port, it is easy to connect to general components, such as barcode readers, and other components such as PTs, other CP-series PLCs, and Inverters.



# 1-2 Basic Operating Procedure

In general, use the following procedure.

### 1. Setting Devices and Hardware

Connect the CPU Unit, Expansion I/O Units, and Expansion Units. Set the DIP switches on the Option Board and Expansion Units as required.

Refer to Section 3 Part Names and Functions and Section 5 Installation and Wiring in the CP1E CPU Unit Hardware User's Manual (Cat. No. W479).

### 2. Wiring

Wire the power supply, I/O, and communications.

Refer to Section 5 Installation and Wiring in the CP1E CPU Unit Hardware User's Manual (Cat. No. W479).

### 3. Connecting Online to the PLC

Connect the personal computer online to the PLC.

Refer to Section 4 Programming Device in the CP1E CPU Unit Hardware User's Manual (Cat. No. W479).

### 4. I/O Allocations

Allocations for built-in I/O on the CPU Unit are predetermined and memory is allocated automatically to Expansion I/O Units and Expansion Units, so the user does not have to do anything.

Refer to Section 6 I/O Allocation in the CP1E CPU Unit Software User's Manual (Cat. No. W480).

### 5. Software Setup

Make the PLC software settings.

With a CP1E CPU Unit, all you have to do is set the PLC Setup.

When using an E-type CPU Unit or when using an N-type CPU Unit without a Battery, be sure to consider selecting the *Clear retained memory area* (*HR/DM/CNT*) Check Box in the *Startup Data Read* Area in the PLC Settings.

Refer to 3-2-4 Initializing I/O Memory at Startup and Section 7 PLC Setup in the CP1E CPU Unit Software User's Manual (Cat. No. W480).

### 6. Writing the Programs -

Write the programs using the CX-Programmer.

Refer to Section 4 Programming Concepts in the CP1E CPU Unit Software User's Manual (Cat. No. W480).

### 7. Checking Operation

Check the I/O wiring and the Auxiliary Area settings, and perform trial operation.

The CX-Programmer can be used for monitoring and debugging.

Refer to Section 8 Overview and Allocation of Built-in Functions in the CP1E CPU Unit Software User's Manual (Cat. No. W480).

### 8. Basic Program Operation -

Set the operating mode to RUN mode to start operation.

#### 1-3 **Specifications**

#### **General Specifications** 1-3-1

The following table lists the general specifications of CP1E CPU Units.

	Item	AC power supply	DC power supply							
	Model	CP1E-□□□□-A	CP1E-N□□□-D							
Enclosure		Mounted in a panel								
Dimension	ns (H × D × W)	CPU Unit with 20 I/O points (CP1E-□20D□□-□) : 90mm*1 ×85mm*2 ×86mm								
		CPU Unit with 30 I/O points (CP1E-□30D□□-□) : 90mm*1 ×85mm*2 ×130mm								
		m* <sup>1</sup> ×85mm* <sup>2</sup> ×150mm								
Weight		CPU Unit with 20 I/O points (CP1E-□20D□□-□): 370g	CPU Unit with 20 I/O points (CP1E-□20D□□-□) : 370g max.							
		CPU Unit with 30 I/O points (CP1E-□30D□□-□): 600g	max.							
		CPU Unit with 40 I/O points (CP1E-□40D□□-□): 660g	max.							
Electri-	Supply voltage	100 to 240 VAC 50/60 Hz	24 VDC							
cal spec- ifications	Operating voltage range	85 to 264 VAC	20.4 to 26.4 VDC							
mounons	Power consumption	15 VA/100 VAC max.	12W may (CD1E [200]] D)							
		25 VA/240 VAC max. (CP1E-□20D□-A)	13W max. (CP1E-□20D□-D)							
		50 VA/100 VAC max. (CP1E-□30D□-A/□40D□-A)	34W max. (CP1E-□30D□-D/□40D□-D)							
		70 VA/240 VAC max.	34W Max. (OF TE-130011-0/1140011-0)							
	Inrush current	120 VAC, 20 A for 8 ms max. for cold start at room tem-	24 VDC, 30A for 20 ms max. for cold start at room tem-							
		perature	perature							
		240 VAC, 40 A for 8 ms max. for cold start at room temperature								
	External power supply	Not provided. (CP1E-□20D□-A)								
		24 VDC, 300 mA (CP1E-□30D□-A/□40D□-A)	Not provided.							
	Insulation resistance	$20~M\Omega$ min. (at 500 VDC) between the external AC terminals and GR terminals	Except between DC primary current and DC secondary carrent							
	Dielectric strength	2,300 VAC 50/60Hz for 1 min between AC external and GR terminals Leakage current: 5 mA max.	Except between DC primary current and DC secondary carrent							
	Power interrupt time	10 ms min.	2 ms min.							
Applica-	Ambient operating temper-	0 to 55°C								
tion envi-	ature									
ronment	Ambient humidity	10% to 90%								
	Atmosphere	No corrosive gas.								
	Ambient storage tempera- ture	-20 to 75°C (excluding battery)								
	Altitude	2,000 m max.								
	Pollution degree	2 or less: Conforms to JIS B3502 and IEC 61131-2.								
	Noise resistance	2 kV on power supply line (Conforms to IEC61000-4-4.)								
	Overvoltage category	Category II: Conforms to JIS B3502 and IEC 61131-2.								
	EMC immunity level	Zone B								
	Vibration resistance	Conforms to JIS 60068-2-6.								
		5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz								
		Acceleration of 9.8 m/s <sup>2</sup> for 100 min in X, Y, and Z direct	ions (10 sweeps of 10 min each = 100 min total)							
	Shock resistance	Conforms to JIS 60068-2-27.								
		147 m/s², 3 times in X, Y, and Z directions								
Terminal b	olock	Fixed (not removable)								
Terminal s	screw size	M3								
Applicable	estandards	Conforms to EC Directives.								
Grounding	g method	Ground to $100\Omega$ or less.								

Total of 110 mm with mounting brackets.

<sup>\*2</sup> Excluding cables.

# 1-3-2 Characteristics

The following table gives the characteristics of CP1E CPU Units.

		<u> </u>			СР	1E-				
	Iten	n	E20DR-A	E30DR-A	E40DR-A	N20D□-□	N30D□-□	N40D□-□		
Program	capacity		. , ,	2K steps (8 KB) including the symbol table, comments, and program indices of the CX-Programmer for CP1E  8K steps (32 KB) including the symbol table, comments, and program indices of the CX-Programmer for CP1E						
Control n	nethod		Stored program method							
I/O contro	ol method		Cyclic scan with	immediate refres	hing					
Program	language		Ladder programs	3						
Instruction	ons		Approximately 20	00						
Processii	ng speed	Overhead process- ing time	0.4 ms							
		Instruction execu- tion times	Basic instructions Special instruction	•						
		s Expansion I/O nits connected	None	3 Units		None	3 Units			
	n number of I/0		20	150 (30 built in, 40 x 3 expansion)	160 (40 built in, 40 x 3 expansion)	20	150 (30 built in, 40 x 3 expansion)	160 (40 built in, 40 x 3 expansion)		
Built-in I/	0		20 12 inputs 8 outputs	30 18 inputs 12 outputs	40 24 inputs 16 outputs	20 12 inputs 8 outputs	30 18 inputs 12 outputs	40 24 inputs 16 outputs		
Built-in input func- tions	High-speed counters	High-speed counter mode/maximum frequency	Incremental Puls 10 kHz: 6 counte Up/Down Inputs 10 kHz: 2 counte Pulse + Directior 10 kHz: 2 counte Differential Phase	ers n Inputs ers e Inputs (4x)		Incremental Pu 100 kHz: 2 cou Up/Down Inpu 100 kHz: 1 cou Pulse + Directi 100 kHz: 2 cou Differential Phi	8 outputs   12 outputs   16 output   Incremental Pulse Inputs   100 kHz: 2 counters,10 kHz: 4 counters   Up/Down Inputs   100 kHz: 1 counters   Pulse + Direction Inputs   100 kHz: 2 counters   Differential Phase Inputs (4x)			
	Cour		5 kHz: 2 counters 50 kHz: 1 counter, 5 kHz: 1 counter  • Linear mode  • Ring mode							
		Count value	32 bits							
		Counter reset		•	cluding increment pu	lse input)				
		modes Control method	Software reset	<u>t</u>						
		Control method	Target Matching Range Comparis	son						
	Input interru	ıpts		ot input pulse widt	h: 50 µs min.)					
	Quick-respo	onse Inputs	6 inputs (input pu	ulse width: 50 μs ι	min.)					
	Normal input	Input constants	,	et in the PLC Setu 2, 4, 8, 16, or 32	up (0 to 32 ms, defau	lt: 8 ms).				
Built-in output func-	Pulse out- puts (Models with	Pulse output method and out- put frequency		ction not included		Pulse + Directi 1 Hz to 100 kF				
tions	transistor outputs	Output mode				Continuous mode (for speed control)     Independent mode (for position control)				
	only)	Number of output pulses				Relative coordinates: 0000 0000 to 7FFF FFFF hex (0 to 2147483647)     Absolute coordinates: 8000 0000 to 7FFF FFFF hex (-2147483647 to 2147483647)				
		Acceleration/ deceleration curves	-				celeration and dec ve acceleration and	,		
	Changing during institution execu		1			Only target pos	sition can be chanç	ged.		
		Origin searches	<u></u>			Included				
	PWM out- puts (Models	Frequency	PWM output fund	ction not included			Hz (in increments of to 32,000 Hz (in in			
	with transis tor outputs only)					Accuracy: +1% +5%/-0% at 1	% (in increments of %/-0% at 2 Hz to 10 0,000 Hz to 32,000	,000 Hz and		
Analas -	diuotoro	Output mode	2 adjustara (C-#	ing range: 0 to 05	:=\	Continuous Mo	ode			
Analog a		heral USB port		ing range: 0 to 25 SB 2.0 B-type cor						
nica-	2 sype pent	Transmission	5 m max.	22 2.0 D type 001						
tions		distance								

	Item					1E-		
			E20DR-A	E30DR-A	E40DR-A	N20D□-□	N30D□-□	N40D□-□
Communica	Built-in RS-23		No built-in RS-232C	port			forms to EIA RS-232	C.
tions		Communica-				Half duplex		
		tions method Synchroniza-				Start-stop		
		tion				1004400	6 10 0 00 4 57 6	ar 115 O khaa
		Baud rate Transmission				1.2, 2.4, 4.8, 9.6, 19.2, 38.4, 57.6, or 115.2 kbps 15 m max.		
		distance				10 III III ax.		
		Supported	]			Host Link		
		protocol				<ul><li>1:N NT Link</li><li>No-protocol</li></ul>		
						Serial PLC I	inks (master, slave)	
	Carial aution		Option Board canno	t be marinted		Modbus-RTI		
	Serial option	Mountable	Option Board Carino	n be mounted.			1 port • CP1W-CIF01	
		Option Boards					One RS-232C p  CJ1W-CIF11 One RS-422A/4 (not isolated)  CP1W-CIF12 One RS-422A/4 (isolated)	85 port
		Communica-					Depends on Option	n Board.
		tions method					Daniel C :	- Dl
		Synchroniza- tion					Depends on Option	n Board.
		Baud rate	1				1.2, 2.4, 4.8, 9.6,	19.2, 38.4, 57.6,
		Compatible					or 115.2 kbps  • Host Link	
		protocols					• 1:N NT Link	
							No-protocol mo     Serial PLC Link	
							Modbus-RTU Ea	
			One cyclic execut     One scheduled in     Six input interrupt     Sixteen high-spee	terrupt task (alwa tasks (interrupt t	asks 2 to 7)	•	)	
	routine number		128					
Maximum jum Scheduled into			128 1 interrupt task					
Clock	errupt tasks		Clock function not in	ocluded		Included.		
Ciock			The time of error oc 01:01:01 Sunday.	currence displays		Accuracy (monthly deviation):-4.5 min to -0.5 min at ambient temperature of 55°C -2.0 min to +2.0 min at ambient temperature of 25°C -2.5 min to +1.5 min at ambient temperature of 0°C -2.5 min at ambient		
Memory backu	ıp Built-in E	EPROM	Ladder programs ar A section of the Dat					
	*With CP tery (op	1W-BAT01 Bat-	Battery cannot be m	•			rature: 55°C):	
CIO Area	Input Bit	s	1,600 bits (100 word	ds): CIO 0.00 to C	IO 99.15 (CIO	, , , , , , , , , , , , , , , , , , ,		
	Output B	Bits	1,600 bits (100 word	ds): CIO 100.00 to	CIO 199.15 (C	CIO 100 to CIO 1	99)	
		.C Link Words	1,440 bits (90 words	•	,		289)	
Work Area (W)			1,600 bits (100 word	,	•	9)		
Holding Area (	н)		800 bits (50 words): Bits in this area mai			operating mode	is changed.	
Auxiliary Area	(A)		Read-only: 7,168 bit	ts (448 words) (A	0 to A447)	-20.2019 111006	you.	
Temporary Area (TR)			Read/write: 4,896 bits: TR0 to TR1	, , ,	-+0 (U A/ 33)			
Timer Area (T)			256 timer numbers		rate from coun	ters))		
Counter Area (C)			256 counter number					
Data Memory			2K words: D0 to D2 Of these, 1,500 wor memory (built-in EE Auxiliary Area.	ds can be saved t PROM) using set	tings in the		0 words can be save in EEPROM) using s	
Operating modes			PROGRAM Mode: Program execution is stopped. Preparations can be executed prior to program execution in this mode.  MONITOR Mode: Programs are executed. Some operations, such as online editing, and changes to present values in I/O memory, are enabled in this mode.  RUN Mode: Programs are executed. This is the normal operating mode.					

# 1-3-3 Functional Specifications

The following table gives the functional specifications of CP1E CPU Units.

Function					Description			
Cycle time	Minimum cycle time				Makes the cycle time consistent.			
manage- ment	Monitoring the cycle	time			Monitors the cycle time.			
CPU Unit built-in functions	Inputs	High- speed counters inputs	inputs	eed pulse	High-speed pulses from devices such as a rotary encoder are counted. The counted values are stored in the Auxiliary Area.Interrupt tasks can be executed when target is reached or by range comparison.			
		liiputs	Input pu quency	ilse fre- measurement	The frequency of pulses input by the PRV instruction is measured.			
		Interrupt inp	uts		Relevant interrupt tasks are executed during the cycle when the CPU Unit built-in inputs turn ON or turn OFF.			
		Quick-respo	nse input	s	Inputs can be read without being affected by cycle time. Use the quick-response inputs to read signals shorter than the cycle time.			
		Normal inputs	I/O Cyclic refres refreshing		The CPU Unit's built-in I/O are cyclically refreshed.			
			hing	Immediate refreshing	I/O refreshing by immediate refreshing instructions.			
			Input response times		Input constants can be set for Basic I/O Units.  The response time can be increased to reduce the effects of chattering and noise at input contacts. The response time can be decreased to enable detecting shorter input pulses.			
	Outputs	Pulse out- puts (Mod- els with transistor outputs	Pulse co	ontrol	A pulse signal is output and positioning or speed control is performed with a servo driver that accepts a pulse input.  Continuous mode for speed control or independent mode for position control can be used. There are functions for changing to positioning during speed control and for changing the target value during positioning.			
		only )	Origin positioning		Origin searches and origin returns.			
		PWM outputs (Models with transistor outputs only )		with transis-	Pulses for which the duty ratio (ratio between ON time and OFF time during one pulse cycle) can be set are output.			
		Normal outputs	Load OF	F function	All of the outputs on the CPU Unit's I/O can be turned OFF when an error occurs in RUN or MONITOR mode.			
Expansion I/O Units	Functions sup- ported by both	I/O refresh-	Cyclic re	efreshing	The Expansion I/O Units and Expansion Units are cyclically refreshed.			
and	Expansion I/O Unit	ing		ing by IORF	I/O refreshing by IORF instruction.			
Expansion Units	and Expansion Unit	Load OFF fu			All of the outputs on Expansion I/O Units and Expansion Units are turned OFF (0000 hex) when an error occurs in RUN or MONITOR mode.			
	Expansion I/O Units	Input respon	ut response times		The response time can be increased to reduce the effects of chattering and noise at input contacts.  The response time can be decreased to enable detecting shorter input pulses.			
	Expansion Units	Unit error de	tection		Errors in Expansion Units are detected. The CPU Unit is notified that the Expansion Unit stopped due to an error.			
Memory manage-	Holding I/O memory v	when changing	g operatir	ig modes	The status of I/O memory can be held when the operating mode is changed. The forced-set/reset status can be held when the operating mode is changed .			
ment func- tions	Automatic backup to (built-in EEPROM)				Automatic backup of ladder programs and parameter area to the backup memory (built-in EEPROM).			
Communi- cations	Peripheral USB port	Peripheral be	us (toolbu	ıs)	For communications with programming device (CX-Programmer).			
outions	Serial port (N-type on				- DT - 1/2 1/2			
	Host Link (SYS	<u> </u>			Host Link commands can be sent from a PT or a computer to read/write I/O memory, and perform other operations for PLC.			
	No-protocol co		<b>i</b>		I/O instructions for communications ports (TXD/RXD instructions) can be used for data transfer with peripheral devices such as bar code readers.			
	NT Link comm	unications			I/O memory in the PLC can be allocated and directly linked to various PT functions, including status control areas, status notification areas, touch switches, lamps, memory tables, and other objects.			
	Serial PLC Links				Up to 10 words of data per Unit can be shared between up to nine CPU Units (one polling unit and eight polled units).  * A PT cannot be connected.			
	Modbus-RTU E	Modbus-RTU Easy Master function			Modbus-RTU commands are sent by the Modbus-RTU Master function. Mod- bus slaves, such as inverters, can be easily controlled with serial communica- tions.			
Interrupt	Scheduled interrupts				Tasks can be executed at a specified interval (1.0 ms min., Unit: 0.1 ms).			
	Input interrupts				Interrupt tasks are processed when the built-in input turns ON or OFF.			
	High-speed counter interrupts				This function counts input pulses with the CPU Unit's built-in high-speed counter and executes an interrupt task when the count reaches the preset value or falls within a preset range (target value or zone comparison).			

PLC Setup error detection		Fu	nction	Description
Debugging	ply man-	Memory protection		and Counter Present Values are held even when power is turned OFF.
Force-set/reset    Force-set/reset   Specified bits can be set or reset.			erruptions counter	·
Differentiate monitoring   CNOFF changes in specified bits can be monitored.	Debugging			GRAM mode.
Storing the stop position at errors				·
Program check  Self-diagnosis and restoration  CPU error detection  User-defined failure diagnosis  CPU and the time of occurance of error codes predefined by the CPU Unit are stored.  CPU unit WDT errors are detected.  The built-in outputs, Expansion I/O Unit outputs, and Expansion Unit outputs are turned OFF.  Non-fatal error detection  (User-defined non-fatal error detection to User-defined end-fatal error)  (User-defined non-fatal error detection to User-defined end-fatal error)  ERROR present present expansion in the public present in the public present in the public present in the public present in consumption of the public present in publi				- '
FALS/FÂL errors at startup.  Details and the time of cocurance of error codes predefined by the CPU Unit are stored.  CPU error detection  CPU unit WDT errors are detected.  Errors can be generated for user-specified conditions Non-fatal errors (FAL) and statal errors (FAL) and statal errors (FAL) and statal errors (FAL) and statal errors.  Non-fatal error detection  (User-defined non-fatal error)  Backup memory error detection  (User-defined non-fatal error)  Backup memory error detection  PLC setup error detection  PLC setup error detection  This function detects when data in the backup memory (built-in EEPROM) that stores the ladder program is corrupted.  Battery error detection (N-type CPU Units only)  This function detects when the Cption Board is malfunctioning or disconnected.  Battery error detection  This function detects when the battery vottage is low or the battery is disconnected.  This function detects when the battery vottage is low or the battery is disconnected.  This function detects when the battery vottage is low or the battery is disconnected.  This function detects errors that cocur in more than the number of CP1W Expansion Units and expansion Units are consistent out in male another Unit.  Detection of too many I/O points  Program error detection  Instruction processing error detection  Indirect DM addressing BCD error detection  No END error detection  No END error detection  No END error detection  Task error detection  No END error detection  No END error detection  This function detects are error when the evaluation between tasks was attempted.  Differentiation overflow error detection error detection error detection  No END error detection  No END error detection  This function detects are error when there is no END instruction at the end of the program.  This function detects are error when an attempt is made to access an illegal area with an instruction operand.  This function detects are error when			nion at errors	recorded.
restoration    CPU error detection		Program check		
User-defined failure diagnosis  Errors can be generated for user-specified conditions:Non-fatal errors (FAL) and fatal errors (FAL).  In the built-in outputs, Expansion I/O Unit outputs, and Expansion Unit outputs are turned OFF.  Non-fatal error detection  (User-defined non-fatal error)  detection  Backup memory error detection  This function detects when data in the backup memory (built-in EEPROM) that stores the ladded program is corrupted.  PLC Setup error detection  This function detects when data in the backup memory (built-in EEPROM) that stores the ladded program is corrupted.  Battery error detection (N-type CPU Units only)  Wemory error detection (N-type CPU Units only)  Fatal Error Detection  Memory error detection  I/O bus e	nosis and			are stored.
Load OFF function	restoration			
Non-fatal error detection   System FAL error detection   (User-defined non-fatal error)   Backup memory error detection   This function generates a non-fatal (FAL) error when the user-defined conditions are met in program.			diagnosis	and fatal errors (FALS).
detection   Guernefined non-fatal error)   tions are met in program.   Eachup memory error detection   This function detects when data in the backup memory (built-in EEPROM) that stores the ladder program is corrupted.			1	are turned OFF.
Backup memory error detection   This function detects when data in the backup memory (built-in EEPROM) that stores the ladder program is corrupted.   PLC Setup error detection   This function detects settling errors in the PLC Setup.   Option Board errors   This function detects when the Option Board is malfunctioning or disconnected.				
Popular Board errors   This function detects when the Option Board is malfunctioning or disconnected.			Backup memory error detection	This function detects when data in the backup memory (built-in EEPROM) that
Battery error detection (N-type CPU Units only)   This function detects when the battery voltage is low or the battery is disconnected.			PLC Setup error detection	This function detects setting errors in the PLC Setup.
Patal Error Detection			Option Board errors	,
Fatal Error Detection				nected.  * This function is valid only when a battery is mounted and the <i>Do not detect</i>
Detection of too many I/O points  This function detects when more than the maximum number of CPTW Expansion I/O thits and another Unit.  Program error detection  This function detects when there is an error in the program. See the following for details.  Instruction processing error detection  Indirect DM addressing BCD error  Illegal area access error detection  No END error detection  This function detects an error when the given data value is invalid when executing an instruction, or execution of instruction between tasks was attempted.  This function detects an error when an indirect DM/EM address in BCD mode is not BCD.  Illegal area access error detection  No END error detection  This function detects an error when an attempt is made to access an illegal area with an instruction operand.  This function detects an error when there is no END instruction at the end of the program.  Task error detection  This function detects an error when there is no END instruction at the end of the program.  This function detects an error when too many differentiated instructions are entered or deted during online editing (131,072 times or more).  Invalid instruction error detection  User program area overflow error detection and the system.  User program area overflow error detects an error when an attempt is made to execute an instruction that is not defined in the system.  This function detects an error when an attempt is made to execute an instruction that is not defined in the system.  This function detects an error when instruction data is stored after the last address in user program area.  Cycle time exceeded error detection (user-defined fatal error)  This function monitors the cycle time (10 to 1,000 ms) and stops the operation when the set value is exceeded.  This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral USB port or serial port).  Read protection set a password using the CX-Programmer.  Overwrite protection functio		Fatal Error Detec-	Memory error detection	·
Sion I/O Units and Expansion Units are connected to the PLC.   Program error detection		tion	I/O bus error detection	
See the following for details.			Detection of too many I/O points	
detection			Program error detection	
Perror   Illegal area access error detection   This function detects an error when an attempt is made to access an illegal area with an instruction operand.			detection	cuting an instruction, or execution of instruction between tasks was attempted.
tion area with an instruction operand.  No END error detection  This function detects an error when there is no END instruction at the end of the program.  Task error detection  Task error detection  The execution condition for an interrupt task was met but there is no interrupt task with the specified number.  Differentiation overflow error detection  Invalid instruction error detection  User program area overflow error detection that is not defined in the system.  This function detects an error when an attempt is made to execute an instruction that is not defined in the system.  This function detects an error when instruction data is stored after the last address in user program area.  Cycle time exceeded error detection (user-defined fatal error)  This function monitors the cycle time (10 to 1,000 ms) and stops the operation when the set value is exceeded.  System FALS error detection (user-defined fatal error)  This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral USB port or serial port).  Read protection using password  This function protects reading and displaying programs using passwords. Read protection: Set a password using the CX-Programmer.  * Overwrite protection function not included.			error	is not BCD.
Task error detection				
Lask with the specified number.			No END error detection	
detection   entered or deleted during online editing (131,072 times or more).			Task error detection	
tion to that is not defined in the system.  User program area overflow error detection  Cycle time exceeded error detection  This function monitors the cycle time (10 to 1,000 ms) and stops the operation when the set value is exceeded.  System FALS error detection (user-defined fatal error)  Maintenance  Maintenance  Automatic online connection via network  This function generates a fatal (FALS) error when the user-defined conditions are met in program.  This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral USB port or serial port).  Security functions  Read protection using password  This function protects reading and displaying programs using passwords. Read protection: Set a password using the CX-Programmer.  * Overwrite protection function not included.				
error detection   address in user program area.			tion	tion that is not defined in the system.
tion   when the set value is exceeded.			error detection	address in user program area.
Maintenance  Maintenance  Automatic online connection via network  CX-Programmer is directly connected by a serial connection (peripheral USB port or serial port).  Security functions  Read protection using password  This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral USB port or serial port).  This function protects reading and displaying programs using passwords. Read protection: Set a password using the CX-Programmer.  * Overwrite protection function not included.			tion	when the set value is exceeded.
nance  CX-Programmer is directly connected by a serial connection (peripheral USB port or serial port).  Security functions  Read protection using password  This function protects reading and displaying programs using passwords. Read protection: Set a password using the CX-Programmer.  * Overwrite protection function not included.			(user-defined fatal error)	are met in program.
functions  Read protection: Set a password using the CX-Programmer.  * Overwrite protection function not included.	nance			CX-Programmer is directly connected by a serial connection (peripheral USB port or serial port).
·		Read protection usin	g password	Read protection: Set a password using the CX-Programmer.
		Write protection from	n FINS commands	This function prohibits writing by using FINS commands sent over the network.



# **Basic System Configuration and Devices**

This section describes the basic system configuration and device models of the CP1E.

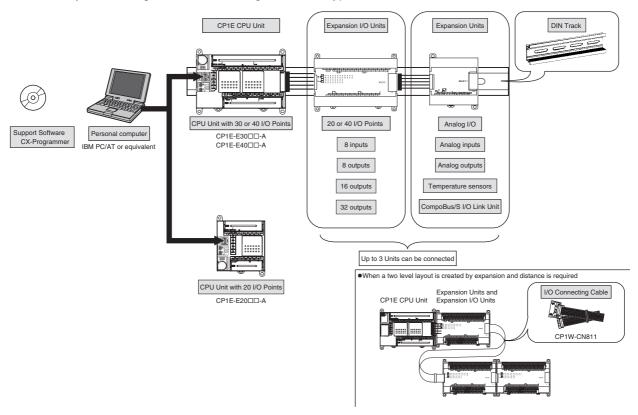
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#### 2-1 **Basic System Configuration**

This section describes the system configurations using E-type and N-type CP1E CPU Units.

#### 2-1-1 Basic System Configuration Using an E-type CPU Unit

The system configuration when using a CP1E E-type CPU Unit is shown below.





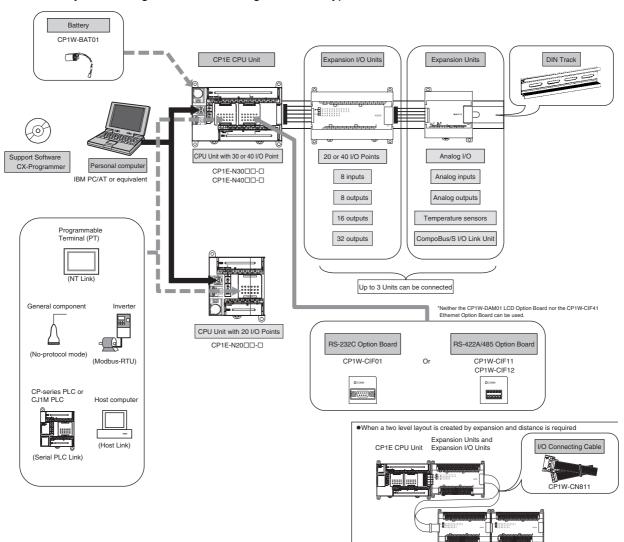
#### **Precautions for Correct Use**

For CP1E CPU Units, the following I/O memory area will be unstable after a power interruption.

- DM Area (D) (excluding words backed up to the EEPROM using the DM function)
- Holding Area (H)
- · Counter Present Values and Completion Flags (C)
- Auxiliary Area related to clock functions(A) Mount the CP1W-BAT01 Battery (sold separately) to an N-type CPU Unit if data in the above areas need to be retained after a power interruption. A Battery cannot be mounted to an E-type CPU Unit.

# 2-1-2 Basic System Configuration Using an N-type CPU Unit

The system configuration when using a CP1E N-type CPU Unit is shown below.





#### **Precautions for Correct Use**

For CP1E CPU Units, the following I/O memory area will be unstable after a power interruption.

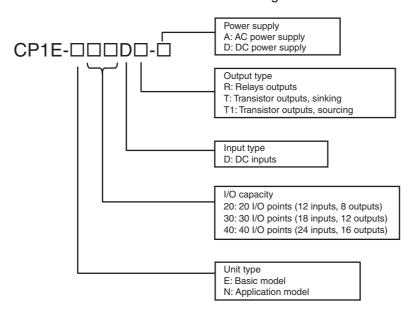
- DM Area (D) (excluding words backed up to the EEPROM using the DM function)
- Holding Area (H)
- Counter Present Values and Completion Flags (C)
- Auxiliary Area related to clock functions(A)
   Mount the CP1W-BAT01 Battery (sold separately) to an N-type CPU Unit if data in the above areas need to be retained after a power interruption. A Battery cannot be mounted to an E-type CPU Unit.

#### **CPU Units** 2-2

This section describes the models of CP1E CPU Units.

#### 2-2-1 **CPU Unit Models**

The CP1E CPU Unit model numbers are configured as shown below.



The following is a list of available CP1E CPU Unit models.

# E-type CPU Units

Name and appearance	Model number	Numb	per of built-in	ı I/O points	Power supply	Output	i dram i	DM Area	Current consumption		Weight
		Total	Number of inputs	Number of outputs	specifica- tions	type	capacity	capacity	5 VDC	24 VDC	Weight
CPU Unit with 20 I/O Points	CP1E-E20DR-A	20	12	8	AC power supply	Relays	2K steps	2K words	0.17A	0.08A	360g max.
					100 to 240 VAC						
CPU Unit with 30 I/O Points	CP1E-E30DR-A	30	18	12					0.17A	0.07A	540g max.
CPU Unit with 40 I/O Points	CP1E-E40DR-A	40	24	16					0.17A	0.09A	650g max.

Note A battery cannot be mounted to an E-type CPU Unit.

# N-type CPU Units

Name and amount	Madalassahas	Numb	er of built-ir	ı I/O points	Power supply	Output	Pro-	DM Area		rent mption	Walasha
Name and appearance	Model number	Total	Number of inputs	Number of outputs	specifica- tions	type	gram capacity	capacity	5 VDC	24 VDC	Weight
CPU Unit with 20 I/O Points	CP1E-N20DR-A	20	12	8	AC power supply 100	Relays	8K steps	8K words	0.18A	0.08A	370g max.
	CP1E-N20DT-A				to 240 VAC	Sinking transis- tors			0.23A	0.02A	340g max.
- 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1	CP1E-N20DT1-A					Sourcing transistors			0.23A	0.02A	340g max.
	CP1E-N20DR-D				DC power supply 24V	Relays					340g max.
	CP1E-N20DT-D				Зарріу 247	Sinking transis- tors			0.18A	0.08A	310g max.
	CP1E-N20DT1-D					Sourc- ing transis- tors			0.23A	0.02A	310g max.
CPU Unit with 30 I/O Points	CP1E-N30DR-A	30	18	12	AC power supply	Relays			0.21A	0.07A	600g max.
	CP1E-N30DT-A				100 to 240 VAC	Sinking transis- tors			0.27A	0.02A	570g max.
	CP1E-N30DT1-A					Sourc- ing transis- tors			0.27A	0.02A	570g max.
	CP1E-N30DR-D				DC power supply 24V	Relays			0.21A	0.07A	515g max.
	CP1E-N30DT-D					Sinking transis- tors			0.27A	0.02A	485g max.
	CP1E-N30DT1-D					Sourc- ing transis- tors			0.27A	0.02A	485g max.
CPU Unit with 40 I/O Points	CP1E-N40DR-A	40	24	16	AC power supply	Relays			0.21A	0.09A	660g max.
	CP1E-N40DT-A				100 to 240 VAC	Sinking transis- tors			0.31A	0.02A	630g max.
	CP1E-N40DT1-A					Sourc- ing transis- tors			0.31A	0.02A	630g max.
	CP1E-N40DR-D				DC power supply 24V	Relays			0.21A	0.09A	575g max.
	CP1E-N40DT-D				эирріў 240	Sinking transis- tors			0.31A	0.02A	545g max.
	CP1E-N40DT1-D					Sourcing transistors			0.31A	0.02A	545g max.

#### 2-2-2 **Optional Products**

# Optional Products for CPU Units

Name and appearance	Model number	Applications		rent mption	Weight
			DC5V	DC24V	
RS-232C Option Board	CP1W-CIF01	Mounted in the option slot of an N-type CPU Unit with 30 or 40 I/O points and can be used as an RS-232C port.	Includ- ing in CPU	-	Includ- ing in CPU
Non-isolated RS-422A/485 Option Board	CP1W-CIF11	Mounted in the option slot of an N-type CPU Unit with 30 or 40 I/O points and can be used as an RS-422A/485 port.  Maximum transmission distance: 50 m	Includ- ing in CPU	_	Includ- ing in CPU
Isolated RS-422A/485 Option Board	CP1W-CIF12	Mounted in the option slot of an N-type CPU Unit with 30 or 40 I/O points and can be used as an RS-422A/485 port.  Maximum transmission distance: 500 m	0.075A	-	30g
Battery	CP1W-BAT01	Mounted in an N-type CPU Unit.  Mount the Battery to an N-type CPU Unit if data in the following areas need to be retained after a power interruption.  DM Area (D) (excluding words backed up to the EEPROM using the DM backup function)  Holding Area (H) Counter Present Values and Completion Flags (C)  Auxiliary Area related to clock function (A) A Battery cannot be mounted to an E-type CPU Unit.	-	-	-

Note The CP1W-ME05M Memory Cassette, CP1W-DAM01 LCD Option Board, and CP1W-CIF41 Ethernet Option Board cannot be used with the CP1E CPU Unit.

# **Installation and Wiring Products**

Name and appearance	Model number	Specifications and application
DIN Track	PFP-50N	Track length: 50 cm, Height: 7.3 mm
	PFP-100N	Track length: 1 m, Height: 7.3 mm
	PFP-100N2	Track length: 1 m, Height: 16 mm
End Plate	PFP-M	Stopper to prevent Units from moving on the DIN Track.
5		
I/O Connecting Cable	CP1W-CN811	Length: 800 mm
W 00		This cable is used if the connecting cable for the Expansion I/O Unit or Expansion Unit is not long enough or for a vertical configuration.  Only one I/O Connecting Cable can be used in each PLC.

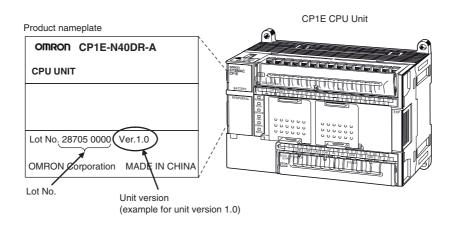
#### 2-2-3 Unit Versions of CPU Units

# **Unit Versions**

A "unit version" has been introduced to manage CPU Units in the CP Series according to differences in functionality accompanying Unit upgrades.

#### Notation of Unit Versions on Products

The unit version is given to the right of the lot number on the nameplate of the products for which unit versions are being managed, as shown below.



#### Confirming Unit Versions with Support Software

CX-Programmer can be used to confirm the unit version of the CP1E CPU Units.

Refer to *4-1 Applicable Programming Devices for CP1E* for details on the CX-Programmer.

The CX-Programmer can be used to confirm the unit version using one of the following methods.

- · Using the PLC Information
- Using the Unit Manufacturing Information

# **Unit Versions**

Туре	Model numbers	Unit version
CP1E CPU Units	CP1E-E□□D□-A	Unit version 1.0
	CP1E-N□□D□-□	

# Unit Versions and Support Software

The relationship between the unit versions of CP1E CPU Units and versions of Support Software is shown below.

#### Relationship between Unit Versions and Support Software

		Re	Required Support Software*						
CPU Unit	Functions used CX-Programmer for CP1E		CX-Programmer (CX-One)	CX-Programmer Micro PLC Limited Edition					
		Version 1.0 or higher	Version 8.2 or higher	Version 8.2 or higher					
CP1E-E□□D□-A	Unit version 1.0	0	0	0					
CP1E-N□□D□-□	functions	Supports Smart Input function.	Does not support Smart Input function.	Does not support Smart Input function.					

<sup>\*</sup> A Programming Console cannot be used.

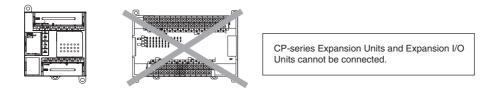
# 2-3 Expansion I/O Unit or Expansion Unit

This section describes the connection of Expansion I/O Units or Expansion Units to a CP1E CPU Unit.

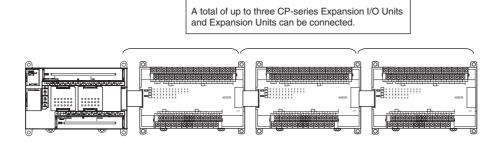
# 2-3-1 Expandable CPU Units

- Expansion I/O Units and Expansion Units cannot be connected to an E-type or N-type CPU Units with 20 I/O points.
- A total of up to three Expansion I/O Units and Expansion Units can be connected to an E-type or N-type CPU Unit with 30 or 40 I/O points.

#### CP1E CPU Unit with 20 I/O Points



#### CP1E CPU Unit with 30 or 40 I/O Points



#### 2-3-2 Connection Methods

Connection cables for the Expansion I/O Units and Expansion Units are used to connect the Units.

The length can be extended by using a CP1W-CN811 I/O Connection Cable (length: 800 mm).

Leave approximately 10mm of space between the CPU Unit and the Exapansion I/O Units or Expansion Units.

# 2-3-3 Maximum Number of I/O Points for an Expansion I/O Unit or Expansion Unit

CPU Unit	Built-in I/O on CPU Unit			Total number of Expansion I/O Units and Expansion Units that can	Number of inputs: 24 Number of outputs: 16 Total number of I/O points when three CP1W-40ED□ Expansion I/O Units are connected		
	Total	Number of inputs	Number of outputs	be connected	Total	Number of inputs	Number of outputs
CP1E-□20D□-□	20	12	8	Not possible.	20	12	8
CP1E-□30D□-□	30	18	12	3 Units maxi-	150	90	60
CP1E-□40D□-□	40	24	16	mum	160	96	64

#### **Expansion I/O Units and Expansion Units** 2-3-4

# **Expansion I/O Units**

Name and appearance	Model number	Specific	Specifications			Weight
		Outputs	Inputs	5V	24V	1
8-point Input Unit	CP1W-8ED	Not provided.	8 inputs, 24 VDC	0.018A	_	200g
	00,000					0.50
8-point Output Unit	CP1W-8ER	8 relay outputs	Not provided.	0.026A	0.044A	250g
0100	CP1W-8ET	8 transistor outputs, sinking		0.075A	-	250g
	CP1W-8ET1	8 transistor outputs, sourcing		0.075A	-	250g
16-point Output Unit	CP1W-16ER	16 relay outputs	Not provided.	0.042A	0.090A	280g
1627	CP1W-16ET	16 transistor outputs, sinking		0.076A	_	225g
	CP1W-16ET1	16 transistor outputs, sourcing		0.076A	_	225g
20-point I/O Unit	CP1W-20EDR1	8 relay outputs	12 inputs, 24 VDC	0.103A	0.044A	300g
E	CP1W-20EDT	8 transistor outputs, sinking		0.130A	_	300g
0	CP1W-20EDT1	8 transistor outputs, sourcing		0.130A	_	300g
32-point Output Unit	CP1W-32ER	32 relay outputs	Not provided.	0.049A	0.131A	465g
Mile	CP1W-32ET	32 transistor outputs, sinking		0.113A	_	325g
0 9 0	CP1W-32ET1	32 transistor outputs, sourcing		0.113A	-	325g
40-point I/O Unit	CP1W-40EDR	16 relay outputs	24 inputs, 24 VDC	0.080A	0.090A	380g
4200	CP1W-40EDT	16 transistor outputs, sinking		0.160A	_	320g
0 9 90	CP1W-40EDT1	16 transistor outputs, sourcing		0.160A	-	320g

# **Expansion Units**

Name and appearance	Model number	Specifications		rrent mption	Weight
		·	5V	24V	
Analog I/O Unit	CP1W-MAD11	2 analog inputs 0 to 5 V, 1 to 5 V, 0 to 10 V, -10 to 10 V, 0 to 20 mA, and 4 to 20 mA 1 analog output 1 to 5 V, 0 to 10 V, -10 to 10 V, 0 to 20 mA, 4 to 20 mA Resolution: 1/6,000	0.083A	0.110A	250g
Analog Input Unit	CP1W-AD041	4 analog inputs 0 to 5 V, 1 to 5 V, 0 to 10 V, -10 to 10 V, 0 to 20 mA, and 4 to 20 mA Resolution: 1/6,000	0.100A	0.090A	200g
Analog Output Unit	CP1W-DA041	4 analog outputs 1 to 5 V, 0 to 10 V, -10 to 10 V, 0 to 20 mA, and 4 to 20 mA Resolution: 1/6,000	0.080A	0.124A	200g
Temperature Sensor Unit	CP1W-TS001	Thermocouple inputs K or J, 2 inputs	0.040A	0.059A	250g
	CP1W-TS002	Thermocouple inputs K or J, 4 inputs	0.040A	0.059A	250g
	CP1W-TS101	Platinum resistance thermometer inputs Pt100 or JPt100, 2 inputs	0.054A	0.073A	250g
	CP1W-TS102	Platinum resistance thermometer inputs Pt100 or JPt100, 4 inputs	0.054A	0.073A	250g
CompoBus/S I/O Link Unit	CP1W-SRT21	Can perform communications as a Compo- Bus/S slave via 8 inputs and 8 outputs.	0.029A	_	200g

#### 2-3-5 **Restrictions on System Configuration**

The following restrictions apply to the CP-series Expansion Units and CP-series Expansion I/O Units that can be connected to CP1E CPU Units.

## Restriction on the Number of Connected Units

A total of up to three Expansion Units and Expansion I/O Units can be connected to a CPU Unit with either 30 or 40 I/O points. Expansion Units and Expansion I/O Units cannot be connected to CPU Units with 20 I/O points.

# Restrictions on External Power Supply Capacity

The following restrictions apply when using the CPU Unit's external power supply.

#### AC-power-supply CPU Unit with 30 or 40 I/O Points

The power supply capacity is restricted for AC-power-supply CPU Units with 30 or 40 I/O points. It may not be possible to use the full 300 mA of the external power supply, though a CPU Unit can connect any CP-series Expansion I/O Unit or Expansion Unit.

The entire 300 mA from the external power supply can be used if Expansion Units and Expansion I/O Units are not connected.

Refer to 2-4-1 External Power Supply Capacity When Expansion I/O Units or Expansion Units are Connected for details.

### AC-power-supply or DC-power-supply CPU Unit with 20 I/O Points

There is no external power supply on AC-power-supply or DC-power-supply CPU Units with 20 I/O points.

# Restrictions by ambient temperature

According to the ambient temperature, there are restrictions on power supply voltage and output load current for the DC-power-supply CPU Units.

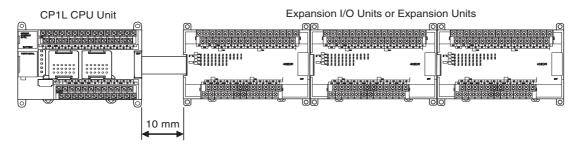
Refer to Output Specifications for Relay Outputs in 3-1-3 Common I/O Specifications and in 3-2-4 I/O Specifications for details.

# **Restrictions on the Number of Simultaneously ON Points**

Use CP1W-32ER/ET/ET1 32-point Output Units with the number of simultaneously ON less than 24 points (75%).

# **Mounting Restriction**

When connecting CP-series Expansion Units or Expansion I/O Units to a CPU Unit with AC power, provide a space of approximately 10 mm between the CPU Unit and the first Expansion Unit or Expansion I/O Unit.



If sufficient space cannot be provided between the CPU Unit and the first Expansion Unit or Expansion I/O Unit, use the PLC in an ambient temperature of 0 to 50°C.

# **Unit Current Consumption and** 2-4 **External Power Supply Capacity**

This section describes the current consumption and external power supply capacity of units used by the

#### 2-4-1 External Power Supply Capacity When Expansion I/O Units or **Expansion Units are Connected**

Power of 24 VDC can be supplied to external devices from CPU Units with 30 or 40 I/O points. Calculate the usable capacity of external power supply according to the following example.

# **Calculation Examples of the Capacity Limit of External Power** Supply

	CPU Unit	Ex	Expansion Units			Limit
		1 <sup>st</sup> unit	2 <sup>nd</sup> unit	3 <sup>rd</sup> unit		
	CP1E-□40D□-A	CP1W- DA041	CP1W- DA041	CP1W- DA041		
5V	0.21A	0.08A	0.08A	0.08A	0.45A	≤1.2A
24V	0.09A	0.124A	0.124A	0.124A	0.462A	≤0.7A
Power consumption	5 V×0.45 A=2.25 W 24 V×0.462 A=11.088 W			13.388 W	≤18.5 W	
Usable capacity of external power supply  18.5 W (Total of usable power consumption) – 13.388 W= 5.162 W 5.162 W/24 V=0.215 A			0.215A	≤0.3A		

# 2-4-2 Current Consumption

#### CPU Units

#### **E-type CPU Units**

I/O capacity	Model number	Current consumption		
i/O capacity	Wiodel Humber	5 VDC	24 VDC	
20 I/O points	CP1E-E20DR-A	0.17A	0.08A	
30 I/O points	CP1E-E30DR-A	0.17A	0.07A	
40 I/O points	CP1E-E40DR-A	0.17A	0.09A	

#### **N-type CPU Units**

I/O consoitu	Model number	Current co	nsumption
I/O capacity	Model number	5 VDC	24 VDC
20 I/O points	CP1E-N20DR-A	0.18A	0.08A
	CP1E-N20DT-A	0.23A	0.02A
	CP1E-N20DT1-A	0.23A	0.02A
	CP1E-N20DR-D	0.18A	0.08A
	CP1E-N20DT-D	0.23A	0.02A
	CP1E-N20DT1-D	0.23A	0.02A
30 I/O points	CP1E-N30DR-A	0.21A	0.07A
	CP1E-N30DT-A	0.27A	0.02A
	CP1E-N30DT1-A	0.27A	0.02A
	CP1E-N30DR-D	0.21A	0.07A
	CP1E-N30DT-D	0.27A	0.02A
	CP1E-N30DT-D	0.27A	0.02A
40 I/O points	CP1E-N40DR-A	0.21A	0.09A
	CP1E-N40DT-A	0.31A	0.02A
	CP1E-N40DT1-A	0.31A	0.02A
	CP1E-N40DR-D	0.21A	0.09A
	CP1E-N40DT-D	0.31A	0.02A
	CP1E-N40DT1-D	0.31A	0.02A

- Note 1 The current consumption of CP1W-CIF01/11 Option Boards is included in the CPU Unit's current consumption.
  - 2 The current consumption of CP1W-CIF12 Option Boards is 0.075A (5 VDC).
  - **3** The current consumptions given in the following table must be added to the current consumption of the CPU Unit if an Expansion Unit or Expansion I/O Unit is connected.

# • Expansion I/O Units and Expansion Units

	Unit na		Model number	Current co	Current consumption		
	Unit na	ime	Model number	5 VDC	24 VDC		
Expan	sion I/O Units	8 inputs	CP1W-8ED	0.018A	-		
		8 outputs	CP1W-8ER	0.026A	0.044A		
			CP1W-8ET	0.075A	-		
			CP1W-8ET1				
		16 outputs	CP1W-16ER	0.042A	0.090A		
			CP1W-16ET	0.76A	_		
			CP1W-16ET1				
		20 I/O points	CP1W-20EDR1	0.103A	0.044A		
		12 inputs	CP1W-20EDT	0.130A	-		
		8 outputs	CP1W-20EDT1				
		32 outputs	CP1W-32ER	0.049A	0.131A		
			CP1W-32ET	0.113A	-		
			CP1W-32ET1				
		40 I/O points	CP1W-40EDR	0.080A	0.090A		
		24 inputs	CP1W-40EDT	0.160A	-		
		16 outputs	CP1W-40EDT1				
Expa- nsion	Analog Input Unit	4 inputs	CP1W-AD041	0.1A	0.09A		
Units	Analog Output Unit	4 outputs	CP1W-DA041	0.080A	0.124A		
	Analog I/O Unit	Analog inputs: 2 Analog outputs: 1	CP1W-MAD11	0.083A	0.110A		
	Temperature	K or J thermocou-	CP1W-TS001	0.040A	0.059A		
	Sensor Units	ples	CP1W-TS002				
		Pt or JPt platinum	CP1W-TS101	0.054A	0.073A		
		resistance ther- mometers	CP1W-TS102				
	CompoBus/S I/O Link Unit	8 inputs 8outputs	CP1W-SRT21	0.029A	_		



# **Part Names and Functions**

This section describes the part names, function specifications and terminal arrangements of the CP1E CPU Unit and other Units.

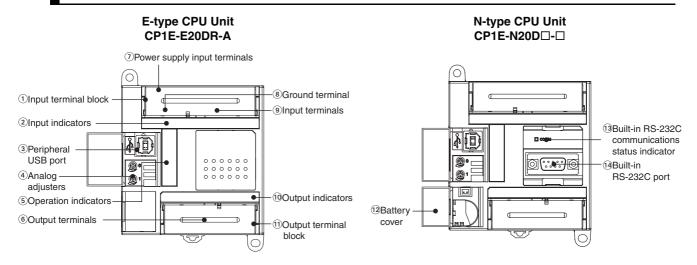
3-1	CPU L	Jnits	-2
	3-1-1	CPU Units with 20 I/O Points	-2
	3-1-2	CPU Units with 30 or 40 I/O Points	-5
	3-1-3	Common I/O Specifications	-8
	3-1-4	Optional Serial Communications Port for N-type CPU Units 3-	13
3-2	Expan	sion I/O Units	16
	3-2-1	Expansion Input Unit	16
	3-2-2	Expansion Output Units	17
	3-2-3	Expansion I/O Units	19
	3-2-4	I/O Specifications 3-2	21

#### **CPU Units** 3-1

This section describes the names of the CPU Unit parts and provides the I/O specifications and terminal arrangements. Refer to A-1 Dimensions for the dimensions, A-2 Wiring Diagrams for the wiring diagrams.

#### 3-1-1 CPU Units with 20 I/O Points

### **Part Names and Functions**



Number	Name	Function
1	Input terminal block	This is the terminal block for inputs such as the power supply input and 24 VDC inputs.
2	Input indicators (yellow)	Input status is displayed. An indicator will be ON when the input is ON.
3	Peripheral USB port	Used to connect to a personal computer for programming and monitoring by the CX-Programmer for CP1E.
4	Analog adjusters	By turning an analog adjuster, it is possible to adjust the value of A642 or A643 within a range of 0 to 255.
5	Operation indicators	The CPU Unit's operating status can be confirmed with this indicator.
		Refer to CPU Unit Status Indicators (Page 3-3).
6	Output terminals	Loads such as lamps, contactors, and solenoid valves can be connected.
7	Power supply input terminals	Power of 100 to 240 VAC or 24 VDC can be supplied.
8	Ground terminal	Protective ground ( $\stackrel{\leftarrow}{=}$ ): To prevent electric shock, ground to 100 $\Omega$ or less.
9	Input terminals	Input devices such as switches and sensors can be connected.
10	Output indicators (yellow)	Output status is displayed. An indicator will be ON when the output is ON.
11)	Output terminal block	This is the terminal block for outputs such as relay outputs and transistor outputs.
12	Battery cover for N-type CPU Units	A Battery can be installed by opening the cover. (The Battery is optional).
13	Built-in RS-232C com- munications status indi- cator	This indicator will be flashing when the built-in RS-232C port is in communication mode.
14	Built-in RS-232C port for N-type CPU Units	By connecting a PT, the controlled system can be monitored and data can be collected.

# **CPU Unit Status Indicators**

●: Not lit ★ : Flashing ★ : Lit



Indicator	Color	Status	Description
POWER	Green	¤ Lit	Power is ON.
		Not lit	Power is OFF.
RUN	Green	¤ Lit	The CP1E is executing a program in either RUN or MONITOR mode.
		Not lit	Operation is stopped in PROGRAM mode or due to a fatal error.
ERR/ALM	Red	¤ Lit	A fatal error (including FALS execution) or a hardware error (WDT error) has occurred.
			CP1E operation will stop and all outputs will be turned OFF.
		)III	A non-fatal error has occurred (including FAL execution).
		Flashing	CP1E operation will continue.
		Not lit	Normal
INH	Yellow	¤	The Output OFF Bit (A500.15) was turned ON.
		Lit	All outputs will be turned OFF.
		Not lit	Normal
PRPHL	Yellow	∭ Flashing	Communications (either sending or receiving) are in progress through the peripheral USB port.
		Not lit	Other than the above.
BKUP	Yellow	¤ Lit	The user programs, parameters, or specified DM Area words are being written to the backup memory (built-in EEPROM).
		Not lit	Other than the above.



#### **Precautions for Safe Use**

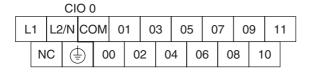
Do not turn OFF the power supply to the PLC when the BKUP indicator is lit. It indicates that data is being written to the backup memory (built-in EEPROM).

If the power supply is turned OFF while the BKUP indicator is ON, data in the backup memory (built-in EEPROM) may be destroyed.

# **Terminal Arrangements**

#### Input Arrangement

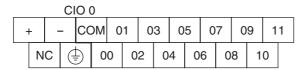
#### **AC Power Supply**



L1,L2/N: Power supply terminal (<u>+</u>) : Protective ground terminal

COM : Common terminal 00 to 11: Input terminal NC : No connection

#### **DC Power Supply**

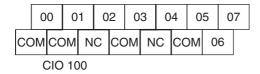


: Power supply terminal (<u>+</u>) : Protective ground terminal

COM : Common terminal 00 to 11: Input terminal : No connection

#### Output Arrangement

#### **AC Power Supply and DC Power Supply**



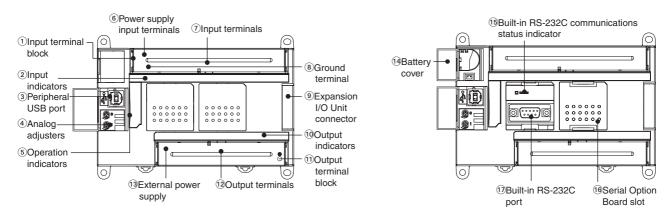
COM : Common terminal 00 to 07: Output terminal NC : No connection

### 3-1-2 CPU Units with 30 or 40 I/O Points

# **Part Names and Functions**

# E-type CPU Unit CP1E-E30/40DR-A

# N-type CPU Unit CP1E-N30/40D□-□

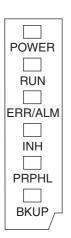


Number	Name	Function			
1	Input terminal block	This is the terminal block for inputs such as the power supply input and 24-VDC inputs.			
2	Input indicators (yellow)	Input status is displayed. An indicator will be ON when the input is ON.			
3	Peripheral USB port	Used to connect to a personal computer for programming and monitoring by the CX-Programmer for CP1E.			
4	Analog adjusters	By turning an analog adjuster, it is possible to adjust the value of A6 or A643 within a range of 0 to 255.			
(5)	Operation indicators	The CPU Unit's operating status can be confirmed with this indicator.			
		Refer to CPU Unit Status Indicators (Page 3-6).			
6	Power supply input terminal	Power of 100 to 240 VAC or 24 VDC can be supplied.			
7	Input terminals	Input devices such as switches and sensors can be connected.			
8	Ground terminal	Protective ground ( $\stackrel{\leftarrow}{\equiv}$ ): To prevent electric shock, ground to 100 $\Omega$ or less.			
		Functional ground ( $\stackrel{\leftarrow}{=}$ ): If noise is a significant source of errors or if electrical shock is a problem, connect to the protective ground terminal and ground both with a ground of $100\Omega$ or less (AC power supply only).			
9	Expansion I/O Unit connector	CP-series Expansion I/O Units or Expansion Units such as Analogue I/O Units, and Temperature Sensors can be connected.			
		Refer to 5-2-4 Connecting Expansion I/O Units and Expansion Units.			
10	Output indicators (yellow)	Output status is displayed. An indicator will be ON when the output is ON.			
11)	Output terminal block	This is the terminal block for outputs such as relay outputs, transistor outputs, and the external power supply output.			
12)	Output terminals	Loads such as lamps, contactors, and solenoid valves can be connected.			
13	External power supply ter- minals	The external supply terminals output up to 300 mA max at 24 VDC.  They can be used as a service power supply for input devices (AC power supply only).			
14)	Battery cover for N-type CPU Units	A Battery can be installed by opening the cover. (Battery is optional).			
15	Built-in RS-232C communications status indicator	This indicator will be flashing when the built-in RS-232C port is in communication mode.			

Name	Function
Option Board slot for N-type	An Option Board can be connected to the slot.
CPU Units	· CP1W-CIF01 RS-232C Option Board
	· CP1W-CIF11 RS-422A/485 Option Board (Maximum transmission distance: 50 m) or CP1W-CIF12 RS-422A/485 Option Board (Maximum transmission distance: 500 m)
Built-in RS-232C port for N-type CPU Units	By connecting a PT, the controlled system can be monitored and data can be collected.
	Option Board slot for N-type CPU Units

# **CPU Unit Status Indicators**

●: Not lit 🕱 : Flashing 💢 : Lit



Indicator	Color	Status	Description	
POWER	Green	¤ Lit	Power is ON.	
		Not lit	Power is OFF.	
RUN	Green	¤ Lit	The CP1E is executing a program in either RUN or MONITOR mode.	
		Not lit	Operation is stopped in PROGRAM mode or due to a fatal error.	
ERR/ALM	Red	¤ Lit	A fatal error (including FALS execution) or a hardware error (WDT error) has occurred.  CP1E operation will stop and all outputs will be turned OFF.	
			A non-fatal error has occurred (including FAL execution).	
		Flashing	CP1E operation will continue.	
		Not lit	Normal	
INH	Yellow	¤ Lit	The Output OFF Bit (A500.15) was turned ON. All outputs will be turned OFF.	
		Not lit	Normal	
PRPHL	Yellow	Communications (either sending or receiving) are in progres flashing the peripheral USB port.		
		Not lit	Other than the above.	
BKUP	Yellow	¤ Lit	The user program, parameters, or specified DM Area words are being written to the backup memory (built-in EEPROM).	
		Not lit	Other than the above.	

#### **Precautions for Safe Use**

Do not turn OFF the power supply to the PLC when the BKUP indicator is lit. It indicates that data is being written to the backup memory (built-in EEPROM).

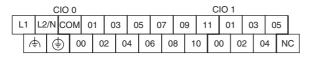
If the power supply is turned OFF while the BKUP indicator is ON, data in the backup memory (built-in EEPROM) may be destroyed.

# **Terminal Arrangements**

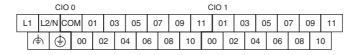
#### Input Arrangement

#### **AC Power Supply**

CP1E-□30D□-A



#### CP1E-□40D□-A



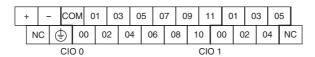
L1,L2/N: Power supply terminal
COM: Common terminal
00 to 11: Input terminal

: Functional ground terminal : Protective ground terminal

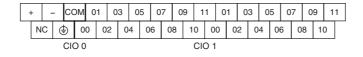
NC : No connection

#### **DC Power Supply**

CP1E-N30D□-D



#### CP1E-N40D□-D



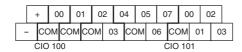
+,- : Power supply terminal
COM : Common terminal
00 to 11 : Input terminal
NC : No connection

: Protective ground terminal

#### Output Arrangement

#### **AC Power Supply**

CP1E-□30D□-A

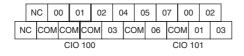


#### CP1E-□40D□-A

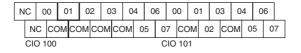


#### **DC Power Supply**

CP1E-N30D□-D



#### CP1E-N40D□-D



+,- : External supply terminal COM : Common terminal

00 to 07 : Output terminal

NC: No connection
COM: Common terminal
00 to 07: Output terminal

#### 3-1-3 **Common I/O Specifications**

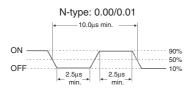
The following table gives the specifications that apply to the built-in I/O on a CP1E CPU Unit.

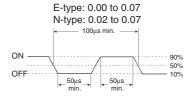
# **Specifications**

Item	Specification			
Input type	High-speed counter inputs or normal inputs	interrupt i respor	counter inputs, nputs, quick- nse inputs mal inputs	Normal inputs
Input bits	CIO 0.00 to CIO 0.01	CIO 0.02	to CIO 0.07*1	CIO 0.08 to CIO 0.11 and CIO 1.00 to CIO 1.11*1
Input voltage	24 VDC, +10%, -15%			
Applicable sensors	2-wire and 3-wire sensors			
Input impedance	3.3 kΩ	3.3 kΩ		4.8 kΩ
Input current	7.5 mA typical	7.5 mA typical		5 mA typical
ON voltage/ current	3 mA min. at 17.0 VDC min.	3 mA min. at 1	17.0 VDC min.	3 mA min. at 14.4 min.
OFF voltage/ current	1 mA max. at 5.0 VDC max.	1 mA max. at	5.0 VDC max.	1 mA max. at 5.0 VDC max.
ON response time*2	E-type CPU Unit: 50 μs min. N-type CPU Unit: 2.5 μs min.	50 μs max.		1 ms max.
OFF response	E-type CPU Unit: 50 μs min.	50 μs max.		1 ms max.
time*2	N-type CPU Unit: 2.5 μs min.			
Circuit	E-type CPU Unit		N-type CPU Unit	
configuration	Inputs: CIO 0.00 to CIO	0.07	Inputs:	CIO 0.00, CIO 0.01
		Internal	IN 3.3kg	Input indicator 1000pF Internal circuits
	Inputs: CIO 0.08 to CIO 0.11 and CIO 1.00 to CIO 1.11		Inputs: CIO 0.02 to CIO 0.07	
			IN 3.3kΩ	Input indicator  1000pF  Internal circuits
				CIO 0.08 to CIO 0.11 O 1.00 to CIO 1.11  Input indicator  Internal circuits

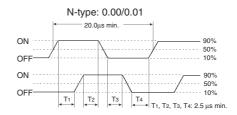
- \*1 The bits that can be used depend on the model of CPU Unit.
- \*2 The response time is the delay caused by hardware. The delay set in the PLC Setup (0 to 32 ms, default: 8 ms) for a normal input must be added to this value.

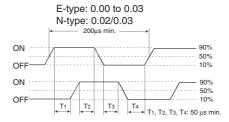
Pulse plus direction input mode, Increment mode Up/down input mode





#### Differential phase mode





# **Output Specifications for Relay Outputs**

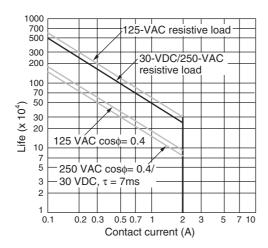
#### CP1E-□□□DR-□

Item			Specification		
Maximum switching capacity			2 A 250 VAC (cosφ= 1)		
			2 A 24 VDC (4 A/common)		
Minimum switch	ning capacit	ty	10 mA 5 VDC		
Service life of relay			200,000 operations (24 VDC)		
			70,000 operations (250 VAC, $\cos \phi = 0.4$ )		
	Mechanica	al	20,000,000 operations		
ON response ti	me		15 ms max.		
OFF response	time		15 ms max.		
Circuit configuration			Output indicator  Out  Internal circuits  Com 250 VAC, 2A, 24 VDC, 2 A max.		

#### Estimating the Service Life of Relays

Under normal conditions, the service life of output contacts is as shown above. The service life of relays is as shown in the following diagram as a guideline.

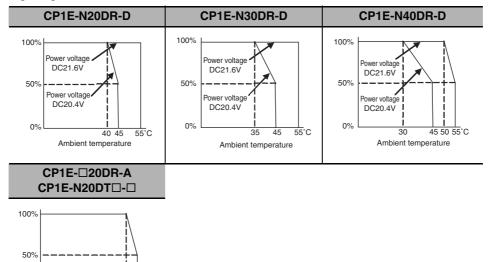
#### CP1E-□□DR-□



Ambient temperature

#### Relationship between Continuous Simultaneous ON Rate and Ambient **Temperature**

There are restrictions on the power supply voltage and output load current imposed by the ambient temperature. Make sure that the power supply voltage and output load current are within the following ranges.



Note The above restrictions apply to the relay output load current from the CPU Unit even if Expansion I/O Units are not connected.

# Output Specifications for Transistor Outputs (Sinking or Sourcing)

CP1E-N30/40DT(1)-□, CP1E- N20DT(1)-□

#### Normal Outputs

	Specification			
Item	CIO 100.00 and CIO 100.01	CIO 100.02 to CIO 100.07 and CIO 101.00 to CIO 101.07*2		
Maximum switching capacity	0.3 A/output, 0.9 A/common*1 4.5 to 30 VDC CP1E-N20D□-□: 1.8 A/Unit CP1E-N30D□-□: 2.7 A/Unit CP1E-N40D□-□: 3.6 A/Unit			
Minimum switching capacity	1 mA 4.5 to 30 VDC			
Leakage current	0.1mA max.			
Residual voltage	0.6 V max.	1.5V max.		
ON response time	0.1 ms max.	0.1 ms max.		
OFF response time	0.1 ms max.	1 ms max.		
Fuse	Not provided.			
Circuit configuration	Normal outputs: CIO 100.00 to CIO 100.01 (sinking)  OUT OUT OUT 4.5 to 30 VDC COM(-)  OUT COM(-)  OUT COM(-)  OUT COM(-)  OUT COM(-)  OUT OUT COM(-)  OUT OUT OUT OUT OUT OUT OUT OUT OUT OU	Normal outputs: CIO 100.02 to CIO 101.07 (sinking)  OUT  OUT  45 to 30  VDC  COM(-)  OUT  COM(-)  COM(-)  OUT  COM(-)  COM(-)  OUT  COM(-)  COM(-)  OUT  COM(-)  COM(-)  OUT  COM(-)  COM(-)  COM(-)  OUT  COM(-)  COM		
	Normal outputs: CIO 100.00 to CIO 100.01 (sourcing)      Internal circuits     OUT OUT OUT OUT OUT OUT OUT OUT OUT	Normal outputs: CIO 100.02 to CIO 101.07 (sourcing)    COM(+)		

- \*1 Also do not exceed 0.9 A for the total for CIO 100.00 to CIO 100.03.
- \*2 The bits that can be used depend on the model of CPU Unit.



#### **Precautions for Correct Use**

Do not connect a load to an output terminal or apply a voltage in excess of the maximum switching capacity.

### • Pulse Outputs (CIO 100.00 and CIO 100.01)

Item	Specification
Maximum switching capacity	100 mA 4.5 to 26.4 VDC
Minimum switching capacity	7 mA 4.5 to 26.4 VDC
Maximum output frequency	100 kHz
Output waveform	OFF 90%  ON 10%  4μs min. 2μs min.

#### **Additional Information**

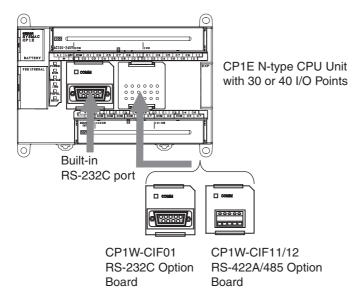
- The load for the above values is assumed to be the resistance load, and does not take into account the impedance for the connecting cable to the load.
- · Due to distortions in pulse waveforms resulting from connecting cable impedance, the pulse widths in actual operation may be smaller than the values shown above.

#### • PWM Output (CIO 100.01)

Item	Specification		
Maximum switching capacity	30 mA 4.5 to 26.4 VDC		
Maximum output frequency	32 kHz		
PWM output accuracy	For ON duty +1%, -0%:10 kHz output		
	For ON duty +5%, -0%: 0 to 32 kHz output		
Output waveform	OFF  ON   ON duty= $\frac{\text{ton}}{\text{T}} \times 100\%$		

## 3-1-4 Optional Serial Communications Port for N-type CPU Units

The Serial Communication Port can be used for a CP1E N-type CPU Unit.



#### **Optional Serial Communication Board**

Model numbers	Port	Maximum transmission distance	Connection method
CP1W-CIF01	One RS-232C port	15m	Connector (D-sub, 9 pin female)
CP1W-CIF11	One RS-422A/485 port (not isolated)	50m	Terminal block (using ferrules)
CP1W-CIF12	One RS-422A/485 port (isolated)	500m	Terminal block (using ferrules)

#### How to mount an Option Board

When mounting an Option Board, first remove the slot cover.

Grasp both of the cover's up/down lock levers at the same time to unlock the cover, and then pull the cover out.

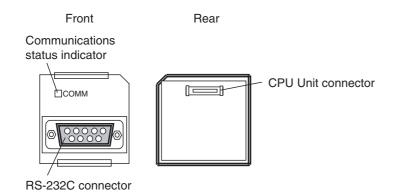
Then to mount the Option Board, check the alignment and firmly press it in until it snaps into place.



#### **Precautions for Correct Use**

Always turn OFF the power supply to the PLC before mounting or removing an Option Board.

# Built-in RS-232C Port and CP1W-CIF01 RS-232C Option Board

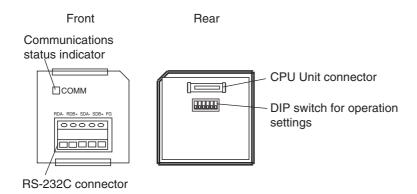


#### RS-232C Connector

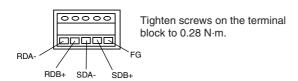


Pin	Abbr.	Signal	Signal direction
1	FG	Frame ground	-
2	SD(TXD)	Send data	Outputs
3	RD(RXD)	Receive data	Inputs
4	RS(RTS)	Request to send	Outputs
5	CS(CTS)	Clear to send	Inputs
6	5V	Power	-
7	DR(DSR)	Data set ready	Inputs
8	ER(DTR)	Data terminal ready	Outputs
9	SG(0V)	Signal ground	-
Connector hood	FG	Frame ground	_

# CP1W-CIF11 or CP1W-CIF12 RS-422A/485 Option Board



#### RS-422A/485 Terminal Block



### • DIP switch for operation settings



Pin		Setting			
1	ON	ON (both ends)	Terminating resistance selection		
	OFF	OFF			
2	ON	2-wire connections	2-wire or 4-wire selection*1		
	OFF	4-wire connections			
3	ON	2-wire connections	2-wire or 4-wire selection*1		
	OFF	4-wire connections			
4	-	-	Not used.		
5	ON	RS control enabled	RS control selection for RD*2		
	OFF	RS control disabled (Data always received.)			
6	ON	RS control enabled	RS control selection for SD*3		
	OFF	RS control disabled (Data always sent.)			
always sent.)					

<sup>\*1</sup> Set both pins 2 and 3 to either ON (2-wire) or OFF (4-wire).

<sup>\*2</sup> To disable the echo-back function, set pin 5 to ON (RS control enabled).

<sup>\*3</sup> When connecting to a device on the N side in a 1: N connection with the 4-wire method, set pin 6 to ON (RS control enabled).

Also, when connecting by the 2-wire method, set pin 6 to ON (RS control enabled).

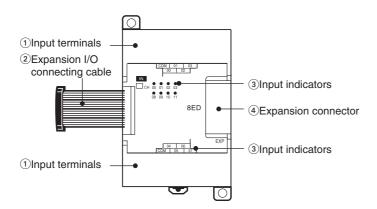
#### **Expansion I/O Units** 3-2

This section describes the names of the Expansion I/O Unit parts and provides the input specifications and terminal arrangement. Refer to A-1 Dimensions for the dimensions, A-2 Wiring Diagrams for the wiring diagrams.

#### **Expansion Input Unit** 3-2-1

## **Part Names and Functions**

8-point Input Units (CP1W-8ED)

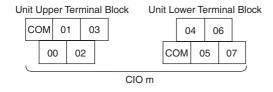


Number	Name	Function
1	Input terminals	Used to connect input devices.
2	Expansion I/O connecting cable	This is a connection cable to connect the adjacent CPU Unit, Expansion I/O Unit, or Expansion Unit. For extended connections or vertical arrangements, use the CP1W-CN811 I/O Connecting Cable (length: 800 mm).
3	Input indicators	Input status is displayed. An indicator will be ON when the input is ON.
4	Expansion connector	CP-series Expansion I/O Units or Expansion Units can be connected.
		Refer to 5-2-4 Connecting Expansion I/O Units and Expansion Units.

## **Terminal Arrangements**

The first word of input words allocated to the Expansion Input Unit is indicated by CIO m.

#### Input Terminal Arrangement



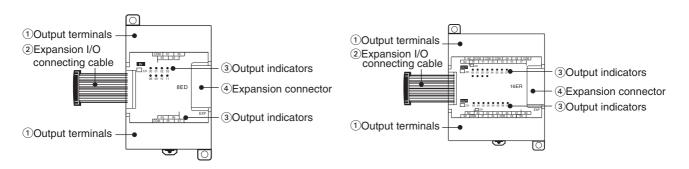
Note COM terminals are connected inside.

## 3-2-2 Expansion Output Units

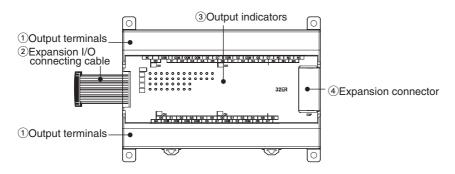
## **Part Names and Functions**

# 8-point Output Units CP1W-8ER/8ET/8ET1

#### 16-point Output Units CP1W-16ER/ET/ET1



# 32-point Output Units CP1W-32ER/ET/ET1

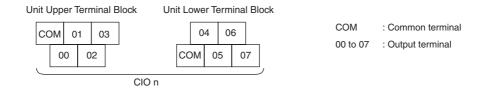


Number	Name	Function
1	Output terminals	Used to connect output devices.
2	Expansion I/O con- necting cable	This is a connection cable to connect the adjacent CPU Unit, Expansion I/O Unit, or Expansion Unit. For extended connections or vertical arrangements, use the CP1W-CN811 I/O Connecting Cable (length: 800 mm).
3	Output indicators	Output status is displayed. An indicator will be ON when output is ON.
4	Expansion connector	CP-series Expansion I/O Units or Expansion Units can be connected.
		Refer to 5-2-4 Connecting Expansion I/O Units and Expansion Units.

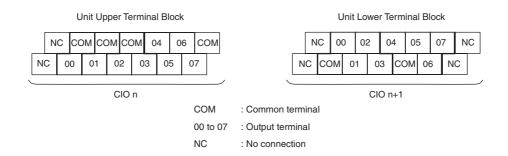
## **Terminal Arrangements**

The first word of output words allocated to the Expansion Output Unit is indicated by CIO n.

## 8-point Output Units (CP1W-8E□)

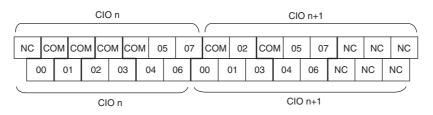


#### • 16-point Output Units (CP1W-16E□)

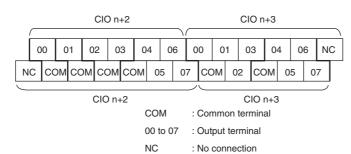


## Units with 32 Output Points (CP1W-32E□)

#### Unit Upper Terminal Block



#### Unit Lower Terminal Block

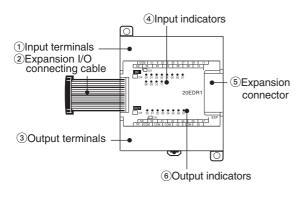


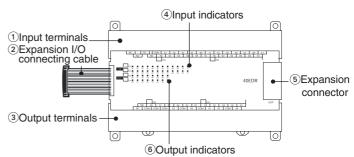
## 3-2-3 Expansion I/O Units

## **Part Names and Functions**

# Units with 20 I/O Points CP1W-20EDR1/EDT/EDT1

# Units with 40 I/O Points CP1W-40 EDR/EDT/EDT1





Number	Name	Function
1)	Input terminals	Used to connect input devices.
2	Expansion I/O connecting cable	This is a connection cable to connect the adjacent CPU Unit, Expansion I/O Unit, or Expansion Unit. For extended connections or vertical arrangements, use the CP1W-CN811 I/O Connecting Cable (length: 800 mm).
3	Output terminals	Used to connect output devices.
4	Input indicators	Input status is displayed. An indicator will be ON when the input is ON.
(5)	Expansion connector	CP-series Expansion I/O Units or Expansion Units can be connected.
		Refer to 5-2-4 Connecting Expansion I/O Units and Expansion Units.
6	Output indicators	Output status is displayed. An indicator will be ON when the output is ON.

## **Terminal Arrangements**

The first word of input words allocated to the Expansion I/O Unit is indicated by CIO m and the first word of the output words by CIO n.

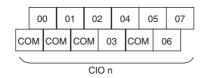
#### 20-point I/O Units (CP1W-20ED□)

• Input (Unit Upper Terminal Block)



COM : Common terminal 00 to 11 : Input terminal : No connection

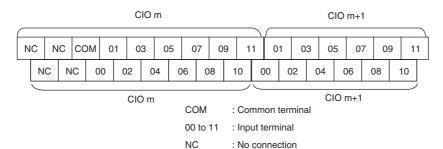
• Output (Unit Lower Terminal Block)



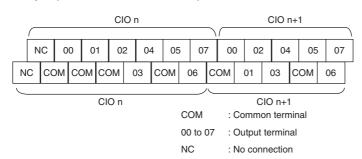
COM : Common terminal 00 to 07 : Output terminal

## 40-point I/O Units (CP1W-40ED□)

• Input (Unit Upper Terminal Block)



• Output (Unit Lower Terminal Block)



## 3-2-4 I/O Specifications

This section describes the I/O specifications common to all Expansion I/O Units.

## I/O Specifications

## Input Specifications (CP1W-8ED/20EDR1/20EDT/20EDT1/40EDR/40EDT/40EDT1)

Item	Specification
Input voltage	24 VDC, +10%, -15%
Input impedance	4.7 kΩ
Input current	5 mA typical
ON voltage	14.4 VDC min.
OFF voltage	5.0 VDC max.
ON response time	1 ms max.*
OFF response time	1 ms max.*
Circuit configuration	Output indicator  IN  A7K\(\Omega\)  COM I  Output indicator  Internal circuits

<sup>\*</sup> The response time is the delay caused by hardware. The delay set in the PLC Setup (0 to 32 ms, default: 8 ms) must be added to this value. For the CP1W-40EDR/EDT/EDT1, a fixed value of 16 ms must be added.



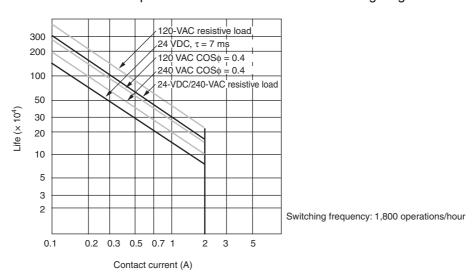
#### **Precautions for Safe Use**

Do not apply voltage in excess of the rated voltage to the input terminal.

## Output Specifications for Relay Outputs (CP1W-8ER/16ER/20EDR1/32ER/40EDR)

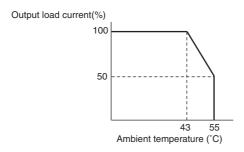
	Item		Specification	
Maximum	switching cap	acity	2 A 250 VAC (cosφ = 1), 2 A 24 VDC (4 A/common)	
Minimum s	switching cap	acity	10 mA 5 VDC	
Service life of relay	Electrical	Resistive load	150,000 operations (24 VDC)	
		Inductive load	100,000 operations (240 VAC, $\cos \phi = 0.4$ )	
	Mechanical		20,000,000 operations	
ON respor	nse time		15 ms max.	
OFF respo	onse time		15 ms max.	
OFF response time Circuit configuration			Output indicator  Output indicator  OUT  Internal circuits  COM 250 VAC, 2A, 24 VDC, 2 A max.	

· Estimating the Service Life of Relays The service life of output contacts is as shown in the following diagram.



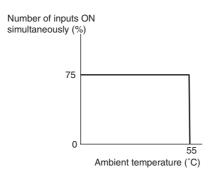
 Restrictions of CP1W-16ER/32ER In addition to the above restrictions, limit the output load current so that it satisfies the following derating curve.

#### CP1W-16ER/32ER



• CP1W-32ER's maximum number of simultaneously ON output points is 24 (75%).

# Relation between Number of ON Outputs and Ambient Temperature (CP1W-32ER)



According to the ambient temperature, there are restrictions on power supply voltage and output load current for the CPU Units connected with the Expansion I/O Units (CP1W-8ER/16ER/20EDR1/32ER/40EDR). Use the PLC in the range of the power supply voltage and output load current as show below.

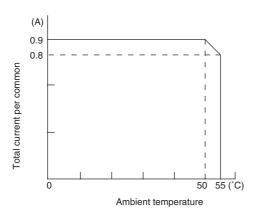
The ambient temperature is restricted for the DC-power-supply CPU Units (CP1E-N□□□-D).
 Derating curve of the output load current for Expansion I/O Units (CP1W-8ER/16ER/20EDR1/32ER/40EDR).

Connected to CP1E-N30DR-D	Connected to CP1E-N40DR-D	Connected to CP1E-N30DT□-D	Connected to CP1E-N40DT□-D	
Power voltage: 21.6 VDC Power voltage: 20.4 VDC 35 45 55°C Ambient temperature	Power voltage: 21.6 VDC Power voltage: 20.4 VDC OM Note that the second	Power voltage: 21.6 VDC Power voltage: 20.4 VDC  35 45 55°C Ambient temperature	Power voltage: 21.6 VDC Power voltage: 20.4 VDC 35 45 55°C Ambient temperature	

## • Output Specifications for Transistor Outputs (Sinking or Sourcing)

	Specification							
Item	CP1W-40EDT	CP1W-32ET CP1W-32ET1	CP1W-20EDT CP1W-20EDT1	CP1W-16ET CP1W-16ET1	CP1W-8ET CP1W-8ET1			
Maximum	4.5 to 30 VDC	4.5 to 30 VDC	24 VDC +10%/-5%	4.5 to 30 VDC	4.5 to 30 VDC			
switching	0.3 A/output	0.3 A/output	0.3 A/output	0.3 A/output	0.3 A/output			
capacity* <sup>1</sup>	0.9 A/common 3.6 A/Unit	0.9 A/common 7.2 A/Unit	0.9 A/common 1.8 A/Unit	0.9 A/common 3.6 A/Unit	0.9 A/common 1.8 A/Unit			
Leakage current	0.1 mA max.	0.1 mA max.	0.1 mA max.	0.1 mA max.	0.1 mA max.			
Residual voltage	1.5 V max.	1.5 V max.	1.5 V max.	1.5 V max.	1.5 V max.			
ON response time	0.1 ms max. 0.1 ms max.		0.1 ms	0.1 ms max.	0.1 ms max.			
OFF response	1 ms max.	1 ms max.	1 ms max.	1 ms max.	1 ms max.			
time	At 24 VDC +10%/ -5%, 5 to 300 mA	At 24 VDC +10%/ -5%, 5 to 300 mA	At 24 VDC +10%/ -5%, 5 to 300 mA	At 24 VDC +10%/ -5%, 5 to 300 mA	At 24 VDC +10%/ -5%, 5 to 300 mA			
Maximum number of simultaneously ON outputs	16 points (100% load)	24 points (100% load)	8 points (100% load)	16 points (100% load)	8 points (100% load)			
Fuse*2			1 fuse/common					
Circuit configuration	Sinking Output indicator Internal circuits Output indicator Output indicat							

\*1 If the ambient temperature is maintained below 50°C, up to 0.9 A/common can be used.



\*2 The fuse cannot be replaced by the user. Replace the Unit if the fuse breaks due to an short-circuit or overcurrent.



#### **Precautions for Safe Use**

Do not connect a load to an output terminal or apply a voltage in excess of the maximum switching capacity.



# **Programming Device**

This section describes the features of the CX-Programmer for CP1E used for programming and debugging PLCs, as well as how to connect the PLC with the Programming Device.

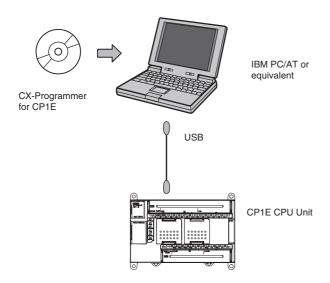
4-1	Applic	cable Programming Devices for CP1E	4-2
	4-1-1	Applicable Programming Devices	4-2
	4-1-2	CX-Programmer for CP1E	4-3
	4-1-3	Operating Environment and System Configuration	4-4
	4-1-4	Features of the CX-Programmer for CP1E	4-4
	4-1-5	Installing the Software	4-7
4-2	Conne	ecting by USB	4-8
	4-2-1	Connecting by USB	4-8
	4-2-2	Installing the USB Driver	4-9

# **Applicable Programming Devices for** CP1E

A programming device is a software application for initializing, programming, monitoring, and debugging PLCs. This section describes the programming device used by CP1E.

#### 4-1-1 **Applicable Programming Devices**

The programming devices in the following table are used to program and monitor the CP1E Unit.



Product	Model	Compatible CX-Programmer versions	Unit version of CP1E CPU Unit	Support for Smart Input	Saved pro- gram file extension	Reference
CX-Programmer for CP1E	WS02- CXPC3	Version 1.0 or higher	Unit version 1.0	Supported	.CXE	Described in this section.
CX-Programmer (CX-One)	WS02- CXPC1-V8	Version 8.2 or higher*	Ver1.0	Not supported	.CXP	Refer to the CX-Programmer Operation Manual (Cat. No. W446).

- \* To use CX-Programmer version 8.2 with a CP1E CPU Unit, the CX-One version 3 auto-update must be installed.
  - The CX-Programmer for CP1E and CX-Programmer (CX-One) can be used at the same time.
  - The CX-Programmer (CX-One) and the CX-Programmer for CP1E can be installed on the same computer and both applications can be run at the same time.



#### **Precautions for Correct Use**

- This section describes the unique applications and functions of the CX-Programmer for CP1E. In the remainder of this section, "CX-Programmer" refers to the CX-Programmer for CP1E. When using the full version of CX-Programmer provided in CX-One, refer to the CX-Programmer Operation Manual (Cat. No. W446).
- A Programming Console cannot be used for the CP1E. Use the CX-Programmer for CP1E.

## Using Project Files Saved with the CX-Programmer (.CXP) on the CX-Programmer for CP1E

The CX-Programmer for CP1E cannot open a .CXP project created on the CX-Programmer (CX-One). Use programming from a project saved in a .CXP file on the CX-Programmer for CP1E according to the following procedure.

- 1 Start the CX-Programmer (CX-One) and CX-Programmer for CP1E together.
- 2 Copy the rungs of the program to be used from the Ladder Programming Window of the CX-Programmer (CX-One), and paste them into the CX-Programmer for CP1E.



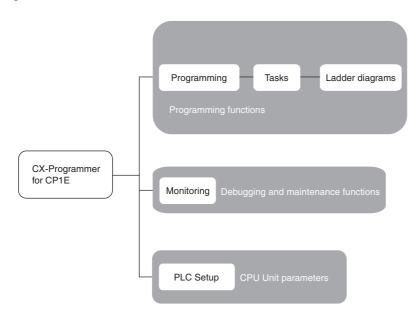
#### **Additional Information**

Files created with the CX-Programmer for CP1E (.CXE) can be opened with CX-Programmer version 8.2 and higher.

## 4-1-2 CX-Programmer for CP1E

## **CX-Programmer for CP1E**

The CX-Programmer for CP1E is a basic software application for creating and debugging PLC programs.



#### 4-1-3 **Operating Environment and System Configuration**

The following system is required to operate the CX-Programmer for CP1E. Make sure your system provides the following conditions and has the necessary components.

Item	Description
Supported computer	IBM PC/AT or equivalent
CD-ROM or DVD-ROM drive	One or more
Supported operating systems	Windows Vista, Windows XP, Windows 2000 (Service Pack 2 or later)
CPU	Pentium II 333 MHz or faster
RAM	256 MB min., 512 MB or more recommended
Required hard disk space	600 MB min.
Display	800 x 600 SVGA min.
PLC and connection port	USB port
Supported PLCs	CP1E

#### 4-1-4 Features of the CX-Programmer for CP1E

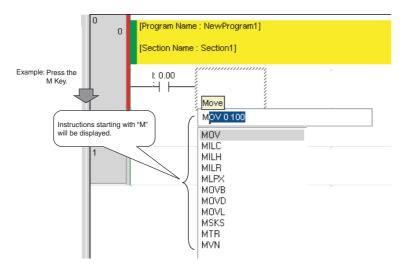
## Simple Menu Configuration

- · With two menu levels, menu commands can be easily found.
- · Options have been simplified.

## **Smart Input Mode That Automatically Displays Candidates**

#### Automatic Instruction Candidate Function

When the first letter of the instruction mnemonic is input, possible instructions are automatically displayed.

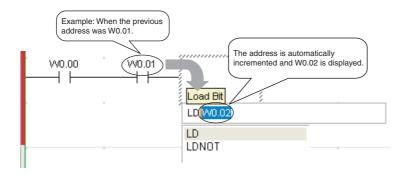


#### Automatic Address Increment Function

The addresses are automatically incremented to the addresses input last time by 1.

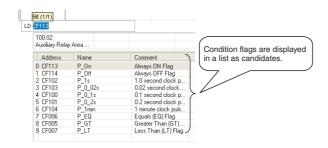
The addresses of inputs and outputs are incremented by 1 respectively.

- +1 bit for a bit address
- +1 word for a word address



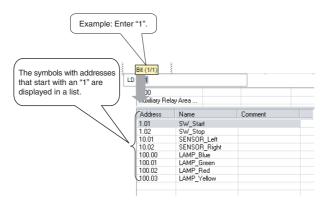
## System-defined Symbol List

Condition Flags are also displayed in a list as candidates.



#### Automatic Symbol Candidate Function

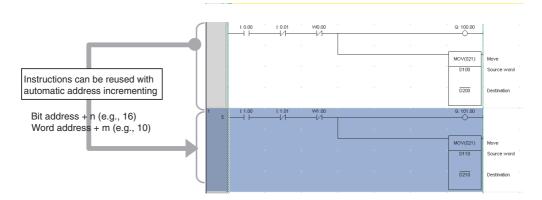
When inputting symbol names, symbol candidates are automatically displayed based on the first letter.



## Instructions Can Be Copied with Automatic Address Incrementing

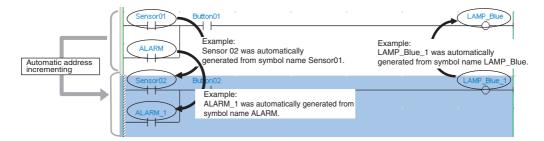
#### Automatic Address Incrementing

A copied group of ladder instructions can be pasted with a specified address offset (e.g., 16 bits).



#### Automatic Generation of Symbol Names and I/O Comments

If there is a symbol name or I/O comment when instructions are copied, new symbols and I/O comments will also be automatically generated.



## 4-1-5 Installing the Software

This section provides a simple description of how to install the CX-Programmer for CP1E on the hard disk of a computer.

## **Preparing for Installation**

Check the following items before beginning with the installation.

#### Available Hard Disk Space

The CX-Programmer for CP1E can be installed on the hard disk only. At least 600 MB of hard disk space is required. Make sure that there is enough space available.

#### Windows Environment and Installation Destination

The CX-Programmer for CP1E is a software application for a Windows operating environment. The software is installed on top of Windows. Make sure that Windows Vista, XP or Windows 2000 is installed and functioning correctly on the computer.

#### USB Port

To transfer ladder programs from the computer to the CP1E and to use the monitoring functions via the USB port, enable the computer's USB port. Refer to the computer's manual for information on enabling the USB port.

## **Installation Procedure**

This section describes how to install the software on a computer using the following drive configuration as an example.

C drive: Hard disk drive D drive: CD-ROM drive

- 1 Start Windows and insert the CX-Programmer for CP1E Master Disk in the CD-ROM drive.

  The installation program will be started by the computer's auto-run function. If the installation program does not start, select *Specify File Name and Run* from the Windows Start Menu, enter "d:\setup" and click the **OK** Button.
- **2** Complete the installation process following the instructions provided on-screen.



#### **Precautions for Correct Use**

Log on as a user with Administrator privileges when uninstalling.

## **Uninstalling the CX-Programmer for CP1E**

Uninstall the CX-Programmer for CP1E when it is no longer required. Uninstall the application using **Add and Remove Applications** in the control panel.



#### **Precautions for Correct Use**

Log on as a user with Administrator privileges when uninstalling.

#### **Connecting by USB** 4-2

This section describes how to connect a computer running the CX-Programmer for CP1E and the CP1E CPU Unit.

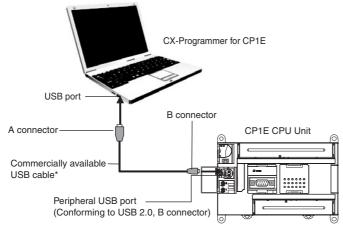
#### 4-2-1 Connecting by USB

## **Preparations for Connection**

The USB driver must be installed in the computer to connect the PLC to the computer using the USB port. Refer to 4-2-2 Installing the USB Driver for the installation of the USB driver.

## **Connection Methods**

Using commercially available USB cable, connect the CX-Programmer for CP1E to the peripheral USB port on the CPU Unit.



<sup>\*</sup> Commercially available USB cable: 5 m max., for USB 2.0.



#### **Precautions for Correct Use**

The CX-Programmer for CP1E cannot be used by connecting to the built-in RS-232C port or a Serial Option Board port of the CP1E CPU Unit.

## **Connecting Cable**

Use the following cable to connect the CP1E CPU Unit to the CX-Programmer for CP1E.

Port at Unit	Port at computer	Network type (com- munications mode)	Model numbers	Length
Peripheral USB port (Conforming to USB 2.0, B connector)	USB port	` ,	Commercially available USB cable (A connector - B connector)	5m max.

## **Restrictions on Connecting by USB**

The following restrictions apply to the connection of the CP1E to a computer due to the USB specifications. Keep these restrictions in mind when using the USB port.

- Only one CP1E CPU Unit can be connected by USB to a single personal computer. It is not possible
  to connect multiple CP1E CPU Units simultaneously.
- Do not remove the USB cable while connected online. The application must be offline before the cable is removed. The CX-Programmer for CP1E will not go online simply by reinserting the USB cable. Place the CX-Programmer offline before reinserting the USB cable, then place it online again.

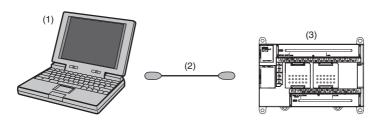
## 4-2-2 Installing the USB Driver

The USB driver for CP1E must be installed on the computer running the CX-Programmer for CP1E in order to connect the CP1E to the computer via USB.

When the personal computer is connected to the CP1E by USB cable, the personal computer automatically recognizes the device and the USB driver installation is started.

## Windows 2000 or Vista

Connect the computer's USB port (1) and the CP1E CPU Unit's peripheral USB port (3) with a USB cable (2).



The USB driver will be automatically installed when the cable is connected.





#### **Additional Information**

If the software is not automatically installed, refer to *Installing a Specified USB Driver* later in this section.

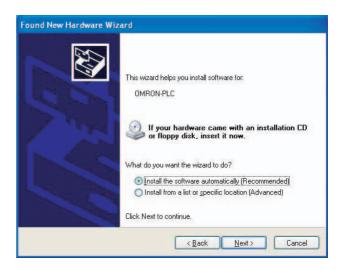
## **Windows XP**

- Turn ON the power supply to the PLC and connect the peripheral USB port on the PLC to the personal computer using a USB cable. The computer will automatically detect the device when the cable is connected and display the following message.
- The following dialog box will be displayed. Select one of the options and click the Next Button.





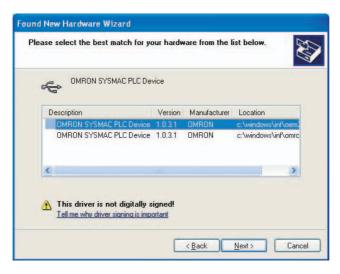
The following dialog box will be displayed. Select the Install the software automatically (Recommended) Option and click the Next Button.





#### **Additional Information**

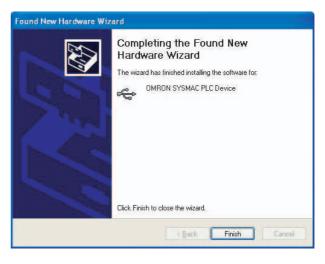
- If the software cannot be installed automatically, refer to *Installing a Specified USB Driver* later in this section.
- If the installation media is not inserted or the USB device driver is installed for another port, a
  Driver List Dialog Box will be displayed. Make sure that the newest driver is selected and click
  the Next Button.



Ignore the following dialog box if it is displayed and click the Continue Anyway Button.



The following dialog box will be displayed if the installation is completed normally. Click the Finish Button.



## **Installing a Specified USB Driver**

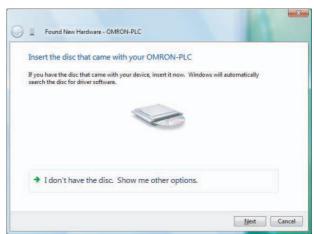
If the USB driver cannot be installed automatically, use the following procedure to install it.

#### Windows Vista

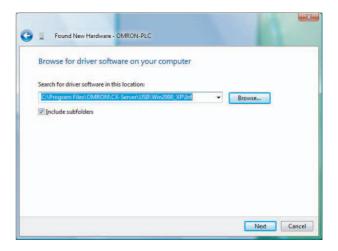
- Turn ON the power supply to the PLC and connect the peripheral USB port on the PLC to the personal computer using a USB cable.
- The following dialog box will be displayed. Select Locate and install driver software (Recommended).



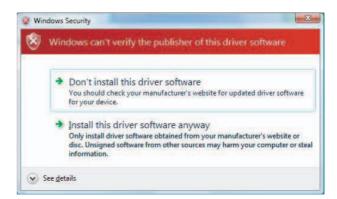
The following dialog box will be displayed. Select I don't have the disc. Show me other options.



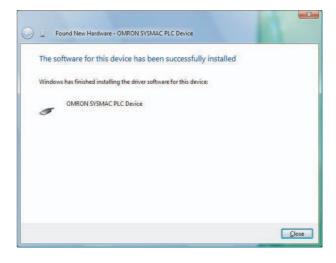
The following dialog box will be displayed. Click the Browse Button, specify the following location, and then click the Next Button. C:\Program Files\OMRON\CX-Server\USB\wind2000\_XP\Inf



Ignore the following dialog box if it is displayed and select *Install this* driver software anyway.



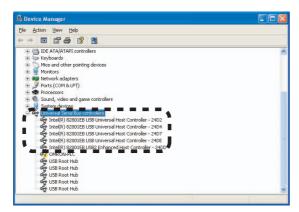
The following dialog box will be displayed when the driver software has been installed successfully.



## **Confirming Installation**

Check that the driver has been installed correctly after the installation.

- From the desktop click Start and right-click My Computer. A pop-up menu will be displayed.
- Select Properties. The **System Properties** Dialog Box will be displayed.
- Click the **Hardware** Tab and click the **Device Manager** Button. The **Device Manager** Dialog Box will be displayed.
- Double-click the USB (Universal Serial Bus) Controller Device.
- Check that OMRON SYSMAC PLC Device is displayed. If it appears, then the USB driver has been installed correctly.



Close the **Device Manager** Dialog Box and **System Properties** Dialog Box. If OMRON SYSMAC PLC Device does not appear, reinstall the USB driver.

## Uninstalling the USB Driver

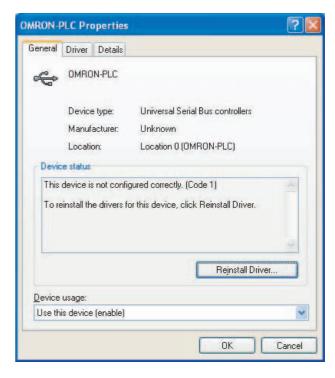
If the USB driver installation fails for some reason or is cancelled in progress, the USB driver must be reinstalled.

First, check whether installation failed.

- Display the Device Manager on the computer. If **USB Device** is displayed for **Other Devices**, it means that the USB driver installation has failed.
- Right-click on *USB Device* and select *Delete* to delete the driver. Reinsert the USB cable to display the USB driver installation dialog box. Install the driver following the instructions again.

## Re-installing the USB Driver

**1** Right-click *OMRON-PLC* under *Universal Serial Bus controllers* and select *Properties*. The properties will be displayed.



**2** Click the **Reinstall Driver** Button. The Hardware Update Wizard Dialog Box will be displayed. Install the driver software using the procedure described in *4-2-2 Installing the USB Driver* 





# **Installation and Wiring**

This section describes how to install and wire CP1E Units.

5-1	Fail-saf	e Circuits	5-2
5-2	Installa	tion	5-3
	5-2-1	Installation Location	5-3
	5-2-2	Unit Arrangement	5-6
	5-2-3	Installation	5-7
	5-2-4	Connecting Expansion I/O Units and Expansion Units	5-12
5-3	Wiring	5	5-14
	5-3-1	Wiring Procedure	5-14
	5-3-2	Wiring Power Supply and Ground Lines	5-14
	5-3-3	I/O Wiring	5-17
	5-3-4	Wiring Safety and Noise Controls	5-21
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#### **Fail-safe Circuits** 5-1

This section describes the fail-safe circuits that must be set up outside the CP1E.

Always set up safety circuits outside of the PLC to prevent dangerous conditions in the event of errors in the CP1E CPU Unit or external power supply.

In particular, be careful of the following points.

## Timing of Supplying Power to the PLC and the Controlled System

If the PLC's power supply is turned ON after the controlled system's power supply, outputs in Units such as DC Output Units may momentarily not function properly.

To prevent any malfunction, add an external circuit that prevents the power supply to the controlled system from going ON before the power supply to the PLC itself.

## Safety Circuit for Errors (Outputs Turned OFF)

When any of the following errors occur, PLC operation (program execution) will stop and all outputs from the Units will be turned OFF.

- A CPU error (watchdog timer error) or CPU on standby
- · A fatal error (memory error, I/O bus error, too many I/O points error, program error, cycle time too long error, or FALS error)

Be sure to add any circuits necessary outside of the PLC to ensure the safety of the system in the event of an error that stops PLC operation.

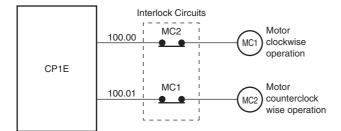
## Safety Circuit after a Malfunction (When an Output Remains ON)

It is possible for an output to remain ON due to a malfunction in the internal circuitry of the Output Unit, such as a relay or transistor malfunction. Always add any circuits necessary outside of the PLC to ensure the safety of the system in the event that an output fails to go OFF.

## **External Interlock Circuits**

When the PLC controls operation such as the clockwise and counterclockwise operation of a motor and if there is any possibility of an accident or mechanical damage due to faulty PLC operation, provide an external interlock such as the one shown below to prevent both the forward and reverse outputs from turning ON at the same time.

#### Example:



A circuit like the one shown in the diagram on the left is required to prevent outputs MC1 and MC2 from both being ON at the same time even if both PLC outputs CIO 100.00 and CIO 100.01 are both ON.

## 5-2 Installation

This section describes the environmental factors that must be considered and the installation location of each Unit.

#### 5-2-1 Installation Location

## **Installation Environment**

Do not install the Unit in the following locations.

- Locations subject to ambient temperatures lower than 0°C or higher than 55°C.
- Locations subject to drastic temperature changes or condensation.
- Locations subject to ambient humidity lower than 10% or higher than 90%.
- · Locations subject to corrosive or flammable gases.
- · Locations subject to excessive dust, salt, or metal filings.
- · Locations that would subject the PLC to direct shock or vibration.
- · Locations exposed to direct sunlight.
- · Locations that would subject the PLC to water, oil, or chemical reagents.

Always enclose or protect the PLC sufficiently in the following locations.

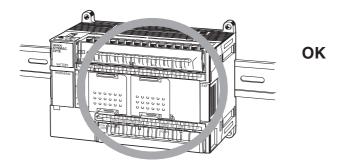
- Locations subject to static electricity or other forms of noise.
- · Locations subject to strong electromagnetic fields.
- Locations subject to possible exposure to radioactivity.
- · Locations close to power lines.

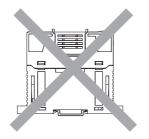
## **Installation in Cabinets or Control Panels**

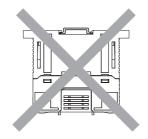
When the CP1E is being installed in a cabinet or control panel, be sure to provide proper ambient conditions as well as access for operation and maintenance.

#### Installation Orientation

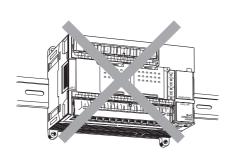
When installing the CP1E in a control panel, it must be installed with the side with indicators and communications ports facing the front to ensure proper heat dissipation.

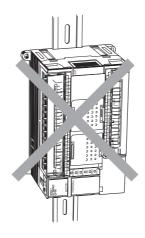






## Not possible





#### Accessibility for Operation and Maintenance

- To ensure safe access for operation and maintenance, separate the PLC as much as possible from high-voltage equipment and moving machinery.
- The PLC will be easiest to install and operate if it is mounted at a height of 1.0 to 1.6 m above the floor.

# **WARNING**

Do not touch the power supply or the area around the I/O terminals while power is being supplied or immediately after power has been turned OFF. Doing so may result in burns.





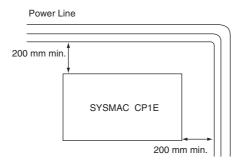
#### **Precautions for Correct Use**

After the power supply has been turned OFF, wait until the PLC has sufficiently cooled before touching it.

#### • Improving Noise Resistance

Leave space between the CP1E and control panel or other devices to allow adequate dissipation of heat generated by the power supply.

- Do not mount the PLC in a control panel containing high-voltage equipment.
- Install the PLC at least 200 mm (6.5 feet) from power lines.

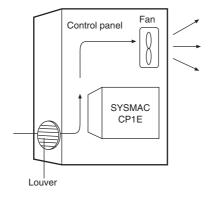


• Ground the mounting plate between the PLC and the mounting surface.

#### Temperature Control

The ambient operating temperature around the CP1E must be between 0 and 55°C. Observe the following precautions.

- Provide enough space for good air flow.
- Do not install the PLC above equipment that generates a large amount of heat such as heaters, transformers, or high-capacity resistors.
- If the ambient temperature exceeds 55°C, install a cooling fan or air conditioner.



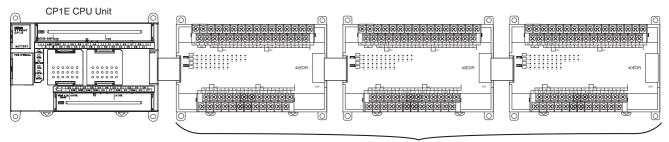
#### 5-2-2 **Unit Arrangement**

This section describes how to arrange the CP1E Units.

As shown in the following diagrams, Units can be arranged in one or two rows when Expansion I/O Units or Expansion Units are used.

## Arrangement in One Row

Expansion I/O Units and Expansion Units can be installed in a side-by-side arrangement.



CP-series Expansion Units and Expansion I/O Units



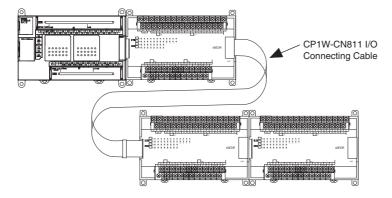
#### **Precautions for Correct Use**

When connecting CP-series Expansion Units or Expansion I/O Units to a CPU Unit with AC power, provide a space of approximately 10 mm between the CPU Unit and the first Expansion Unit or Expansion I/O Unit.

If sufficient space cannot be provided between the CPU Unit and the first Expansion Unit or Expansion I/O Unit, use the PLC in an ambient temperature of 0 to 50°C.

## **Arrangement in Two Rows**

The Units can be arranged in two rows using the CP1W-CN811 I/O Connecting Cable (800 mm).





#### **Precautions for Correct Use**

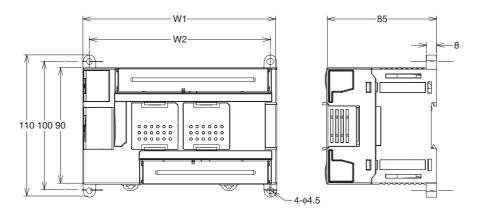
I/O Connecting Cable can be used in one place only in each CP1E PLC. It cannot be used in more than one place in the same CP1E PLC.

#### 5-2-3 Installation

This section describes how to install the CP1E.

## **Dimensions and Installation Height**

#### Dimensions



Model number	W1	W2
CP1E-□20D□-□	86	76
CP1E-□30D□-□	130	120
CP1E-□40D□-□	150	140

#### Installation Height

The installation height is approximately 90 mm.

When a cable is connected to an Option Board, however, the additional height must be included. Always allow for the additional height when considering the depth of the control panel in which the PLC is to be mounted.

## **Installation Methods**

There are two installation methods.

#### DIN Track Installation

- Units can be mounted to PEP-50N (50 cm) or PEP-100N/100N2 (100 cm) DIN Tracks.
- Units can be moved and removed easily.
- The installation height in the control panel will be increased depending on the type of DIN tracks used.

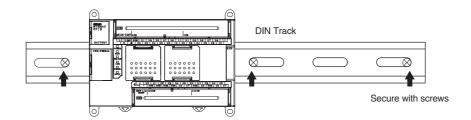
#### Surface Installation

Units can be directly mounted in the control panel using M4 screws.

## Installation Example

#### DIN Track Installation

Secure the DIN Track with screws in at least three places.

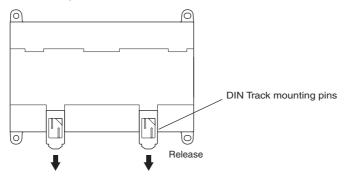


#### Surface Installation

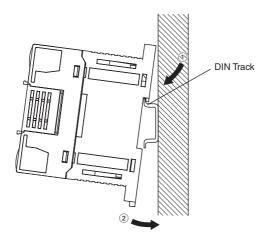
A CP1E CPU Unit and CP-series Expansion I/O Units and Expansion Units can be mounted using M4 screws. For restrictions on the number of Expansion I/O Units and Expansion Units that can be connected, refer to 2-3 Expansion I/O Unit or Expansion Unit.

## **DIN Track Installation**

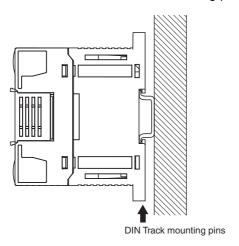
1 Use a screwdriver to pull down the DIN Track mounting pins from the back of the Units to release them, and mount the Units to the DIN Track.



Fit the back of the Units onto the DIN Track by catching (1) the top of the Units on the Track and then pressing (2) in at the bottom of the Units, as shown below.



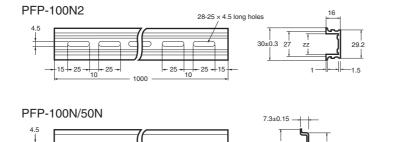
**3** Press in all of the DIN Track mounting pins to securely lock the Units in place.



## **Mounting Brackets**

#### DIN Track

Secure the DIN Track to the control panel using M4 screws at interval of 210 mm or less (6 holes or fewer). The tightening torque is  $1.2 \text{ N} \cdot \text{m}$ .



#### End Plate

Use the PFP-M End Plates to secure the Units so that they do not move towards one end or the other of the DIN Track.

\*PFP-50N dimensions are given in parentheses



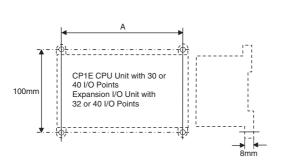
## **Surface Installation**

#### Surface Installation

- Create the mounting holes in the mounting surface as shown in the dimensions diagrams.
- Align the CP1E CPU Unit with the mounting holes and secure it in place with M4 screws.

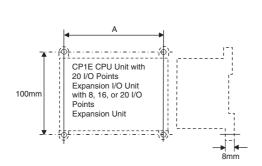
## Surface Installation Mounting Hole Pitch

• CP1E CPU Units with 30 or 40 I/O Points or Expansion I/O Units with 32 or 40 I/O Points



Unit		Mounting hole pitch A (mm)
CP1E CPU Unit	Unit with 30 I/O points	120±0.5
	Unit with 40 I/O points	140±0.5
Expansion I/O Units	Unit with 32 I/O points	140±0.2
	Unit with 40 I/O points	140±0.2

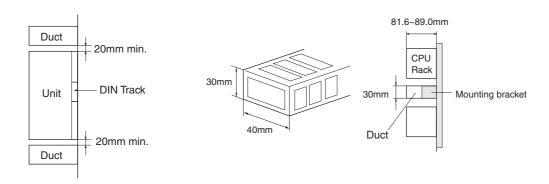
• CP1E CPU Units with 20 I/O Points, Expansion I/O Units with 8, 16, or 20 I/O Points, and Expansion Units



Unit		Mounting hole pitch A (mm)
CP1E CPU Unit	Unit with 20 I/O points	76±0.5
Expansion I/O Units	Unit with 8 input points	56±0.2
	Unit with 8 output points	56±0.2
	Unit with 16 output points	76±0.2
	Unit with 20 I/O points	76±0.2
Analog I/O Units	Analog I/O	76±0.2
	Analog input	
	Analog output	
Temperature Sensor Units		76±0.2

## **Using Wiring Ducts**

Whenever possible, route I/O wiring through wiring ducts. Install the ducts so that it is easy to wire the I/O Units through the ducts. It is handy to have the ducts at the same height as the Racks. Use mounting bases if necessary to adjust the heights.





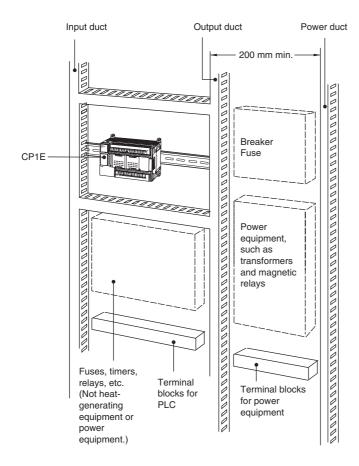
#### **Precautions for Correct Use**

Tighten terminal block screws and cable screws to the following torques.

M4: 1.2 N·m M3: 0.5 N·m

## Routing Wiring Ducts

Install the wiring ducts at least 20 mm between the tops of the Racks and any other objects, (e.g., ceiling, wiring ducts, structural supports, devices, etc.) to provide enough space for air circulation and replacement of Units.

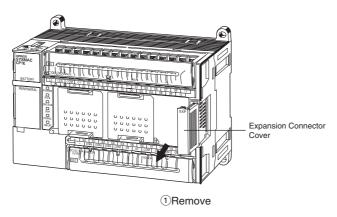


#### Connecting Expansion I/O Units and Expansion Units 5-2-4

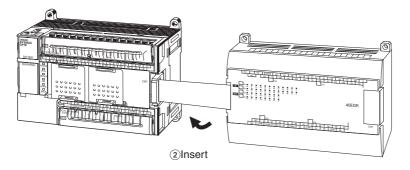
This section describes how to connect Expansion I/O Units and Expansion Units.

# **Connection Methods**

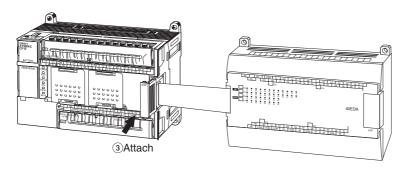
Remove the cover from the CPU Unit's or the Expansion I/O Unit's expansion connector. Use a flat-head screwdriver to remove the cover from the Expansion I/O Connector.



Insert the Expansion I/O Unit's connecting cable into the CPU Unit's or the Expansion I/O Unit's expansion connector.



Attach the cover to the CPU Unit's or the Expansion I/O Unit's expansion connector.



# **Precautions on Connecting Units**

The following restrictions apply to the CP-series Expansion Units and Expansion I/O Units that can be connected to CP1E CPU Units.

#### Maximum Number of Connectable Units

With a CPU Unit with 30 or 40 I/O Points, a total of up to three Expansion I/O Units and Expansion Units can be connected to one CPU Unit. It is not possible to connect to Expansion I/O Units and Expansion Units to a CPU Unit with 20 I/O Points.

#### Wiring **5-3**

This section describes wiring methods for the CPU Unit.

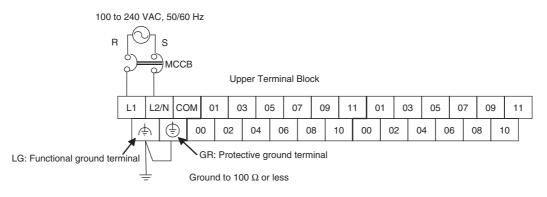
#### **Wiring Procedure** 5-3-1

Make sure that the power supply is OFF before beginning wiring.

Prepare the parts required for wiring.	Prepare crimp terminals and cables for wiring.	-
<b>+</b>		
2. Connect the power supply terminals.	Connect power supply to power supply terminals L1 and L2/N.	Refer to 5-3-2 Wiring Power Supply and Ground Lines.
•		
3. Ground the ground terminal( $\stackrel{\leftarrow}{=}$ ).	Ground to 100 $\Omega$ or less.	Refer to 5-3-2 Wiring Power Supply and Ground Lines.
<b>+</b>		
4. Connect the input terminals.	Connect sensors and switches to the terminals.	Refer to 5-3-3 I/O Wiring.
<b>\</b>		
5. Connect the output terminals.	Connect loads to the terminals.	Refer to 5-3-3 I/O Wiring.

#### Wiring Power Supply and Ground Lines 5-3-2

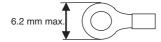
# Wiring AC Power Supply and Ground



- · Wire a separate circuit for the power supply circuit so that there is no voltage drop from the inrush current or startup current that flows when other equipment is turned ON.
- · When several CP1E PLCs are being used, it is recommended to wire the PLCs on separate circuits to prevent a voltage drop from the inrush current or incorrect operation of the circuit breaker.

### AC Power Supply Wiring

- Use twisted-pair power supply cables to prevent noise from the power supply lines. Adding a 1:1 isolating transformer reduces electrical noise even further.
- Consider the possibility of voltage drops and the allowable current, and always use thick power lines.
- · Use round crimp terminals for AC power supply wiring.



Use a power supply within the allowable voltage fluctuation range (85 to 264 VAC).

## Grounding

- Always ground the ground terminal to 100  $\Omega$  or less to protect against electric shock and incorrect operation from electrical noise.
- If one phase of the power supply is grounded, connect the grounded phase to the L2/N terminal.
- The GR terminal is a ground terminal. To prevent electrical shock, use a dedicated ground line (2 mm<sup>2</sup> min.) of 100  $\Omega$  or less.
- The line ground terminal (LG) is a noise-filtered neutral terminal. If noise is a significant source of errors or if electrical shocks are a problem, connect the line ground terminal (LG) to the ground terminal (GR) and ground both with a ground resistance of 100  $\Omega$  or less.
- To prevent electrical shock when short-circuiting between the LG and GR terminals, always use a ground of 100  $\Omega$  or less.
- Do not connect ground lines to other devices or to the frame of a building. Doing so will reverse the effectiveness of the ground and instead have a bad influence.

#### Isolation Transformer

The PLC's internal noise isolation circuits are sufficient to control typical noise in power supply lines. Ground noise can be further reduced by providing the power supply through a 1:1 isolating transformer. Do not ground the secondary coil of the transformer.



Tighten the AC power supply terminal screws to a torque of 0.5 N·m.

Loose screws may result in fire or malfunction.

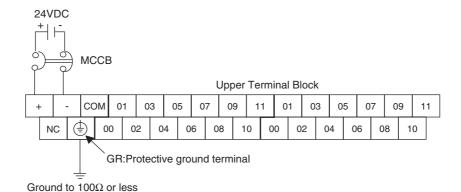




#### **Precautions for Correct Use**

- Loose pieces of wires may fall in the area when wiring. To prevent these pieces from entering
  into the Unit, leave the label on the top of the Unit while wiring.
- Remove the label after the completion of wiring to ensure proper heat dissipation.
- The power supply terminals are located at the top of the Unit. Do not connect a power supply
  to the 24-VDC external supply terminals on the bottom of the Unit. Internal circuits may be
  damaged if power is supplied to these terminals.

# Wiring DC Power Supply and Ground



- Wire a separate circuit for the power supply circuit so that there is no voltage drop from the inrush current or startup current that flows when other equipment is turned ON.
- When several CP1E PLCs are being used, it is recommended to wire the PLCs on separate circuits to prevent a voltage drop from the inrush current or incorrect operation of the circuit breaker.

# DC Power Supply Wiring

· Use crimp terminals or solid wire for power supply wiring. Do not connect bare stranded wires directly to terminals.



- M3 self-rising terminal screws are used. Tighten the terminal block screws to the torque of 0.5 N⋅m.
- Use a power supply within the allowable voltage fluctuation range (20.4 to 26.4 VDC).
- The maximum power consumption is 34 W for CPU Units with 30 or 40 I/O points, 13 W for CPU Units with 20 I/O points.
- There will be a inrush current of about five times that level when the power is turned ON.

#### Grounding

- Always ground the ground terminal to 100Ω or less to protect against electric shock and incorrect operation from electrical noise.
- The GR terminal is a ground terminal. To prevent electrical shock, use a dedicated ground line  $(2mm^2 min.)$  of  $100\Omega$  or less.
- Do not connect ground lines to other devices or to the frame of a building. Doing so will reverse the effectiveness of the ground and instead have a bad influence.



#### **Precautions for Safe Use**

- Be sure not to reverse the positive and negative leads when wiring the power supply terminals.
- Supply power to all of the Power Supply Units from the same source.
- Use reinforced insulation or double insulation for the DC power supplies connected to DC Power Supply Units to comply with EC(Low Voltage Directive) Directives.



#### **Precautions for Correct Use**

- Loose pieces of wires may fall in the area when wiring. To prevent these pieces from entering into the Unit, leave the label on the top of the Unit while wiring.
- Remove the label after the completion of wiring to ensure proper heat dissipation.
- The power supply terminals are located at the top of the Unit.

# 5-3-3 **I/O Wiring**

# I/O Wiring



#### **Precautions for Safe Use**

- Never apply a voltage that exceeds the input voltage for Input Units or the maximum switching capacity for Output Units.
- When the power supply has positive and negative terminals, always wire them correctly.
- Do not bend the I/O Connecting cable past its natural bending radius or pull in it with excessive force. Doing so will damage the cable.

#### Wire Sizes

- AWG22 to AWG18 (0.32 to 0.82 mm<sup>2</sup>) power lines are recommended.
- The current capacity of electric wire depends on factors such as the ambient temperature and insulation thickness, as well as the gauge of the wire.

## Crimp Terminals

- M3 self-rising terminal screws are used.
- Use crimp terminals or solid wire for wiring.
- Do not connect bare stranded wires directly to terminals.
- Tighten the terminal block screws to the torque of 0.5 N·m.
- Use crimp terminals (M3) having the dimensions shown below.



#### Wiring

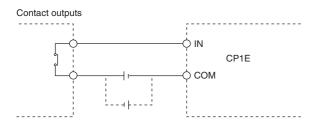
- Wire the Units so that they can be easily replaced.
- · Make sure that the I/O indicators are not covered by the wiring.
- Do not place the I/O wiring in the same conduits or ducts as high-voltage or power lines. Inductive noise can cause errors or damage.
- Tighten the terminal screws to the torque of 0.5 N·m.

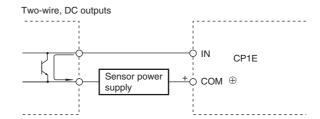
# **Example of Input Device Connections**

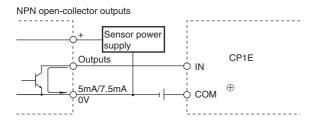
Use the following information for reference when selecting or connecting input devices.

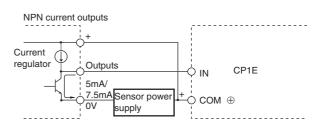
## DC Input Units

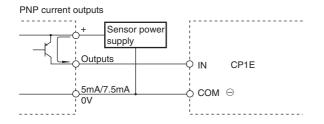
Connectable DC Input Devices (for DC Output Models)

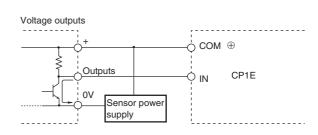




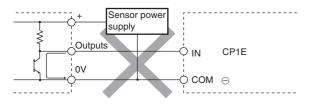








The circuit below should NOT be used for I/O devices having a voltage output.



# **Precautions When Connecting a Two-wire DC Sensor**

When using a two-wire sensor with a 24-VDC input device, check that the following conditions have been met. Failure to meet these conditions may result in operating errors.

#### (1) Relation between voltage when the PLC is ON and the sensor residual voltage:

 $V_{\text{ON}} \leq V_{\text{CC}} - V_{\text{R}}$ 

# (2) Relation between current when the PLC is ON and sensor control output (load current):

Ioυτ(min)≤Ioν≤Ioυτ(max)

Ion=(Vcc-VR-1.5[PLC internal residual voltage]\*)/R<sub>IN</sub>

When IoN is smaller than IOUT (min), connect a bleeder resistor R.

The bleeder resistor constant can be calculated as follows:

 $R \le (V_{CC} - V_R)/(I_{OUT}(min) - I_{ON})$ 

Power W $\geq$ (Vcc  $-V_R$ ) $^2/R \times 4$ (allowable margin)

#### (3) Relation between current when the PLC is OFF and sensor leakage current:

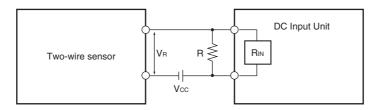
Ioff≥I<sub>leak</sub>

Connect a bleeder resistor if Ileak is greater than IOFF.

Use the following equation to calculate the bleeder resistance constant.

 $R \le R_{IN} \times V_{OFF} / (I_{leak} \times R_{IN} - V_{OFF})$ 

Power  $W \ge (V_{CC} - V_R)^2 / R \times 4$  (allowable margin)



Vcc: Power voltage

Vr: Sensor output residual current

Von: PLC ON voltage

lout: Sensor control current (load current)

Voff: PLC OFF voltage Ion: PLC ON current

Ileak: Sensor leakage current

Ioff: PLC OFF current
R: Bleeder resistance
Rin: PLC input impedance

#### (4) Precautions on Sensor Inrush Current

An incorrect input may occur due to sensor inrush current if a sensor is turned ON after the PLC has started up to the point where inputs are possible.

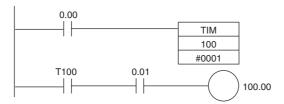
Determine the time required for sensor operation to stabilize after the sensor is turned ON and take appropriate measures, such as inserting into the program a timer delay after turning ON the sensor.

## Programming Example

In this example, the sensor's power supply voltage is used as the input to CIO 0.00.

A 100-ms timer delay (the time required for an OMRON Proximity Sensor to stabilize) is created in the program.

After the Completion Flag for the timer turns ON, the sensor input on input bit CIO 0.01 will cause output bit CIO 100.00 to turn ON.



# **Output Wiring**

# Protective Circuit for Load Short-circuits

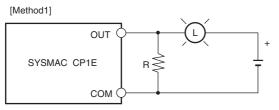
If a load connected to the output terminals is short-circuited, output components and the printed circuit boards may be damaged. To guard against this, incorporate a fuse in the external circuit. Use a fuse with a capacity of about twice the rated output.

# Connecting to a TTL Circuit

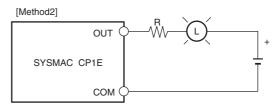
A TTL circuit cannot be connected directly to a transistor output because of the transistor's residual voltage. Connect a TTL Unit through a CMOS-IC. It is necessary to connect a pull-up resistor for a transistor output.

#### Precautions on Inrush Current

When connecting a transistor or triac output to a load having a high inrush current (such as an incandescent lamp), steps must be taken to avoid damage to the transistor or triac. Use either of the following methods to reduce the inrush current.



Providing a dark current of approx. one-third of the rated value through an incandescent lamp

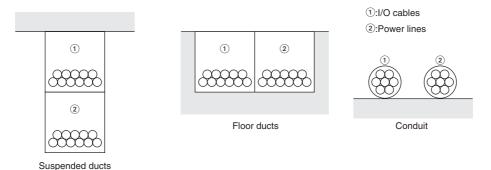


Installing a limiting resistor

# 5-3-4 Wiring Safety and Noise Controls

# I/O Signal Wiring

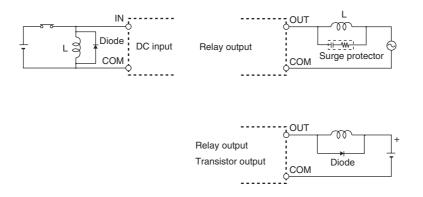
Whenever possible, place I/O signal lines and power lines in separate ducts or conduits both inside and outside of the control panel.



When wiring in the same duct, use shielded cables and connect the shields to the GR terminal to reduce noise.

# **Inductive Loads**

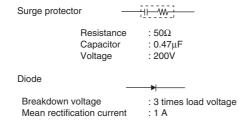
When an inductive load is connected to an I/O Unit, connect a surge protector or diode in parallel with the load as shown below.





#### **Precautions for Correct Use**

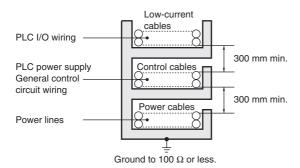
Use surge protectors and diodes with the following specifications.



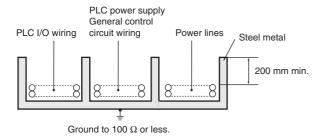
# **Reducing Electrical Noise for External Wiring**

Take the following points into account when externally wiring I/O, power supply, and power lines.

- When multi-conductor signal cable is being used, do not combine I/O wires and other control wires in the same cable.
- If wiring racks are parallel, allow at least 300 mm between them.



 If the I/O wiring and power cables must be placed in the same duct, they must be shielded from each other using grounded steel sheet metal.



#### 5-3-5 **Relay Output Noise Reduction Methods**

The CP1E PLCs conforms to the Common Emission Standards (EN61131-2) of the EMC Directives. However, noise generated by relay output switching may not satisfy these Standards.

In such a case, a surge protector must be connected to the load side or other appropriate countermeasures must be provided outside the PLC. Countermeasures taken to satisfy the standards vary depending on the devices on the load side, wiring, configuration of machines, etc.

Following are examples of countermeasures for reducing the generated noise.

#### Countermeasures (Refer to EN 61131-2 for details.)

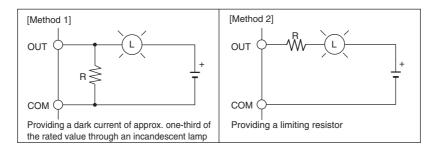
- Countermeasures are not required if the frequency of load switching for the whole system with the PLC included is less than 5 times per minute.
- · Countermeasures are required if the frequency of load switching for the whole system with the PLC included is more than 5 times per minute.

# • Countermeasure Examples

• When switching an inductive load, connect a surge protector, diodes, etc., in parallel with the load or contact as shown below.

Circuit	Cur	rent	Characteristic	Dequired element
Circuit	AC	DC	Cnaracteristic	Required element
CR method  Power C R  R  R  R  R  R  R  R  R  R  R  R  R	ОК	ОК	If the load is a relay or solenoid, there is a time lag between the moment the circuit is opened and the moment the load is reset.  If the supply voltage is 24 or 48 V, insert the arc killer in parallel with the load. If the supply voltage is 100 to 200V, insert the arc killer between the contacts.	The capacitance of the capacitor must be 1 to $0.5~\mu F$ per contact current of 1 A and resistance of the resistor must be $0.5$ to $1~\Omega$ per contact voltage of 1 V. These values, however, vary with the load and the characteristics of the relay. Decide these values from experiments, and take into consideration that the capacitance suppresses spark discharge when the contacts are separated and the resistance limits the current that flows into the load when the circuit is closed again. The dielectric strength of the capacitor must be 200 to 300 V. If the circuit is an AC circuit, use a capacitor with no polarity.
Diode method  Power  Power		ОК	The diode connected in parallel with the load changes energy accumulated by the coil into a current, which then flows into the coil so that the current will be converted into Joule heat by the resistance of the inductive load.  This time lag, between the moment the circuit is opened and the moment the load is reset, caused by this method is longer than that caused by the CR method.	The reversed dielectric strength value of the diode must be at least 10 times as large as the circuit voltage value. The forward current of the diode must be the same as or larger than the load current. The reversed dielectric strength value of the diode may be two to three times larger than the supply voltage if the surge protector is applied to electronic circuits with low circuit voltages.
Varistor method  Power  Power	OK	OK	The varistor method prevents the imposition of high voltage between the contacts by using the constant voltage characteristic of the varistor. There is time lag between the moment the circuit is opened and the moment the load is reset.  If the supply voltage is 24 or 48 V, insert the varistor in parallel with the load. If the supply voltage is 100 to 200 V, insert the varistor between the contacts.	_

• When switching a load with a high inrush current such as an incandescent lamp, suppress the inrush current as shown below.



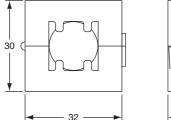
# Conditions for Meeting EMC Directives when Using CP-series Relay **Expansion I/O Units**

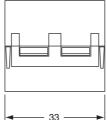
EN61131-2 immunity testing conditions when using the CP1W-40EDR, CP1W-32ER, or CP1W-16ER with a CP1W-CN811 I/O Connecting Cable are given below.

• Recommended Ferrite Core

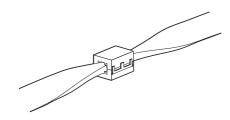
Ferrite Core (Data Line Filter): 0443-164151 manufactured by Nisshin Electric

Minimum impedance: 90  $\Omega$  at 25 MHz, 160  $\Omega$  at 100 MHz



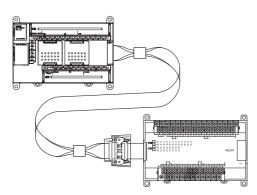


- Recommended Connection Method
- (1) Cable Connection Method



#### (2) Connection Method

As shown below, connect a ferrite core to each end of the CP1W-CN811 I/O Connecting Cable.





# **Troubleshooting**

This section describes how to troubleshoot problems that may occur with a CP1E PLC.

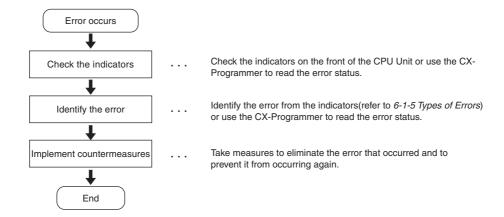
6-1	Trouble	eshooting CPU Unit Errors	6-2
	6-1-1	Errors and Remedies	6-2
	6-1-2	Checking Errors	6-2
	6-1-3	Checking Detailed Status	6-3
	6-1-4	Reading Error Log Information	6-3
	6-1-5	Types of Errors	6-5
	6-1-6	Error Processing Flowchart	6-6
	6-1-7	No Operation When Power Is Supplied	. 6-7
	6-1-8	Fatal Errors	. 6-7
	6-1-9	CPU Errors	6-11
	6-1-10	Non-fatal Errors	6-12
	6-1-11	Other Errors	6-14
6-2	Trouble	eshooting Unit Errors	6-15
	6-2-1	Inputs	
	6-2-2	Outputs	6-16
	6-2-3	CX-Programmer Connection	6-17

# **Troubleshooting CPU Unit Errors**

This section describes how to troubleshoot errors that occur in the CP1E CPU Units.

#### **Errors and Remedies** 6-1-1

Use the following procedure when an error occurs.

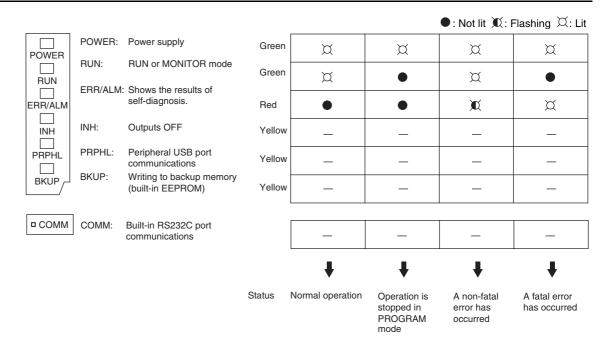


#### 6-1-2 **Checking Errors**

The type of error that occurred can be determined by checking the indicators on the front of the CPU Unit or by using the CX-Programmer.

Refer to 6-1-5 Types of Errors for details on the types of error status.

# **Checking the Indicators**



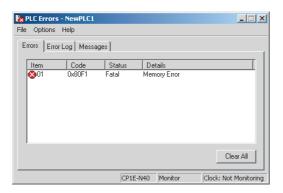
# **Checking Error Status with the CX-Programmer**

Use the following procedure to read the error status.

1 Place the CX-Programmer online with the CPU Unit.

**2** Double-click **Error Log** in the project tree in the main window.

The PLC Errors Window will be displayed. Click the **Errors** Tab. The current errors will be displayed on the Errors Tab Page.



# 6-1-3 Checking Detailed Status

You can check detailed error status using information registered in the Auxiliary Area.

The following error details are registered.

Area	Description			
Error flags	The Auxiliary Area contains flags that indicate the type of error.			
	Error information is provided for various types of error.			
Error information	The Auxiliary Area contains words that provide detailed information on current errors.			
	Error information is provided for various types of error.			
Error code	The Auxiliary Area contain a word that provides a code that describes the error that has occurred.			
	The error code is stored in A400 for all errors.			
	If two or more errors occur at the same time, the highest (most serious) error code will be stored in A400.			

# 6-1-4 Reading Error Log Information

If the error status could not be checked when the error occurred, it can be checked by reading error log

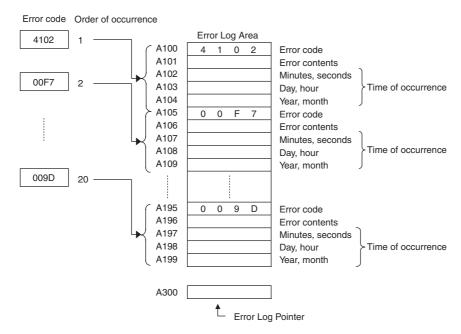
The following information is stored in the error log.

- Error code (This is the same error code as is stored in word A400.)
- · Error contents
- · Time of occurrence

# **Error Log Information**

A maximum of 20 error records will be stored in the error log.

If more than 20 errors occur, the oldest error record (in A100 to A104) will be deleted and the 19 records stored in A105 to A199 will be shifted by one, with the newest record being stored in A195 to A199.



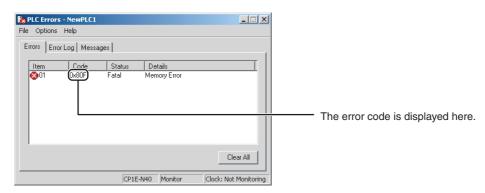
Note CP1E E-type CPU Units do not support the clock function, so the time of occurrence cannot be confirmed. The display is always 01-01-01 01:01:01 Sunday.

# **Checking Error Log Information**

The following methods can be used to check error log information with the CX-Programmer.

## CX-Programmer PLC Error Window

Check the error log by clicking the Error Log Tab in the PLC Errors Window of the CX-Programmer.



The example above shows that a memory error has occurred.

- Error code 80F1 → Memory error
- Error contents (A403) → 0400 → A403.10 is ON → Backup memory error

# • Directly Monitoring the Area where Error Log Information is Stored

**1** Connect the CX-Programmer online.

**2** Read words A100 to A199.

**3** Check the error status from the registered data.

# 6-1-5 Types of Errors

The type of error that has occurred can be identified by checking the indicators on the front of the CPU Unit, or by using the CX-Programmer to check the error status.

The errors detected by the CPU Unit are listed in the following table.

Refer to 6-2 Troubleshooting Unit Errors for errors not detected by the CPU Unit.

• Error code storage word: The error code is stored in A400 when an error occurs.

• Error flags: Flags that indicate the type of error are allocated in the Auxiliary Area.

• Error information: There are words in the Auxiliary Area that provide specific information

on the meaning of error flags and information on the error location and

error details.

●: Not lit X: Flashing X: Lit

											: NOT IIT X		ing ∠:Li
				EDD/				COM (built-in	Error	F	Erro informa		Opera-
	Error	POWER	RUN	ERR/ ALM	INH	PRPHL	BKUP	RS-232C communi- cations status)	code (in A400)	Error flag	Error	Word	tion status
Power	supply error	Not lit	Not lit	Not lit	Not lit	Not lit	-	Not lit	-	-	-	-	Opera- tion stops.
CPU e error)*	rror (WDT 1	¤ Lit	Not lit	¤ Lit	_	-	-	-	_	_	_	_	Opera- tion stops.
	eral USB port unications	¤ Lit	¤ Lit	Not lit	_	Not lit	-	-	_	_	_	_	Opera- tion con- tinues.
	RS-232C port unications	¤ Lit	¤ Lit	Not lit	_	-	-	Not lit	_	_	_	_	Opera- tion con- tinues.
Fatal errors *1*2	Memory error	¤ Lit	Not lit	¤ Lit	-	-	-	-	0x80F1	A401.15	Memory Error Location	A403	Opera- tion stops.
	I/O bus error								0x80CA	A401.14	Always 0x0A0A	A404	
	Too many I/O points error								0x80E1	A401.11	Always 0x4000	A407	
	Program error								0x80F0	A401.09	Program Error Details	A294 to A299	
	Cycle time exceeded error								0x809F	A401.08	-	-	
	FALS error								0xC101 to 0xC2FF	A401.06	_	_	

●: Not lit X: Flashing X: Lit

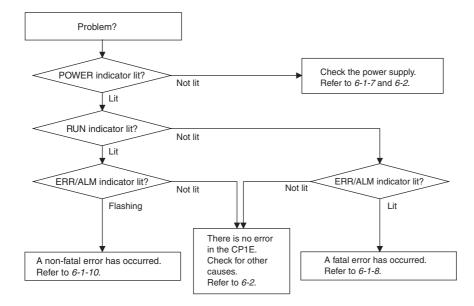
				EDD/				COM (built-in	Error	Funcu	Erro informa		Opera-
	Error	POWER	RUN	ERR/ ALM	INH	PRPHL	BKUP	RS-232C communi- cations status)	code (in A400)	Error flag	Error	Word	tion status
Non- fatal errors	FAL instruction executed	) Lit	X Lit	Flash- ing	-	-	-	-	0x4101 to 0x42FF	A402.15	Executed FAL Number	A360 to A391	Opera- tion con- tinues.
*2	Backup memory error								0x00F1	A315.15	-	_	
	PLC setup error								0x009B	A402.10	PLC Setup Error Location	A406	
	Option Board error								0x00D2	A315.13	Error Option Board Number	A424	
	Battery error								0x00F7	A402.04	_	-	

<sup>\*1</sup> The indicator status is the same for CPU errors and fatal errors, but they can be distinguished because a Programming Device can be connected when a fatal error occurs, but not when a CPU error occurs.

Note The indicator status shows the status of the errors that have occurred in RUN or MONITOR mode.

#### **Error Processing Flowchart** 6-1-6

Confirm the error category by referring to the status of the CPU Unit indicators, investigate the cause for the error in the error tables, and take corrective actions.



<sup>\*2</sup> Refer to 6-1-8 Fatal Errors and 6-1-10 Non-fatal Errors for details on fatal and non-fatal errors.

# 6-1-7 No Operation When Power Is Supplied

First confirm that the POWER indicator (green) is lit.

#### POWER Indicator Not Lit

The power supply may not match the Unit rating, wiring may not be correct, or the Unit may be faulty.

- Confirm the Unit rating (i.e., is it 24 VDC or 100 to 240 VAC?) and see if the supply power matches the rating.
- Check the wiring to see if it is correct and that nothing is disconnected.
- Check the voltage at the power supply terminals. If the voltage is normal and the POWER indicator is not lit, the Unit may be faulty. In that case, replace the Unit.

### POWER Indicator Flashing

There may be fluctuations in the power supply voltage, disconnected wiring, or poor contacts. Check the power supply system and wiring.

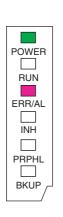
# POWER Indicator Lit but No Operation

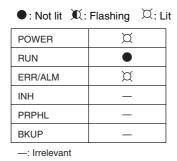
Check the RUN indicator if the POWER indicator is lit but the CPU Unit does not operate.

The CPU Unit may be on standby if the RUN indicator is not lit.

#### 6-1-8 Fatal Errors

#### CPU Unit Indicators





There may be a CPU error or a fatal error if operation stops (i.e., the RUN indicator turns OFF) and the ERR/ALM indicator lights.

Data on fatal errors is displayed on the Errors Tab Page of the CX-Programmer's PLC Errors Window.

Take corrective actions after checking error details based on the CX-Programmer display message together with the Auxiliary Area Error Flags and error information.

- · Errors are listed in order with the most serious errors first.
  - If two or more errors occur at the same time, the most serious error code will be stored in A400.
  - If the IOM Hold Bit hasn't been turned ON to protect I/O memory, all non-retained areas of I/O memory will be cleared when a fatal error other than FALS occurs.
  - I/O memory will be held when the I/O Memory Hold Bit is ON, but outputs will be turned OFF.

# **Memory Errors**

		Cause	Remedy
On err	error has occurred in e or more bits in A40 or has occurred.  The below for details.	n memory. 03 will turn ON to indicate where the	See below.
	Memory Error Loc	cation	
	A403.00 is ON	A checksum error has occurred in the ladder program. The power supply was turned OFF when backing up the user program to backup memory.	Transfer the ladder program again.
	A403.04 is ON	A checksum error has occurred in the PLC Setup.	Transfer the PLC Setup again.

#### Reference

Error flag	Memory Error Flag, A401.15
Error code (A400)	80F1
Error information	Memory Error Location, A403

# I/O Bus Error

An I/O bus error has occurred in data transfer between the CPU Units and Units connected to the I/O

Cycle the power supply. If operation is not restored when the power supply has been cycled, turn OFF the power supply and check that connections are proper and that there is no damage.

Cause	Remedy
An error occurred in data transfer between the CPU Unit and an Expansion Unit or Expansion I/O Unit.  (A value of 0A0A hex will be stored in A404.)	<ul> <li>Cycle the power supply.</li> <li>If the problem persists, turn OFF the power supply and check the Connecting Cables between the Units to see if they are connected properly.</li> <li>Check the Unit connections to be sure they are ok (e.g., that there is no damage).</li> <li>After correcting the problem, turn ON the power to the Units again.</li> </ul>

# Reference

Error flag	I/O Bus Error Flag, A401.14
Error code (A400)	80CA
Error information	I/O Bus Error Details, A404

# **Too Many I/O Points Error**

The number of CP-series Expansion Units and Expansion I/O Units connected exceeds the restriction for the number of Units or words for the system configuration.

Turn OFF the power supply and reconfigure the system within the restrictions.

Cause	Remedy
The number of CP-series Expansion Units and	Connect a maximum of three Expansion Units or Expan-
Expansion I/O Units exceeds the restriction.	sion I/O Units to a CPU Unit with 30 or 40 I/O points.
(A value of 4000 hex will be stored in A407.)	

## • Reference

Error flag	Too Many I/O Points Flag, A401.11
Error code (A400)	80E1
Error information	Too Many I/O Points Details, A407

# **Program Errors**

A program error indicates a problem with the user program. Refer to the error information, check the program, and correct the mistakes.

Clear the error once the problem has been corrected.

Cause	Remedy
Instruction Processing Error (A295.08 turns ON) The instruction could not be executed because of incorrect operand data, and the ER Flag was turned ON. (Only when the Stop CPU on Instruction Error parameter in the PLC Setup is set to Stop.)	<ul> <li>Refer to A298 and A299 (instruction program address when the program fails), check the specifications for the relevant instruction, and set the correct operand data.</li> <li>Set the PLC Setup to not stop operation for an instruction error.</li> </ul>
Indirect DM Addressing BCD Error (A295.09 turns ON)  The operand of indirect DM Area addressing in BCD Mode did not contain a BCD value when the instruction was executed, and the AER Flag was turned ON. (Only when the Stop CPU on Instruction Error parameter in the PLC Setup is set to Stop.)	<ul> <li>Refer to A298 and A299 (instruction program address when the program fails), and correctly set the content for the indirectly addressed DM operand (BCD mode) to BCD or change the specified destination. Alternatively, change the indirect addressing to binary mode.</li> <li>Set the PLC Setup to not stop operation for an instruction error.</li> </ul>
Illegal Area Access Error (A295.10 turns ON)  The AER flag is ON because an illegal area was specified for access when executing the instruction. (Only when the Stop CPU on Instruction Error parameter in the PLC Setup is set to Stop.)  The following operations are considered illegal access:  Reading/writing the parameter area  Writing to an area without memory installed  Writing to a write-protected area  Indirect DM addressing BCD error	<ul> <li>Refer to A298 and A299 (instruction program address when the program fails) and take corrective actions so that illegal area access errors will not occur.</li> <li>Set the PLC Setup to not stop operation for an instruction error.</li> </ul>
No END Error (A295.11 turns ON) This error occurs when there is not an END instruction in the program.	Insert an END instruction at the end of the program allocated to the task stored in A294 (task number when the program fails).
Task Error (A295.12 turns ON) There is no specified interrupt task when an interrupt is generated (input interrupt, high-speed counter interrupt or scheduled interrupt.)	Create a task for the number stored in A294 (task number when the program fails).
Differentiation Overflow Error (A295.13 turns ON)  Differentiation instructions were repeatedly inserted or deleted using the online editor and the system restriction was exceeded.	Change the operating mode to PROGRAM mode and then return to MONITOR mode.
Illegal Instruction Errors (A295.14 turns ON)	Transfer the program again using the CX-Programmer.
Execution of an unexecutable instruction was attempted.	
UM Overflow Error (A295.15 turns ON)	Transfer the program again using the CX-Programmer.
An attempt was made to execute a program that exceeds the user program capacity.	

## • Reference

Error flag	Program Error Flag, A401.09	
Error code (A400)	80F0	
Error information	Program Error Details, A294 to A299	

# Cycle Time Exceeded Error

Cause	Remedy
This error occurs when the cycle time PV exceeds the maximum cycle time set in the PLC Setup.	<ul> <li>Change the program to reduce the cycle time.</li> <li>Change the maximum cycle time setting.</li> <li>Refer to the Maximum Interrupt Task Processing Time (A440) and study the maximum cycle time.</li> <li>For example, use the JUMP instruction to skip sections that are not executed to shorten the cycle time.</li> </ul>

## • Reference

Error flag	Cycle Time Too Long Error, A401.08
Error code (A400)	809F
Error information	_

# **Errors Created with FALS Instructions**

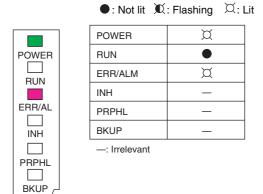
Cause	Remedy
FALS instruction executed (fatal error) in the program.	C100 hex will be added to the FALS number (001 to 1FF hex) and the result will be stored in A400 as the error code (C100 to C2FF hex).
	Check the conditions for executing FALS instructions and remove any causes for the user-defined error.

#### Reference

Error flag	FALS Error Flag, A401.06
Error code (A400)	C101 to C2FF
Error information	-

# 6-1-9 CPU Errors

#### CPU Unit Indicators



A CPU error or fatal error may have occurred if the ERR/ALM indicator lights during operation (RUN mode or MONITOR mode), the RUN indicator turns OFF, and operation stops.

# **CPU Unit Errors**

Cause	Remedy
A WDT (watchdog) error occurred in the CPU Unit. (This does not occur in normal use.)	Cycle the power supply.  The Unit may be faulty. Consult your OMRON representative.

### Reference

Error flag	_
Error code (A400)	ı
Error information	_

**Note** Just as when a CPU error occurs, the RUN indicator will turn OFF and the ERR/ALM indicator will light when a fatal error occurs. Connecting the CX-Programmer, however, is possible for fatal errors but not for CPU errors.

If the CX-Programmer cannot be connected (online), a CPU error has probably occurred.

# 6-1-10 Non-fatal Errors

A non-fatal error has occurred if both the RUN indicator is lit and the ERR/ALM indicator is flashing during operation (i.e., in RUN or MONITOR mode).

#### CPU Unit Indicators



●: Not lit X: Flashing X: L	
POWER	¤
RUN	¤
ERR/ALM	M
INH	_
PRPHL	_
BKUP	_
—: Irrelevant	

Information on the non-fatal errors can be obtained from the Errors Tab Page of the CX-Programmer's PLC Errors Window.

Take corrective actions after checking error details using the display messages and the Auxiliary Area Error Flags and error information.

- · Errors are listed in order with the most serious errors first.
- If two or more errors occur at the same time, the most serious error code will be stored in A400.

# Errors Created with FAL Instructions

Cause	Remedy
A FAL instruction was executed in the program to create a non-fatal error.	Check the conditions for executing FAL instructions and remove any causes of the user-defined error.
(The executed FAL number 001 to 511 will be stored in A360 to A391. The number 4 will be added to the front of 101 to 2FF (which correspond to executed FAL numbers 001 to 511) and the result will be stored in A400 as error code 4101 to 42FF.)	

#### Reference

Error flag	FAL Error Flag, A402.15
Error code (A400)	4101 to 42FF
Error information	-

# **Backup Memory Error**

Cause	Remedy
Writing to the backup memory (built-in EEPROM) fails.	Replace the CPU Unit when the backup memory (built-in EEPROM) has been written to more than 100,000 times.
(A315.15 will turn ON. )	

## • Reference

Error flag	Backup Memory Error Flag, A315.15
Error code (A400)	00F1
Error information	_

# **PLC Setup Errors**

Cause	Remedy
A set value error occurred in the PLC Setup.	Correct the PLC Setup with correct values.

## • Reference

Error flag	PLC Setup Error Flag, A402.10
Error code (A400)	009B
Error information	-

# **Option Board Errors**

Cause	Remedy
The Option Board is removed while the power is being supplied. (A315.13 will turn ON.)	Turn OFF the power supply and then install the Option Board again.

## Reference

Error flag	Option Board Error Flag, A315.13 Other Non-fatal Error Flag, A402.00	
Error code (A400)	00D1	
Error information	-	

# **Battery Errors**

Cause	Remedy
If the PLC Setup is set to detect battery errors, this error will occur when there is an error in the battery in the CPU Unit (i.e., the voltage is low or a battery is not mounted).	Check the battery connections.  Select the <i>Do not detect battery error</i> Check Box in the PLC Setup setting if battery-free operation is being used.

## Reference

Error flag	Battery Error Flag, A402.04	
Error code (A400)	00F7	
Error information	-	

# 6-1-11 Other Errors

# **Communications Errors**

# • CPU Unit Indicators





POWER	¤
RUN	¤
ERR/ALM	
INH	_
PRPHL	•
BKUP	_

Cause	Remedy
An error has occurred in the communications between the peripheral USB port and connected device.	<ul><li>Check the cable wiring.</li><li>Check the USB cable and replace it if necessary.</li></ul>
An error has occurred in the communications between the serial port and connected device.	<ul> <li>Confirm that the serial port 1/2 settings in the PLC Setup are correct.</li> <li>Check the cable wiring.</li> <li>If a host computer is connected, check the serial port</li> </ul>
	settings and program in the host computer.

# **6-2 Troubleshooting Unit Errors**

This section describes how to troubleshoot errors that occur in devices other than the CP1E CPU Unit.

# 6-2-1 Inputs

No.	Symptom	Cause	Remedy
1	Not all inputs turn ON or indicators are not lit.	External power is not supplied for the input.	Supply power.
		2. Supply voltage is low.	Adjust supply voltage to within rated range.
		3. Terminal block screws are loose.	Tighten screws.
2	Not all inputs turn ON even though the indicator is lit.	Input circuit is faulty. (There is a short at the load or something else that caused an overcurrent to flow.)	Replace Unit.
3	Not all inputs turn OFF.	Input circuit is faulty.	Replace Unit.
4	Specific input bit does not	Input device is faulty.	Replace input devices.
	turn ON.	2. Input wiring disconnected.	Check input wiring
		3. Terminal block screws are loose.	Tighten screws.
		4. Too short ON time of external input.	Adjust input device.
		5. Input circuit is faulty.	Replace Unit.
		Input bit number is used for output instruction.	Correct the ladder program.
5	Specific input bit does not	Input circuit is faulty.	Replace Unit.
	turn OFF.	Input bit number is used for output instruction.	Correct the ladder program.
6	Input irregularly turns ON/OFF.	External input voltage is low or unstable.	Adjust external input voltage to within rated range.
		2. Malfunction due to noise.	Take protective measures against noise, such as:
			Install surge suppressor.
			Install insulation transformer.
			Install shielded cables between the Input Unit and the loads.
		3. Terminal block screws are loose.	Tighten screws.
7	Error occurs in units of 8	Common terminal screws are loose.	Tighten screws.
	points or 16 points, i.e., for the same common	2. Faulty data bus	Replace Unit.
	Tor the same common	3. Faulty CPU	Replace CPU Unit.
8	Input indicator is not lit in normal operation.	Faulty indicator or indicator circuit.	Replace Unit.

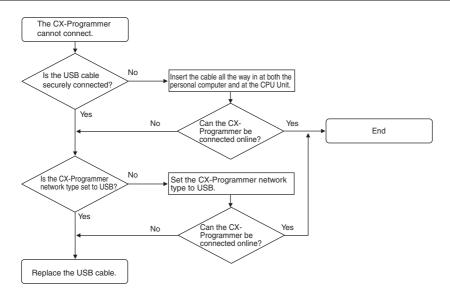
#### Outputs 6-2-2

No.	Symptom	Cause	Remedy
1	Not all outputs turn ON	Load is not supplied with power.	Supply power.
		2. Load voltage is low.	Adjust voltage to within rated range.
		3. Terminal block screws are loose.	Tighten screws.
		Unit failure caused by an overcurrent (possibly caused by a short at the load).	Replace Unit.
		5. Faulty I/O bus connector contact.	Replace Unit.
		6. Faulty output circuit.	Replace Unit.
		7. If the INH indicator is lit, the Output OFF Bit (A500.15) is ON.	Turn A500.15 OFF.
2	Not all outputs turn OFF	Output circuit is faulty.	Replace Unit.
3	Output of a specific bit number does not turn ON	Output ON time is too short because of a mistake in programming.	Correct program to increase the time that the output is ON.
	and indicator is not lit	Bit status controlled by multiple instructions in a ladder program.	Correct program so that each output bit is controlled by only one instruction.
		3. Faulty output circuit.	Replace Unit.
4	Output of a specific bit	Faulty output device.	Replace output device.
	number does not turn ON (indicator lit).	2. Break in output wiring.	Check output wiring.
	(mulcator iit).	Loose terminal block screws.	Tighten screws.
		4. Faulty output bit (relay output only).	Replace Unit.
		5. Faulty output circuit.	Replace Unit.
5	Output of a specific bit	Faulty output bit (relay output only).	Replace Unit.
	number does not turn OFF (indicator is not lit).	Bit does not turn OFF due to leakage current or residual voltage.	Replace external load or add dummy resistor.
6	number does not turn OFF	Bit status controlled by multiple instructions in ladder program.	Correct the ladder program.
	(indicator lit).	2. Faulty output circuit.	Replace Unit.
7	Output irregularly turns ON/OFF.	Low or unstable load voltage.	Adjust load voltage to within rated range.
		Bit status controlled by multiple instructions in ladder program.	Correct program so that each output bit is controlled by only one instruction.
		3. Malfunction due to noise.	Take protective measures against noise, such as:
			Install surge protector.
			<ul> <li>Install insulation transformer.</li> <li>Use shielded cables between the output terminal and the load.</li> </ul>
		4. Terminal block screws are loose.	Tighten screws.
8	Error occurs in units of 8 points or 16 points, i.e., for the same common.	Common terminal screws are loose.	Tighten screws.
		An overcurrent (possibly caused by a short at the load) resulted in a blown fuse for the output.	Replace Unit.
		3. Faulty data bus	Replace Unit.
		4. Faulty CPU	Replace CPU Unit.
9	Output indicator does not light during normal operation.	Faulty indicator.	Replace Unit.

# 6-2-3 CX-Programmer Connection

Use the following procedure if the CX-Programmer cannot connect to the PLC.

# **Connecting via the Peripheral USB Port**





# **Maintenance and Inspection**

This section describes periodic inspections, the service life of the Battery, and how to replace the Battery.

7-1	Periodi	ic Maintenance and Inspection	7-2
	7-1-1	Tools Required for Inspections	7-2
	7-1-2	Periodic Inspection	7-2
	7-1-3	Inspection and Maintenance	7-3
	7-1-4	Unit Replacement Precautions	7-4
7-2	Replac	ing the Battery in N-type CPU Units	7-5

#### **Periodic Maintenance and Inspection** 7-1

This section describes periodic inspections and maintenance of CP1E PLCs.

Daily or periodic inspections are required in order to maintain the PLC's functions in peak operating condition.

#### **Tools Required for Inspections** 7-1-1

# Required Tools

- · Phillips screwdrivers
- · Voltage tester or digital voltmeter
- · Industrial alcohol and clean cotton cloth

### Tools Required Occasionally

- Synchroscope
- Oscilloscope with pen plotter
- Thermometer and hygrometer (humidity meter)

#### 7-1-2 **Periodic Inspection**

Although the major components in CP-series PLCs have an extremely long life time, they can deteriorate under improper environmental conditions. Periodic inspections are thus required to ensure that the required conditions are being kept.

Inspection is recommended at least once every six months to a year, but more frequent inspections will be necessary in adverse environments.

Take immediate steps to correct the situation if any of the conditions in the following table are not met.

#### Battery

Item	Life	Remedy
Check whether the Battery has reached its service life (CP1W-BAT01 Battery).	Service life expectancy is 5 years at 25°C, less at higher temperatures.	Replace the Battery when its service life has passed even if a Battery error has not occurred. The service life depends on the model and ambient temperature.
	(From 1.5 to 5 years depending on model and ambient temperature.)	Refer to 7-2 Replacing the Battery in N-type CPU Units.

# 7-1-3 Inspection and Maintenance

No.	Inspection points	Inspection	Criteria	Remedy	
1	Power supply voltage	Check for voltage fluctuations at the power supply terminals.	Allowable voltage range AC power supply: 85 to 264 VAC DC power supply: 20.4 to 26.4 VDC	Use a voltage tester to check the power supply at the terminals. Take necessary steps to bring voltage fluctuations within limits.	
2	I/O power supply	Check for voltage fluctuations at the I/O terminals.	Voltages must be within I/O specifications for each Unit.	Use a voltage tester to check the power supply at the terminals. Take necessary steps to bring voltage fluctuations within limits.	
3	Ambient environment	Check the ambient temperature. (Inside the control panel if the PLC is in a control panel.)	0 to 55°C	Use a thermometer to check the temperature and make sure that the ambient temperature remains within the allowed range of 0 to 55°C.	
		Check the ambient humidity (inside the control panel if the PLC is in a control panel).	Relative humidity must be 10% to 90% with no con- densation.	Use a hygrometer to check the humidity and ensure that the ambient humidity remains between 10% and 90%.  Make sure that condensation does not occur due to rapid changes in	
				temperature.	
		Check that the PLC is not in direct sunlight.	Not in direct sun- light	Protect the PLC if necessary.	
		Check for accumulation of dirt, dust, salt, metal filings, etc.	No significant accumulation	Clean and protect the PLC if necessary.	
		Check for water, oil, or chemical spray.	No spray on the PLC	Clean and protect the PLC if necessary.	
		Check for corrosive or flam- mable gases in the area of the PLC.	No corrosive or flammable gases	Check by smell or use a sensor.	
		Check the level of vibration or shock.	Vibration and shock must be within specifications.	Install cushioning or shock absorbing equipment if necessary.	
		Check for noise sources near the PLC.	No significant noise sources	Either separate the PLC and noise source or protect the PLC.	
4	Installation and wiring	Check that the Option Boards and cable connectors are fully inserted and locked.	No looseness	Correct any improperly installed connectors.	
		Check for loose screws in external wiring.	No looseness	Tighten loose screws with a Phillips screwdriver.	
		Check crimp connectors in external wiring.	Adequate spacing between connectors	Check visually and adjust if necessary.	
		Check for damaged external wiring cables.	No damage	Check visually and replace cables if necessary.	

#### 7-1-4 **Unit Replacement Precautions**

Check the following when replacing any faulty Units discovered during inspections.

- Do not replace a Unit until the power is turned OFF.
- Check the new Unit to make sure that there are no errors.
- If a faulty Unit is being returned for repair, describe the problem in as much detail as possible, enclose this description with the Unit, and return the Unit to your OMRON representative.
- For poor contact, take a clean cotton cloth, soak the cloth in industrial alcohol, and carefully wipe the contacts clean. Be sure to remove any lint prior to remounting the Unit.



#### **Precautions for Correct Use**

When replacing a CPU Unit, be sure that not only the user program but also all other data required for operation is transferred to or set in the new CPU Unit before starting operation, including DM Area and HR Area settings.

If data area and other data are not correct for the user program, unexpected accidents may occur.

# 7-2 Replacing the Battery in N-type CPU Units

For CP1E N-type CPU Units, the data in the following areas may be unstable when the power is turned ON.

Mount the CP1W-BAT01 Battery (sold separately) to an N-type CPU Unit if data in the following areas need to be retained after a power interruption.

- DM Area (D) (excluding words backed up to the EEPROM using the DM backup function )
- Holding Area (H)
- Counter Present Values and Completion Flags (C)
- · Auxiliary Area related to clock function (A)

A Battery cannot be mounted to an E-type CPU Unit.

The procedure to replace the Battery on an N-type CPU Unit is given below.

# **Battery Service Life and Replacement Period**

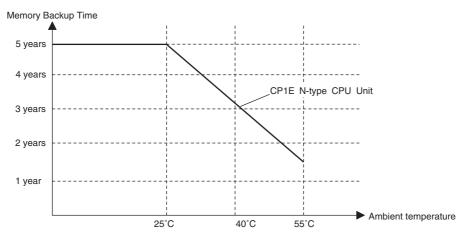
At 25°C, the maximum service life for the Battery is five years whether or not power is supplied to the CPU Unit while the Battery is installed.

The Battery's lifetime will be shorter when it is used at higher temperatures.

The following table shows the approximate minimum lifetimes and typical lifetimes for the backup Battery (total time with power not supplied).

Model number	Approx. maximum lifetime	Approx. minimum lifetime*	Typical lifetime*
CP1E-N□D□-A	5 years	13,000 hours	43,000 hours
		(1.5 years)	(5 years)

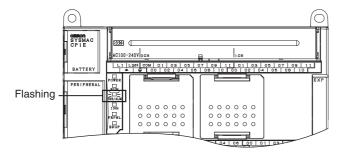
<sup>\*</sup> The minimum lifetime is the memory backup time at an ambient temperature of 55°C. The typical lifetime is the memory backup time at an ambient temperature of 25°C.



<sup>\*</sup> This graphic is for reference only.

# Low Battery Indications

The ERR/ALM indicator on the front of the CPU Unit will flash when the Battery is nearly discharged.



When the ERR/ALM indicator flashes, connect the CX-Programmer to the peripheral USB port and read the error messages.

If a low Battery message appears on the CX-Programmer or the Battery Error Flag (A402.04) is ON, first check whether the Battery is properly connected to the CPU.

If the Battery is properly connected, replace the Battery as soon as possible.

Once a low battery error has been detected, it will take 5 days (at an ambient temperature of 25°C) before the Battery fails assuming that power has been supplied at least once a day.

You can prevent loosing data in the RAM by ensuring that the CPU Unit power is not turned OFF until the Battery is replaced.



# **Precautions for Correct Use**

- The low battery message will appear on the CX-Programmer and the Battery Error Flag (A402.04) will turn ON only if the Detect Low Battery parameter in the PLC Setup has been set to detect a low-Battery error.
  - If this setting has not been made, Battery errors will not be detected.
- The Battery will discharge faster at higher temperatures, e.g., 4 days at 40°C and 2 days at 55°C.

# Replacement Battery

Name: Battery Set Model: CP1W-BAT01



## **Precautions for Correct Use**

Be sure to install a replacement Battery within two years of the production date shown on the Battery's label.

**Production Date** 



Manufactured in March 2009.

# Replacing the Battery

Use the following procedure to replace the Battery when the previous Battery has become completely discharged.



## **Precautions for Safe Use**

We recommend replacing the Battery with the power OFF to prevent the CPU Unit's sensitive internal components from being damaged by static electricity. The Battery can be replaced without turning OFF the power supply. To do so, always touch a grounded piece of metal to discharge static electricity from your body before starting the procedure.

After replacing the Battery, connect a Programming Device and clear the Battery error.

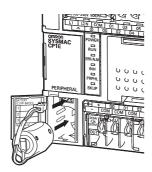
Turn OFF the power supply to the N-type CPU Unit.
If the CPU Unit has not been ON, turn it ON for at least 30 minutes and then turn it OFF.



## **Additional Information**

There is a capacitor inside the N-type CPU Unit that backs up memory when the Battery is removed. If power is not turned ON for at least 30 minutes before replacing the Battery, the capacitor will not be fully charged and memory may be lost before the new Battery is inserted.

2 Open the compartment on the CPU Unit and carefully draw out the Battery. Remove the Battery connector. Connect the new Battery, place it into the compartment, and close the cover.





## **Precautions for Safe Use**

- You must complete this procedure within 5 minutes after turning OFF the power to the CPU Unit to ensure memory backup.
  - If the Battery is removed for more than 5 minutes, data retained by the I/O memory (excluding the DM Area words saved to the backup memory) may be unstable.
- Never short-circuit the Battery terminals; never charge the Battery; never disassemble the Battery; and never heat or incinerate the Battery. Doing any of these may cause the Battery to leak, heat, burn, or rupture, resulting in injury, fire, and possible loss of property.
  - Also, never use a Battery that has been dropped on the floor or otherwise subject to shock. It may leak.
  - UL standards require that batteries be replaced by experienced technicians. Always place an experienced technician in charge of Battery replacement.
- Turn ON the power after replacing the Battery for a CPU Unit that has been unused for a long time
  - Leaving the CPU Unit unused again without turning ON the power even once after the Battery is replaced may result in a shorter Battery life.



## **Additional Information**

The Battery error will be cleared automatically the next time the CPU Unit is turned ON after replacing the Battery.



# Using Expansion Units and Expansion I/O Units

This section describes the Analog Input Unit, Analog Output Unit, Temperature Sensor Units, CompoBus/S I/O Link Unit, and Expansion I/O Units.

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## **Analog Input Units 8-1**

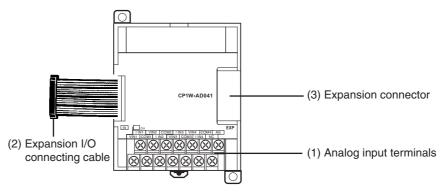
#### 8-1-1 **Overview**

Each CP1W-AD041 Analog Input Unit provides four analog inputs.

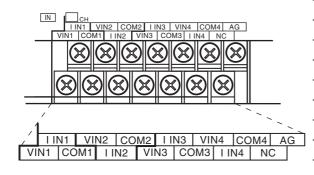
- The analog input signal ranges are 0 to 5 V, 1 to 5 V, 0 to 10 V, -10 to +10 V, 0 to 20 mA, and 4 to 20 mA. The resolution is 1/6,000. The open-circuit detection function is activated in the ranges of 1 to 5 V and 4 to 20 mA.
- The Analog Input Unit uses four input words and two output words.

#### 8-1-2 **Part Names and Functions**

## CP1W-AD041



- (1)Analog Input Terminals Connected to analog output devices.
- Input Terminal Arrangement



V IN1	Voltage input 1
I IN1	Current input 1
COM1	Input common 1
V IN2	Voltage input 2
I IN2	Current input 2
COM2	Input common 2
V IN3	Voltage input 3
I IN3	Current input 3
СОМЗ	Input common 3
V IN4	Voltage input 4
I IN4	Current input 4
COM4	Input common 4

Note When using current inputs, voltage input terminals must be short-circuited with current input terminals.

## (2) Expansion I/O Connecting Cable

Connected to the CPU Unit or Expansion Unit expansion connector. The cable is attached to the Analog Input Unit and cannot be removed.



## **Precautions for Safe Use**

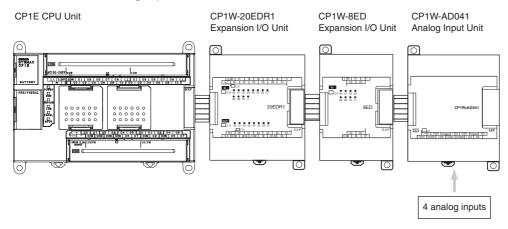
Do not touch the cables during operation. Static electricity may cause operating errors.

(3)Expansion Connector

Connected to the next Expansion Unit or Expansion I/O Unit to enable expansion.

# 8-1-3 Specifications

CP1W-AD041 Analog Input Units are connected to a CP1E CPU Unit.



Model Item		CP1W-AD	0041	
		Voltage input	Current input	
Number of and	alog inputs	4 inputs (4 words allocated)		
Input signal ra	nge	0 to 5 V, 1 to 5 V,0 to 10 V, or -10 to 10 V	0 to 20 mA or 4 to 20 mA	
Max. rated inp	ut	±15 V	±30 mA	
External input	impedance	1 MΩ min.	Approx. 250 Ω	
Resolution		1/6000 (full scale)		
Overall accu-	25°C	0.3% full scale	0.4% full scale	
racy	0 to 55°C	0.6% full scale	0.8% full scale	
A/D conversio	n data	16-bit binary (4-digit hexadecimal)		
		Full scale for -10 to 10 V: F448 to 0BB8 hex		
		Full scale for other ranges: 0000 to 1770 hex		
Averaging fund	ction	Supported (Set in output words n+1 and n+2.)		
Open-circuit d	etection function	Supported		
Conversion time		2 ms/point (8 ms/all points)		
Isolation method		Photocoupler isolation between analog input terminals and internal circuits. No isolation between analog I/O signals.		
Current consu	mption	5 VDC: 100 mA max.; 24 VDC: 90 mA max.		

# Analog Input Signal Ranges

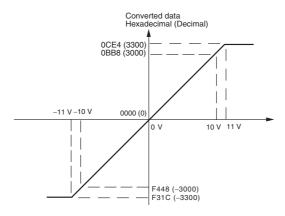
Analog input data is digitally converted according to the input signal range as shown below.



## **Additional Information**

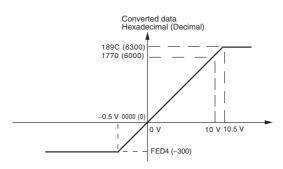
When the input exceeds the specified range, the A/D conversion data will be fixed at either the lower limit or upper limit.

## -10 to 10 V Inputs



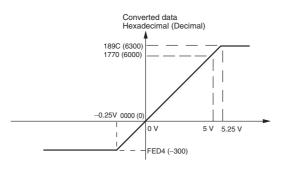
Voltages in the -10 to 10 V range correspond to hexadecimal values F448 to 0BB8 (-3,000 to 3,000). The range of data that can be converted is F31C to 0CE4 hex (-3,300 to 3,300). A negative voltage is expressed as a two's complement.

## 0 to 10 V Inputs



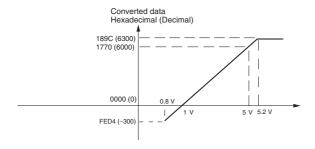
Voltages in the 0 to 10 V range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300). A negative voltage is expressed as a two's complement.

## 0 to 5 V Inputs



Voltages in the 0 to 5 V range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300). A negative voltage is expressed as a two's complement.

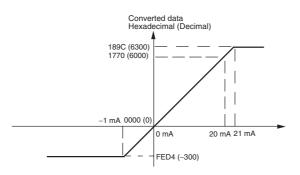
# 1 to 5 V Inputs



Voltages in the 1 to 5 V range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300). Voltage in the range of 0.8 to 1 V is expressed as a two's complement.

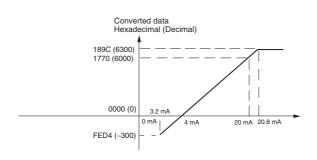
If an input is below the range (i.e., less than 0.8 V), the open-circuit detection function is activated and the data becomes 8,000.

## 0 to 20 mA Inputs



Currents in the 0 to 20 mA range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300). A negative current is expressed as a two's complement.

# 4 to 20 mA Inputs



Currents in the 4 to 20 mA range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300). Current in the range of 3.2 to 4 mA is expressed as a two's complement.

If an input is below the range (i.e., less than 3.2 mA), the open-circuit detection function is activated and the data becomes 8,000.

# Averaging Function

For analog inputs, the averaging function operates when the averaging bit is set to 1. The averaging function outputs the average (a moving average) of the last eight input values as the converted value.

Use this function to smooth inputs that vary at a short interval.

## Open-circuit Detection

The open-circuit detection function is activated when the input range is set to 1 to 5 V and the voltage drops below 0.8 V, or when the input range is set to 4 to 20 mA and the current drops below 3.2 mA.

When the open-circuit detection function is activated, the converted data will be set to 8,000.

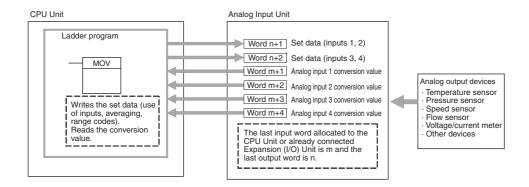
The time for enabling or clearing the open-circuit detection function is the same as the time for converting the data. If the input returns to the convertible range, the open-circuit detection is cleared automatically and the output returns to the normal range.

#### 8-1-4 **Flow of Operation**

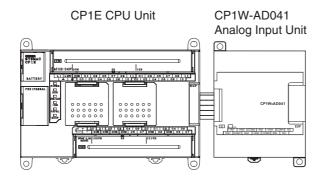


- Create a ladder program.
- Write set data to output words (n+1, n+2).
  - · Set use of inputs.
  - · Select input signals using range codes.
  - · Set use of averaging.
- Read A/D conversion values from input words (m+1 to m+4).
- · For current inputs, confirm that there is no open circuit.

# Writing Set Data and Reading A/D Conversion Values

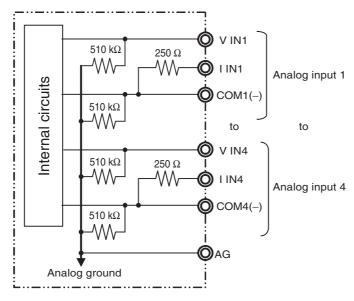


Connect the Analog Input Unit to the CPU Unit.

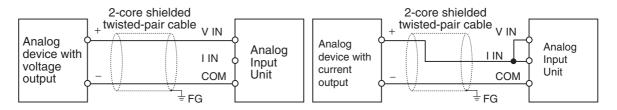


# **2** Wire to analog output devices.

## (1) Wiring internal circuits of the CPU Unit



# (2) Wiring analog output devices to the Analog Input Unit





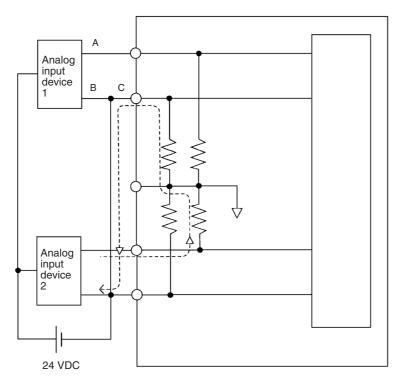
## **Precautions for Correct Use**

- Connect the shield to the FG terminal to prevent noise.
- When an input is not being used, short the + and terminals.
- Separate wiring from power lines (AC power supply lines, high-voltage lines, etc.)
- When there is noise in the power supply line, install a noise filter on the input section and the power supply.



## **Additional Information**

Refer to the following information on open circuits when using voltage inputs.



For example, if connected device 2 is outputting 5 V and the same power supply is being used for both devices as shown above, approximately 1/3, or 1.6 V, will be applied to the input for input device 1.

If a wiring disconnection occurs when voltage input is being used, the situation described below will result. Either separate the power supplies for the connected devices, or use an isolator for each input.

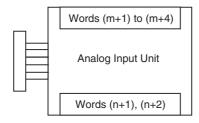
- If the same power supply is being used by the connected devices and a disconnection occurs at points A or B in the above diagram, an unwanted circuit path will occur as shown along the dotted line in the diagram. If that occurs, a voltage of approximately 1/3 to 1/2 of the output voltage of the other connected device will be generated.
- If that voltage is generated while the setting is for 1 to 5 V, open-circuit detection may not be possible.
- If a disconnection occurs at point C in the diagram, the negative (-) side will be used for both devices and open-circuit detection will not be possible.

This problem will not occur for current inputs even if the same power supply is used.

# **3** Create the ladder program.

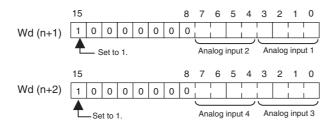
## (1) Allocating I/O Words

Four input words and two output words are allocated from the next words following the last I/O words allocated to the CPU Unit or an existing Expansion Unit or Expansion I/O Unit.

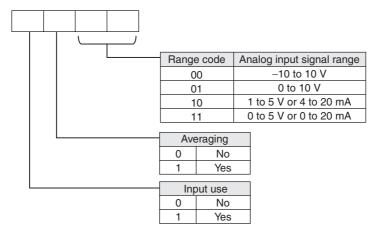


## (2) Writing Set Data

Write the settings for input use, averaging use, and range codes for words n+1 and n+2. When the set data is transferred from the CPU Unit to the Analog Input Unit, the A/D conversion will be started.



#### · Set Data



- The Analog Input Unit will not start converting analog I/O values until the range code has been written.
  - The conversion data will be 0000 until the range code is written.
- Once the settings have been made, it is not possible to change the settings while power
  is being supplied to the CPU Unit. To change the range code or other settings, turn the
  CPU Unit OFF then ON again.

## (3) Averaging

Set whether averaging is to be used for set data. When the averaging bit is set to 1, the average (moving average) for the past eight inputs is output as conversion data.

#### (4) Reading Analog Input Conversion Values

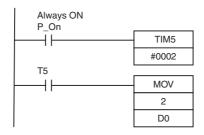
The ladder program can be used to read the memory area words where the converted values are stored.

With word m as the last input word allocated to the CPU Unit or an already-connected Expansion Unit, the A/D conversion data will be output to the following words m+1 to m+4.

#### (5) Startup Operation

After the power is turned ON, it will require two cycle times plus approximately 50 ms before the first conversion data is stored in the input words. Therefore, create a program as shown below, so that when operation begins simultaneously with startup it will wait for valid conversion data.

The analog input data will be 0000 until the initial processing is completed.



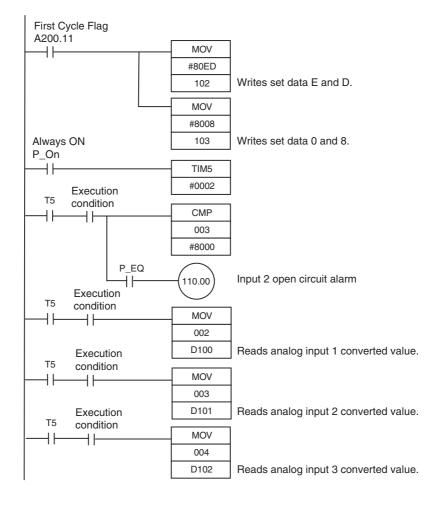
TIM5 is started when the power is turned ON. After 0.1 to 0.2 s (100 to 200 ms) elapses, the TIM5 contact turns ON and the analog input 1 conversion data stored in CIO 2 is transferred to D0.

## (6) Handling Unit Errors

- When an error occurs in an Analog Input Unit, the analog input conversion data becomes 0000.
- Expansion Unit errors are output to bits 0 to 5 of word A436 for Units 1 to 3. The bits are allocated from A436.00 in order starting with the Unit nearest the CPU Unit. CP1W-AD041 is allocated two bits each. Use these flags in the program when it is necessary to detect errors.

# (7) Ladder Program Example

Analog input	Input range	Range code	Averaging	Set data	Destination word
Input 1	0 to 10 V	01	Yes	1101 (D hex)	n+1
Input 2	4 to 20 mA	10	Yes	1110 (E hex)	n+1
Input 3	-10 to +10 V	00	No	1000 (8 hex)	n+2
Input 4	Not used.	-(00)	-	0000 (0 hex)	n+2



## 8-2 **Analog Output Units**

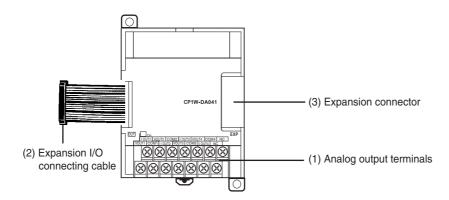
#### 8-2-1 **Overview**

Each CP1W-DA041 Analog Output Unit provides four analog outputs.

- The analog output signal ranges are 1 to 5 V, 0 to 10 V, -10 to +10 V, 0 to 20 mA, and 4 to 20 mA.
- The Analog Output Unit uses four output words.

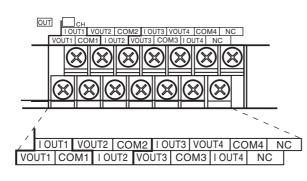
#### **Part Names and Functions** 8-2-2

## CP1W-DA041



## (1) Analog Output Terminals Connected to analog input devices.

• I/O Terminal Arrangement



V OUT1	Voltage output 1
I OUT1	Current output 1
COM1	Output common 1
V OUT2	Voltage output 2
I OUT2	Current output 2
COM2	Output common 2
V OUT3	Voltage output 3
I OUT3	Current output 3
СОМЗ	Output common 3
V OUT4	Voltage output 4
I OUT4	Current output 4
COM4	Output common 4

## (2) Expansion I/O Connecting Cable

Connected to the expansion connector on the CPU Unit or previous Expansion Unit. The cable is provided with the Unit and cannot be removed.



## **Precautions for Safe Use**

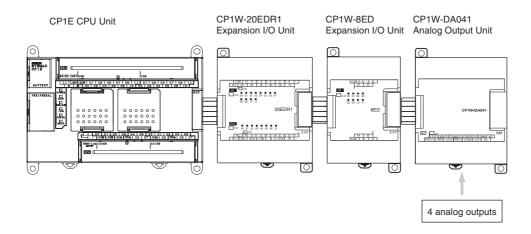
Do not touch the cables during operation. Static electricity may cause operating errors.

#### (3) Expansion Connector

Connected to the next Expansion Unit or Expansion I/O Unit.

# 8-2-3 Specifications

CP1W-DA041 Analog Output Units are connected to a CP1E CPU Unit.



	Model		CP1W-D	CP1W-DA041		
	Item		Voltage output	Current output		
Analog	Number of anal	og outputs	4 outputs (4 words allocated)	•		
output section	Output signal ra	ınge	1 to 5 V, 0 to 10 V, or -10 to 10 V	0 to 20 mA or 4 to 20 mA		
Section	External output allowable load resistance		2 kΩ min.	350 Ω max.		
	External output impedance		0.5 Ω max.	-		
	Resolution		1/6000 (full scale)			
	Overall accuracy	25°C	0.4% full scale			
		0 to 55°C	0.8% full scale			
	D/A conversion data		16-bit binary (4-digit hexadecimal)			
			Full scale for -10 to 10 V: F448 to 0BB8 hex			
			Full scale for other ranges: 0000 to 1770 hex			
Convers	ion time		2 ms/point (8 ms/all points)			
Isolation	Isolation method		Photocoupler isolation between analog I/O terminals and internal circuits. No isolation between analog I/O signals.			
Current	consumption		5 VDC: 80 mA max.; 24 VDC: 124 r	mA max.		

# Analog Output Signal Ranges

The output data is converted to analog according to the output signal range, as shown below.



## **Additional Information**

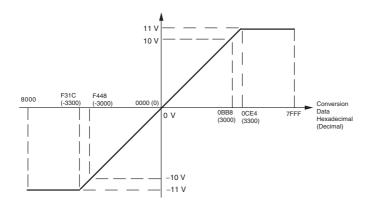
When the output exceeds the specified range, the output signal will be fixed at either the lower limit or upper limit.

# -10 to 10 V

The hexadecimal values F448 to 0BB8 (-3000 to 3000) correspond to an analog voltage range of -10 to 10 V.

The entire output range is -11 to 11 V.

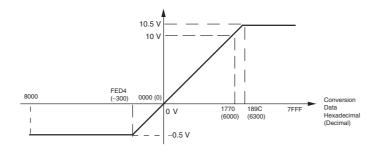
Specify the DA conversion data as the two's complement if it is a negative value.



# 0 to 10 V

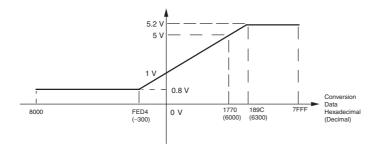
The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog voltage range of 0 to 10 V. The entire output range is -0.5 to 10.5 V.

Specify the DA conversion data as the two's complement if it is a negative value.



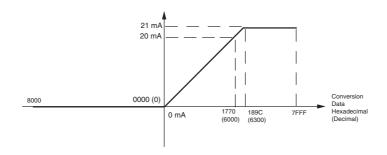
## 1 to 5 V

The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog voltage range of 1 to 5 V. The entire output range is 0.8 to 5.2 V.



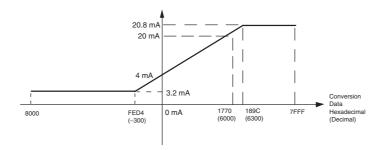
## 0 to 20 mA

The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog current range of 0 to 20 mA. The entire output range is 0 to 21 mA.



#### 4 to 20 mA

The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog current range of 4 to 20 mA. The entire output range is 3.2 to 20.8 mA.

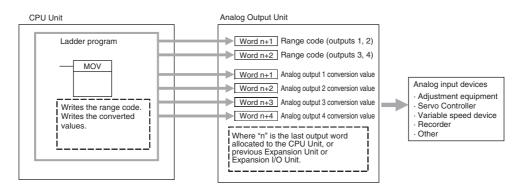


# 8-2-4 Flow of Operation

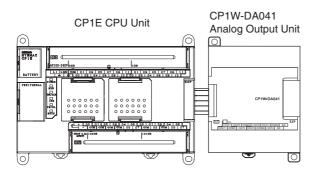


- · Connect Analog Output Units.
- Wire to analog input devices.
- 2 Create a ladder program.
- Write range code to output words (n+1, n+2).
  - · Set use of outputs.
  - Select output signals using range codes.
- Write D/A conversion values to output words (n+1 to n+4).

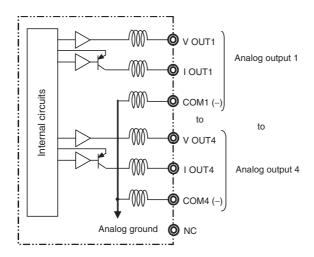
# Writing D/A Conversion Data



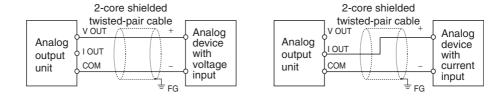
Connect the Analog Output Unit to the CPU Unit.



- Wire to analog input devices.
  - (1) Wiring internal circuits of the CPU Unit



(2) Wiring analog input devices to the Analog Output Unit





# **Precautions for Correct Use**

- Connect the shield to the FG terminal to prevent noise.
- Separate wiring from power lines (AC power supply lines, high-voltage lines, etc.)
- When there is noise in the power supply line, install a noise filter on the input section and the power supply.



#### **Additional Information**

When external power is supplied (when setting the range code), or when there is a power interruption, a pulse-form analog output of up to 1 ms may be generated.

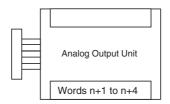
If this causes problems with operation, take countermeasures such as those suggested below.

- Turn ON the power supply for the CP1E CPU Unit first, confirm correct operation, and then turn ON the power supply for the load.
- Turn OFF the power supply for the load before turning OFF the power supply for the CP1E CPU Unit.

# **3** Create the ladder program.

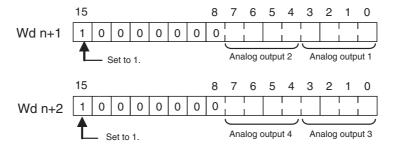
## (1) Allocating Output Words

Four output word are allocated to the Analog Output Unit starting from the next word following the last allocated word on the CPU Unit or previous Expansion Unit or Expansion I/O Unit.

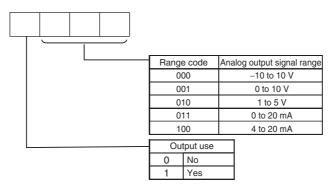


## (2) Writing Set Data

Write the output use and the range code to words n+1 and n+2. The D/A conversion will start when the set data is transferred from the CPU Unit to the Analog Output Unit.



## Set Data



- The Analog Output Unit will not start converting analog I/O values until the range code has been written. The output will be 0 V or 0 mA.
- After the range code has been set, 0 V or 0 mA will be output for the 0 to 10V, -10 to 10V, or 0 to 20 mA ranges, and 1 V or 4 mA will be output for the 1 to 5V and 4 to 20 mA ranges until a convertible value has been written to the output word.

 Once the range code has been set in the Analog Output Unit, it is not possible to change the setting while power is being supplied to the CPU Unit. To change the I/O range, turn the CPU Unit OFF then ON again.

## (3) Writing Analog Output Set Values

The ladder program can be used to write data to the output word where the set value is stored.

The output words will be n+1 to n+4 when "n" is the last output word allocated to the CPU Unit, or previous Expansion Unit or Expansion I/O Unit.

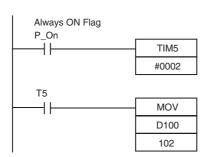
### (4) Startup Operation

After power is turned ON, it will require two cycle times plus approximately 50 ms before the first data is converted.

The following table shows the output status after the initial processing is completed.

Output type	Voltage output		Current	toutput
Output range	0 to 10 V, -10 to +10 V		0 to 20 mA	4 to 20 mA
Before range code is written	ov		0mA	
After range code is written	0V 1V		0mA	4mA

Therefore, create a program as shown below, so that when operation begins simultaneously with startup it will wait for valid set data.



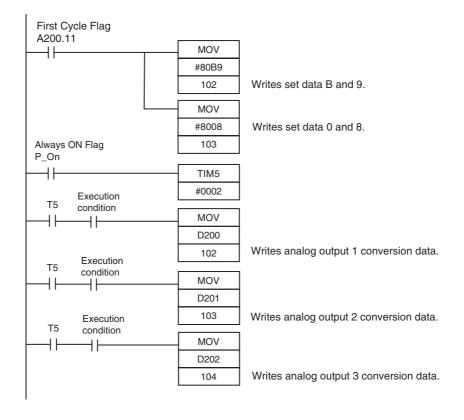
TIM 005 will start as soon as power turns ON. After 0.1 to 0.2 s (100 to 200 ms), the Completion Flag for TIM 005 will turn ON, and the data stored in D100 will be moved to CIO 102 as the conversion data for analog output 1.

## (5) Handling Unit Errors

- When an error occurs at the Analog Output Unit, the analog output will be 0 V or 0 mA. If a CPU error or an I/O bus error (fatal errors) occurs at the CPU Unit and the analog output is set to 1 to 5 V or 4 to 20 mA, 0 V or 0 mA will be output. For any other fatal errors at the CPU Unit, 1 V or 4 mA will be output.
- Expansion Unit and Expansion I/O Unit errors are output to bits 0 to 5 of word A436 for units 1 to 3. The bits are allocated from A436.00 in order starting from the Unit nearest the CPU Unit. CP1W-DA041 is allocated two bits each. Use these flags in the probgram when it is necessary to detect errors.

# (6) Program Example

Analog output	Output range	Range code	Set data	Destination word
Output 1	0 to 10 V	001	1001 (9 hex)	Wd n+1
Output 2	4 to 20 mA	011	1011 (B hex)	Wd n+1
Output 3	-10 to 10 V	000	1000 (8 hex)	Wd n+2
Output 4	Not used.	-(000)	0000 (0 hex)	Wd n+2



## **Analog I/O Units** 8-3

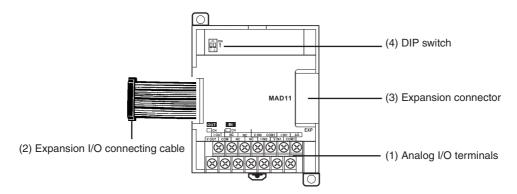
#### 8-3-1 **Overview**

Each CP1W-MAD11 Analog I/O Unit provides 2 analog inputs and 1 analog output.

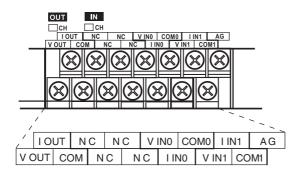
- The analog input range can be set to 0 to 5 V, 1 to 5 V, 0 to 10 V, -10 to 10 V, 0 to 20 mA, or 4 to 20 mA. The inputs have a resolution of 1/6000. An open-circuit detection function can be used with the 1 to 5 V and 4 to 20 mA settings.
- The analog output range can be set to 1 to 5 V, 0 to 10 V, -10 to 10 V, 0 to 20 mA, or 4 to 20 mA. The outputs have a resolution of 1/6000.

#### **Part Names and Functions** 8-3-2

## CP1W-MAD11



- (1) Analog I/O Terminals Connected to analog I/O devices.
- I/O Terminal Arrangements



V OUT	Voltage output	
I OUT	Current output	
COM	Output common	
V IN0	Voltage input 0	
I INO	Current input 0	
COM0	M0 Input common 0	
V IN1	Voltage input 1	
I IN1	Current input 1	
COM1	Input common 1	

Note For current inputs, short V IN0 to I IN0 and V IN1 to I IN1.

## (2) Expansion I/O Connecting Cable

Connected to the expansion connector of a CPU Unit or an Expansion Unit. The cable is provided with the Analog I/O Unit and cannot be removed.



## **Precautions for Safe Use**

Do not touch the cables during operation. Static electricity may cause operating errors.

## (3) Expansion Connector

Used for connecting Expansion Units or Expansion I/O Units.

## (4)DIP Switch

Used to enable or disable averaging.

Pin 1: Average processing for analog input 0



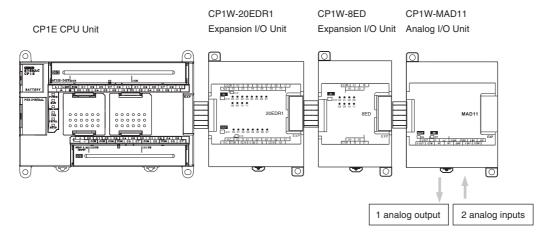
(OFF: Average processing not performed; ON: Average processing performed)

Pin 2: Average processing for analog input 1

(OFF: Average processing not performed; ON: Average processing performed)

# 8-3-3 Specifications

CP1W-MAD11 Analog I/O Units are connected to the CP1E CPU Unit.



	Model		CP1W-MAD11		
	Item		Voltage I/O	Current I/O	
Analog	Number of ar	nalog inputs	2 inputs (2 words allocated)		
Input Section	Input signal ra	ange	0 to 5 V, 1 to 5 V,0 to 10 V, or -10 to 10 V	0 to 20 mA or 4 to 20 mA	
Section	Max. rated in	put	±15 V	±30 mA	
	External inpu	t impedance	1 MΩ min.	Approx. 250 Ω	
	Resolution		1/6000 (full scale)		
	Overall	25°C	0.3% full scale	0.4% full scale	
	accuracy	0 to 55°C	0.6% full scale	0.8% full scale	
	A/D conversion	on data	16-bit binary (4-digit hexadecimal)		
			Full scale for -10 to 10 V: F448 to 0BB8 I	nex	
			Full scale for other ranges: 0000 to 1770 hex		
	Averaging fur	nction	Supported (Settable for individual inputs via DIP switch)		
	Open-circuit of tion	detection func-	Supported		
Analog	Number of ou	ıtputs	1 output (1 word allocated)		
Output Section	Output signal	range	1 to 5 VDC, 0 to 10 VDC, or -10 to 10 VDC	0 to 20 mA or 4 to 20 mA	
	Allowable external output load resistance		1 kΩ min.	600 $Ω$ max.	
	External outp	ut impedance	$0.5~\Omega$ max.	-	
	Resolution		1/6000 (full scale)		
	Overall 25°C		0.4% full scale		
	accuracy	0 to 55°C	0.8% full scale		
	Set data (D/A	conversion)	16-bit binary (4-digit hexadecimal)		
			Full scale for -10 to 10 V: F448 to 0BB8 hex		
			Full scale for other ranges: 0000 to 1770 hex		
Convers	ion time		2 ms/point (6 ms/all points)		
Isolation	method		Photocoupler isolation between analog I/O terminals and internal circuits.		
			No isolation between analog I/O signals.		
Current	consumption		5 VDC: 83 mA max., 24 VDC: 110 mA max.		

# Analog I/O Signal Ranges

Analog I/O data is digitally converted according to the analog I/O signal range as shown below.

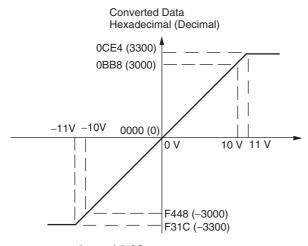


# **Additional Information**

When the input/output exceeds the specified range, the AD/DA converted data will be fixed at either the lower limit or upper limit.

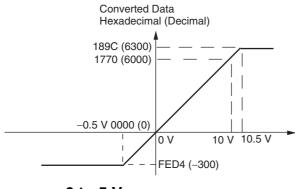
# Analog I/O Signal Ranges

## -10 to 10 V



Voltages in the -10 to 10 V range correspond to hexadecimal values F448 to 0BB8 (-3,000 to 3,000). The range of data that can be converted is F31C to 0CE4 hex (-3,300 to 3,300). A negative voltage is expressed as a two's complement.

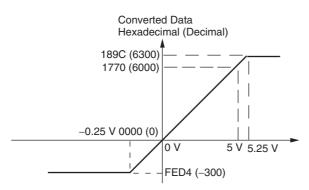




Voltages in the 0 to 10 V range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300).

A negative voltage is expressed as a two's complement.

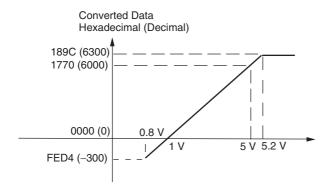
# 0 to 5 V



Voltages in the 0 to 5 V range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300).

A negative voltage is expressed as a two's complement.

## 1 to 5 V

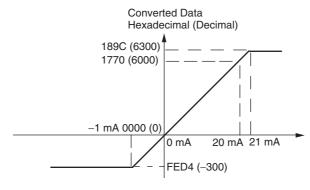


Voltages in the 1 to 5 V range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300).

Voltage in the range of 0.8 to 1 V is expressed as a two's complement.

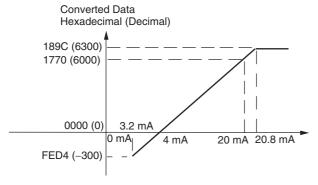
If an input is below the range (i.e., less than 0.8 V), the open-circuit detection function is activated and the data becomes 8,000.

## 0 to 20 mA



Currents in the 0 to 20 mA range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300). A negative current is expressed as a two's complement.

## 4 to 20 mA



Currents in the 4 to 20 mA range correspond to hexadecimal values 0000 to 1770 (0 to 6,000). The range of data that can be converted is FED4 to 189C hex (-300 to 6,300). Current in the range of 3.2 to 4 mA is expressed as a two's complement. If an input is below the range (i.e., less than 3.2 mA), the open-circuit detection function is activated and the data becomes 8,000.

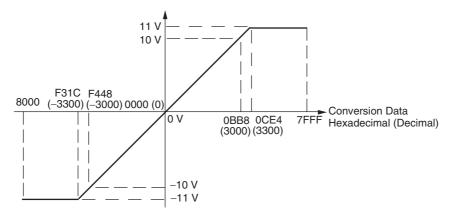
# Analog Output Signal Ranges

## -10 to 10 V

The hexadecimal values F448 to 0BB8 (-3000 to 3000) correspond to an analog voltage range of -10 to 10 V.

The entire output range is -11 to 11V.

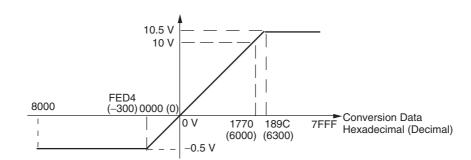
Specify the DA conversion data as the two's complement if it is a negative value.



## 0 to 10 V

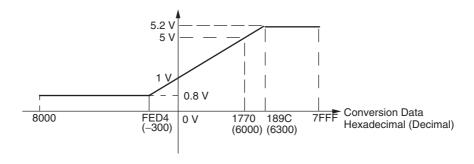
The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog voltage range of 0 to 10  $\rm V$ . The entire output range is -0.5 to 10.5  $\rm V$ .

Specify the DA conversion data as the two's complement if it is a negative value.



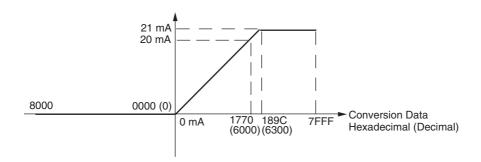
## 1 to 5 V

The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog voltage range of 1 to 5 V. The entire output range is 0.8 to 5.2 V.



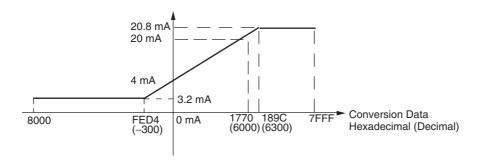
## 0 to 20 mA

The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog current range of 0 to 20 mA. The entire output range is 0 to 21 mA.



## 4 to 20 mA

The hexadecimal values 0000 to 1770 (0 to 6000) correspond to an analog current range of 4 to 20 mA. The entire output range is 3.2 to 20.8 mA.



# **Other Functions**

# Averaging Function for Analog Inputs

The averaging function can be enabled for inputs using the DIP switch. The averaging function outputs the average (a moving average) of the last eight input values as the converted value.

Use this function to smooth inputs that vary at a short interval.

# Open-circuit Detection Function for Analog Inputs

The open-circuit detection function is activated when the input range is set to 1 to 5 V and the voltage drops below 0.8 V, or when the input range is set to 4 to 20 mA and the current drops below 3.2 mA.

When the open-circuit detection function is activated, the converted data will be set to 8,000.

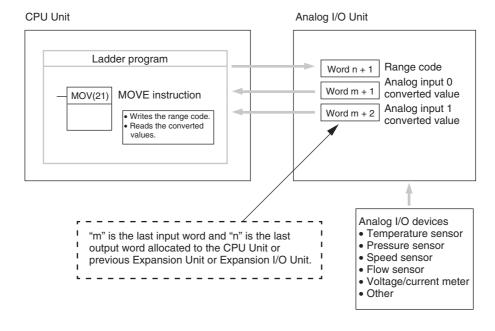
The time for enabling or clearing the open-circuit detection function is the same as the time for converting the data.

If the input returns to the convertible range, the open-circuit detection is cleared automatically and the output returns to the normal range.

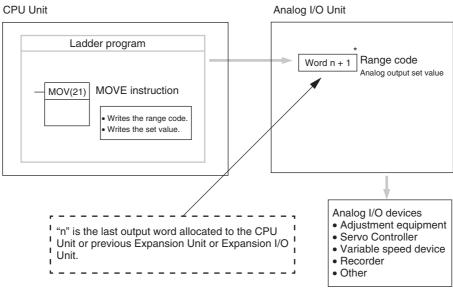
# 8-3-4 Flow of Operation

- Connect the Unit.
- Connect the Analog I/O Unit.
- Set analog inputs as voltage or current inputs and set the averaging function.
- **2** Wire the analog I/O.
- Connect analog I/O devices.
- Program operation in the ladder program.
- Write the range code.
- Analog inputs: Read converted data.
- · Analog output: Write set values.

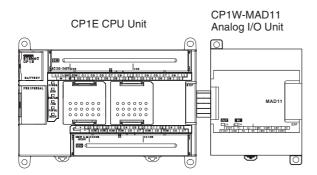
# Reading Range Code Settings and A/D Conversion Data



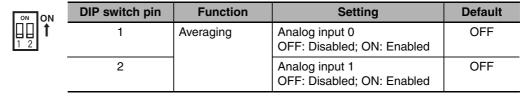
# Writing D/A Conversion Data



- \* Word (n + 1) can be used for either the range code or the analog output set value.
  - Connect the Analog I/O Unit to the CPU Unit.

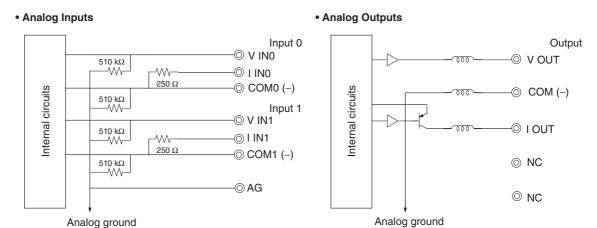


Setting the Averaging Function DIP switch pins 1 and 2 are used to set the averaging function. When averaging is enabled, a moving average of the last eight input values is output as the converted value. The averaging function can be set separately for analog inputs 0 and 1.

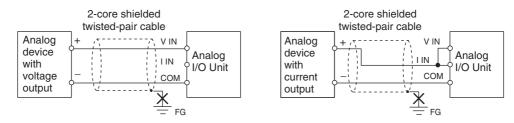


# **2** Wire to analog I/O devices.

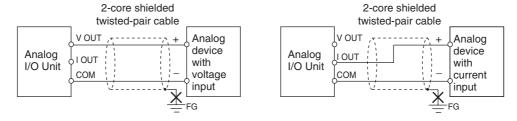
# (1) Wiring internal circuits of the CPU Unit



## (2) Wiring analog output devices to the Analog I/O Unit



## (3) Wiring analog input devices to the Analog I/O Unit





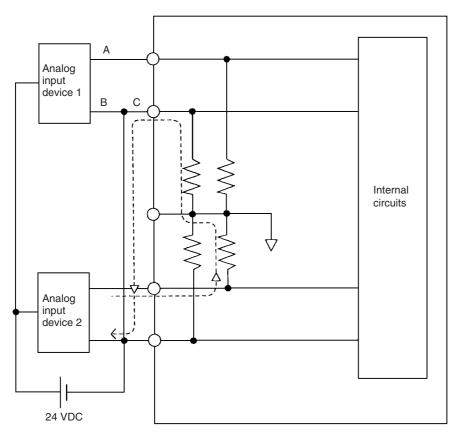
## **Precautions for Correct Use**

- Do not connect the shield when using shielded twisted-pair cables.
- When an input is not being used, short the + and terminals.
- Separate wiring from power lines (AC power supply lines, high-voltage lines, etc.)
- When there is noise in the power supply line, install a noise filter on the input section and the power supply terminals.



### **Additional Information**

Refer to the following information on open circuits when using voltage inputs.



Example: If connected device 2 is outputting 5 V and the same power supply is being used for both devices as shown above, approximately 1/3, or 1.6 V, will be applied to the input for input device 1.

If a wiring disconnection occurs when voltage input is being used, the situation described below will result. Either separate the power supplies for the connected devices, or use an isolator for each input.

- If the same power supply is being used by the connected devices and a disconnection occurs at points A or B in the above diagram, an unwanted circuit path will occur as shown along the dotted line in the diagram. If that occurs, a voltage of approximately 1/3 to 1/2 of the output voltage of the other connected device will be generated.
- If that voltage is generated while the setting is for 1 to 5 V, open-circuit detection may not be possible.
- If a disconnection occurs at point C in the diagram, the negative (-) side will be used for both devices and open-circuit detection will not be possible.

This problem will not occur for current inputs even if the same power supply is used.



#### **Additional Information**

When external power is supplied (when setting the range code), or when there is a power interruption, a pulse-form analog output of up to 1 ms may be generated.

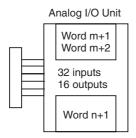
If this causes problems with operation, take countermeasures such as those suggested below.

- Turn ON the power supply for the CP1E CPU Unit first, confirm correct operation, and then turn ON the power supply for the load.
- Turn OFF the power supply for the load before turning OFF the power supply for the CP1E CPU Unit.

# **3** Create the ladder program.

# (1) Allocating I/O Words

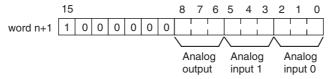
Two input words and one output word are allocated to the Analog I/O Unit starting from the next word following the last allocated word on the CPU Unit or previous Expansion Unit or Expansion I/O Unit.



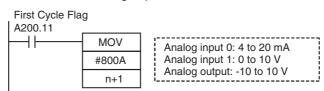
## (2) Writing the Range Code

Write the range code to word n+1. A/D or D/A conversion begins when the range code is transferred from the CPU Unit to the Analog I/O Unit. There are five range codes, 000 to 100, that combine the analog input 0 and 1 and analog output signal ranges, as shown below.

Range code	Analog input 0 signal range	Analog input 1 signal range	Analog output signal range
000	-10 to 10 V	-10 to 10 V	-10 to 10 V
001	0 to 10 V	0 to 10 V	0 to 10 V
010	1 to 5 V/4 to 20 mA	1 to 5 V/4 to 20 mA	1 to 5 V
011	0 to 5 V/0 to 20 mA	0 to 5 V/0 to 20 mA	0 to 20 mA
100	-	_	4 to 20 mA



Example: The following instructions set analog input 0 to 4 to 20 mA, analog input 1 to 0 to 10 V, and the analog output to -10 to 10 V.



- The Analog I/O Unit will not start converting analog I/O values until the range code has been written. Inputs will be 0000, and 0 V or 0 mA will be output.
- After the range code has been set, 0 V or 0 mA will be output for the 0 to 10V, -10 to 10V, or 0 to 20mA ranges, and 1 V or 4 mA will be output for the 1 to 5V and 4 to 20mA ranges until a convertible value has been written to the output word.
- Once the range code has been set, it is not possible to change the setting while power is being supplied to the CPU Unit. To change the I/O range, turn the CPU Unit OFF then ON again.

#### (3) Reading Analog Input Conversion Values

The ladder program can be used to read the memory area words where the converted values are stored.

Values are output to the next two words (m + 1, m + 2) following the last input word (m) allocated to the CPU Unit or previous Expansion Unit or Expansion I/O Unit.

## (4) Writing Analog Output Set Values

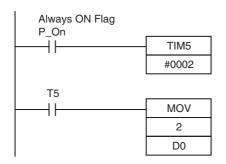
The ladder program can be used to write data to the memory area where the set value is stored.

The output word will be "n+1", where "n" is the last output word allocated to the CPU Unit or previous Expansion Unit or Expansion I/O Unit.

#### (5) Startup Operation

After the power is turned ON, it will require two cycle times plus approximately 50 ms before the first conversion data is stored in the input words. Therefore, create a program as shown below, so that when operation begins simultaneously with startup it will wait for valid conversion data.

Analog input data will be 0000 until initial processing is completed. Analog output data will be 0 V or 0 mA until the range code has been written. After the range code has been written, the analog output data will be 0 V or 0 mA if the range is 0 to 10 V, -10 to 10 V, or 0 to 20 mA, or it will be 1 V or 4 mA if the range is 1 to 5 V or 4 to 20 mA.



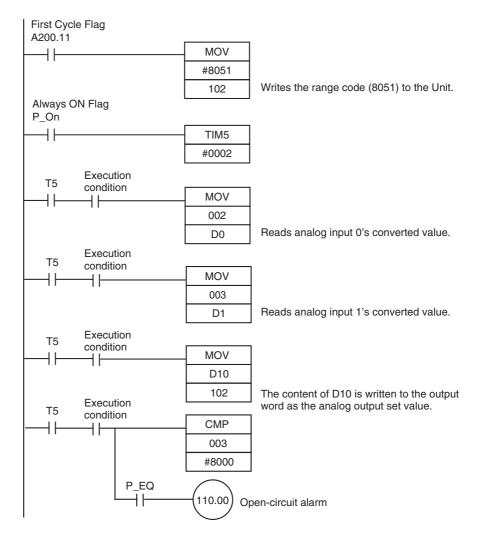
TIM 5 will start as soon as power turns ON. After 0.1 to 0.2 s (100 to 200 ms), the input for TIM 5 will turn ON, and the converted data from analog input 0 that is stored in CIO 2 will be transferred to D0.

## (6) Handling Unit Errors

- When an error occurs in the Analog I/O Unit, analog input data will be 0000 and 0 V or 0 mA will be output as the analog output.
  - If a CPU error or an I/O bus error (fatal errors) occurs at the CPU Unit and the analog output is set to 1 to 5 V or 4 to 20 mA, 0 V or 0 mA will be output. For any other fatal errors at the CPU Unit, 1 V or 4 mA will be output.
- Expansion Unit and Expansion I/O Unit errors are output to bits 0 to 5 of word A436. The bits are allocated from A436.00 in order starting from the Unit nearest the CPU Unit. Use these flags in the program when it is necessary to detect errors.

# (7) Programming Example

Analog input 0: 0 to 10 V Analog input 1: 4 to 20 mA Analog output : 0 to 10 V



## **Temperature Sensor Units** 8-4

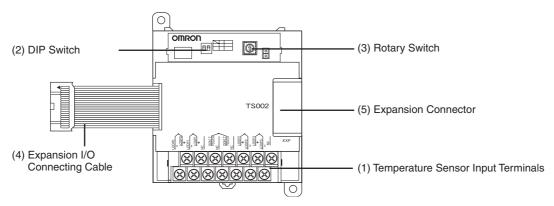
#### 8-4-1 **Overview**

CP1W-TS002/TS102 Temperature Sensor Units each provide up to four input points, and CP1W-TS001/TS101 Temperature Sensor Units each provide up to two input points. The inputs can be from thermocouples or platinum resistance thermometers.

CP1W-TS002/TS102 Temperature Sensor Units are each allocated four input words.

#### 8-4-2 **Part Names and Functions**

## ■ Temperature Sensor Units: CP1W-TS□□□



### (1) Temperature Sensor Input Terminals

Used to connect temperature sensors such as thermocouples or platinum resistance thermometers.

### (2)DIP Switch

Used to set the temperature unit (°C or °F) and the number of decimal places used.

### (3)Rotary Switch

Used to set the temperature input range. Make the setting according to the specifications of the temperature sensors that are connected.

### (4) Expansion I/O Connecting Cable

Connected to the expansion connector of a CP1E CPU Unit or an Expansion Unit or Expansion I/O Unit. The cable is included with the Temperature Sensor Unit and cannot be removed.



### **Precautions for Safe Use**

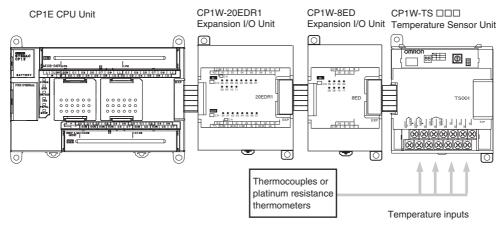
Do not touch the cables during operation. Static electricity may cause operating errors.

### (5) Expansion Connector

Used for connecting Expansion Units or Expansion I/O Units.

## 8-4-3 Specifications

A CP1W-TSDDD Temperature Sensor Unit can be connected to a CP1E CPU Unit.



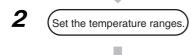
Model	CP1W-TS001	CP1W-TS002	CP1W-TS101	CP1W-TS102	
Temperature sen-	Thermocouples		Platinum resistance thermometer		
sors		, 31		Pt100 and JPt100, but sed for all inputs.	
Number of inputs	2	4	2	4	
Allocated input words	2	4	2	4	
Accuracy	(The larger of ±0.5% of converted value or ±2°C) ±1 digit max. *		(The larger of $\pm 0.5\%$ of converted value or $\pm 1$ °C) $\pm 1$ digit max.		
Conversion time	250 ms for 2 or 4 inpu	ıt points		_	
Converted tempera- ture data	16-bit binary data (4-c	digit hexadecimal)			
Isolation	Photocouplers between	en all temperature inpu	t signals	_	
Current consump-	5 VDC: 40 mA max.,		5 VDC: 54 mA max.,		
tion	24 VDC: 59 mA max.		24 VDC: 73 mA max.		

<sup>\*</sup> Accuracy for a K-type sensor at -100°C or less is ±4°C ±1 digit max.

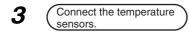
## 8-4-4 Flow of Operation



• Connect the Temperature Sensor Unit.



 Set the temperature unit, 2-decimal-place Mode if required, and set the temperature input range.



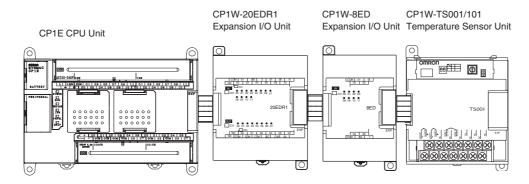
• Connect temperature sensors.



Program operation in the ladder program.

Read temperature data stored in the input word.

Connect the Temperature Sensor Unit to the CPU Unit.



With the Temperature Sensor Unit's DIP switch and rotary switch, set the temperature unit, the number of decimal places, and the temperature input range.



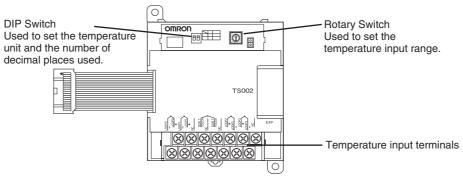
### **Precautions for Safe Use**

Do not touch the DIP switch or rotary switch while power is being supplied. Static electricity may cause operating errors.



## **Precautions for Correct Use**

Always turn OFF the power supply before setting the temperature range.



## (1) DIP Switch Settings

The DIP switch is used to set the temperature unit (°C or °F) and the number of decimal places.



SW	Setting				
1	Temperature unit	OFF	°C		
		ON	°F		
2	Number of deci- mal places*	OFF	Normal (0 or 1 digit after the decimal point, depending on the input range)		
		ON	2-decimal-place Mode		

For details on 2-decimal-place Mode, refer to Two-decimal-place Mode in 8-4-5 Function Descriptions.

## (2) Rotary Switch Setting

## **⚠** Caution

Set the temperature range according to the type of temperature sensor connected to the Unit.



Temperature data will not be converted correctly if the temperature range does not match the sensor.

Do not set the temperature range to any values other than those for which temperature ranges are given in the following table.



An incorrect setting may cause operating errors.

The rotary switch is used to set the temperature range.



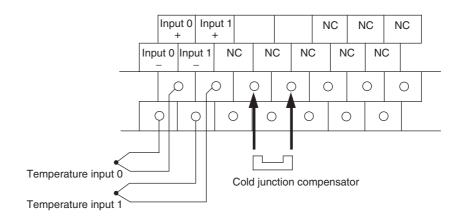
Set-	CP1W-TS001/TS002			(	TS102	
ting	Input type	Range (°C)	Range (°F)	Input type	Range (°C)	Range (°F)
0	K	-200 to 1,300	-300 to 2,300	Pt100	-200.0 to 650.0	-300.0 to 1,200.0
1		0.0 to 500.0	0.0 to 900.0	JPt100	-200.0 to 650.0	-300.0 to 1,200.0
2	J	-100 to 850	-100 to 1,500	_	Cannot be se	et.
3		0.0 to 400.0	0.0 to 750.0	_		
4 to F	-	Cannot be set		_		

## **3** Connect Temperature Sensors.

## (1) Thermocouples

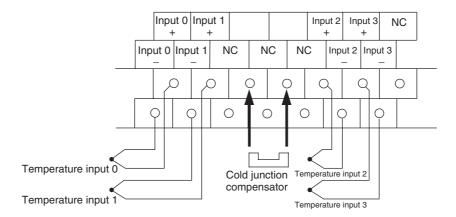
## (a) CP1W-TS001

Either K or J thermocouples can be connected to the CP1W-TS001, but both of the thermocouples must be of the same type and the same input range must be used for each.



### (b) CP1W-TS002

Up to four K or J thermocouples can be connected to the CP1W-TS002, but all four of the thermocouples must be of the same type and the same input range must be used for each





### **Precautions for Correct Use**

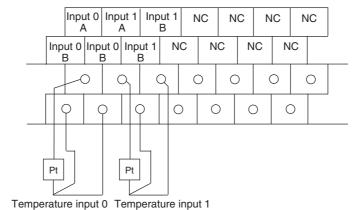
When using a Temperature Sensor Unit with a thermocouple input, observe the following precautions:

- Do not remove the cold junction compensator attached at the time of delivery. If the cold junction compensator is removed, the Unit will not be able to measure temperatures correctly.
- Each of the input circuits is calibrated with the cold junction compensator attached to the Unit.
   If the Unit is used with the cold junction compensator from other Units, the Unit will not be able to measure temperatures correctly.
- Do not touch the cold junction compensator. Doing so may result in incorrect temperature measurement.

### (2) Platinum Resistance Thermometers

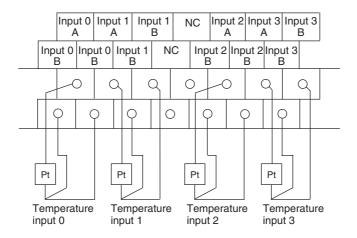
### (a) CP1W-TS101

One or two Pt or JPt platinum resistance thermometers can be connected to the CP1W-TS101, but both of the thermometers must be of the same type and the same input range must be used for each.



### (b) CP1W-TS102

Up to four Pt100 or JPt100 platinum resistance thermometers can be connected to the CP1W-TS102, but all four of the thermometers must be of the same type and the same input range must be used for each.





## **Precautions for Correct Use**

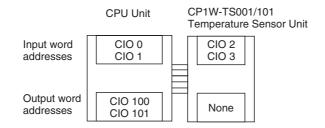
Do not connect anything to terminals not used for inputs.

**4** Create the ladder program.

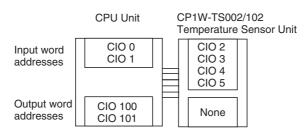
#### (1) Words Allocation

Temperature Sensor Units are allocated words just like other CP-series as Expansion Units or Expansion I/O Units, i.e., in order of connection. A Temperature Sensor Unit is allocated the next input words following the input words of the CPU Unit or previous Expansion Unit or Expansion I/O Unit. Two input words are allocated to the 2-input CP1W-TS001 or CP1W-TS101 and four input words are allocated to the 4-input CP1W-TS002 or CP1W-TS102. No output words are allocated.

• Example 1 (CPU Unit with 30 or 40 I/O Points)



Example 2 (CPU Unit with 30 or 40 I/O Points)



## (2) Reading Temperature Data

The temperature data will be stored in the input words allocated to the Temperature Sensor Unit in 4-digit hexadecimal.

CP1W-TS002/TS102		CP1W-TS001/TS101	
m+1	Converted temperature data from input 0	m+1	Converted temperature data from input 0
m+2	Converted temperature data from input 1	m+2	Converted temperature data from input 1
m+3	Converted temperature data from input 2		
m+4	Converted temperature data from input 3		

"m" is the last input word allocated to the CPU Unit, Expansion I/O Unit, or Expansion Unit connected immediately before the Temperature Sensor Unit.

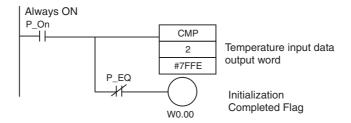
- If the converted value is a negative value, it will be stored as its two's complements.
- Data for range codes that include one digit after the decimal point are stored as binary without the decimal point, i.e., 10 times the actual value is stored.

Input		Data conversion examples			
Unit: 1°C	K, J	850°C-	850°C→0352 hex		
		-200°C-	→FF38 hex		
Unit: 0.1°C	Pt, JPt, K, J	×10	500.0°C→5000→1388 hex		
		-20.0°C→-200→FF38 hex			
			-200.0°C→-2000→F830 hex		

- · If the input temperature exceeds the maximum or minimum value in the temperature input range that has been set by ±20°C or ±20°F, the displayed value will be held.
- If the circuit is disconnected, the open-circuit detection function will operate and the converted temperature data will be set to 7FFF.
- The open-circuit detection function will be automatically cleared and normal input temperature conversion will begin automatically when the input temperature returns to the convertible range.

### (3) Startup Operation

After power is turned ON, approximately 1 s is required for the first conversion data to be stored in the input word. During that period, the data will be 7FFE. Therefore, create a program as shown below, so that when operation begins simultaneously with startup it will wait for valid conversion data.

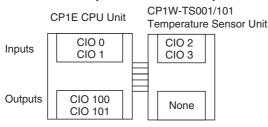


### (4) Handling Unit Errors

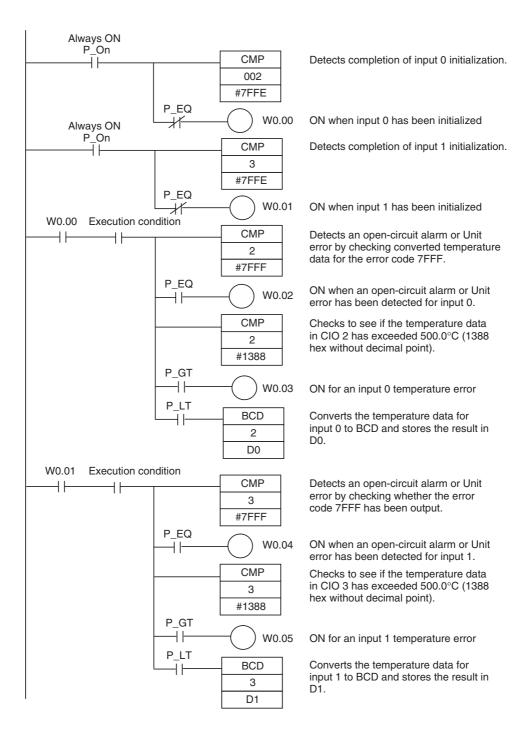
- Expansion Unit and Expansion I/O Unit errors are output to bits 0 to 5 of word A436. The
  bits are allocated from A436.00 in order starting from the Unit nearest the CPU Unit.
  CP1W-TS002 and CP1W-TS102 Temperature Sensor Units are allocated two bits each.
  Use these flags in the program when it is necessary to detect Expansion Unit/Expansion
  I/O Unit errors.
- When an error occurs, the Temperature Sensor Unit data becomes 7FFF hex (the same as for an open-circuit detection). With an open-circuit detection, it is not reflected in word A436.

### (5) Programming Example (CPU Unit with 30 or 40 I/O Points)

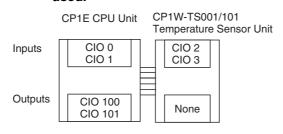
(a) The following programming example shows how to convert the input data from 2 temperature sensor inputs to BCD and store the result in D0 and D1.



Temperature unit	0 (°C)
Number of decimal places	0 (normal)
Input range setting	1 (K: 0.0 to 500.0°C)
Input 0	CIO 2
Input 1	CIO 3

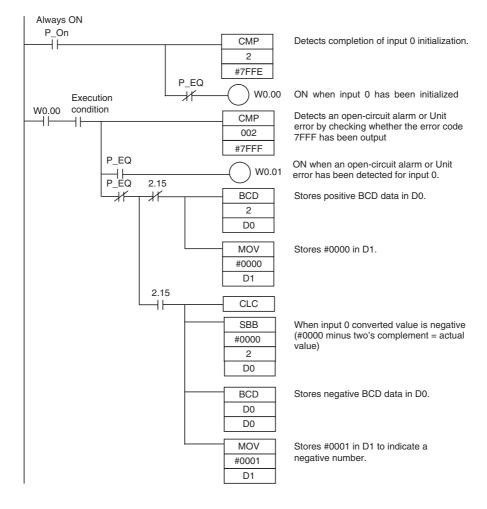


(b) The following programming example shows how to convert the data for temperature input 0 to BCD and store the result in D0 and D1. "#0001" is stored in D1 when the input data is a negative value. The following system configuration is used.

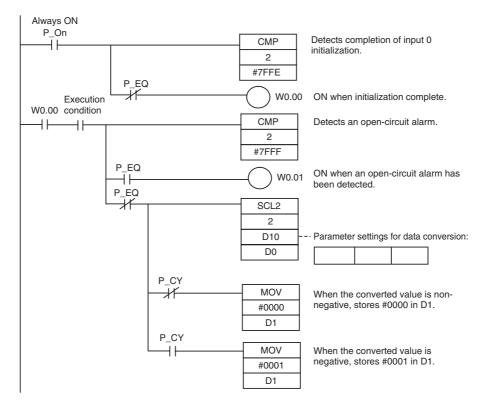


Temperature unit setting	0(°C)
Two-decimal-place Mode	0 (normal)
Input range setting	1 (Pt100: -200.0 to 650.0°C)
Input 0	CIO 2

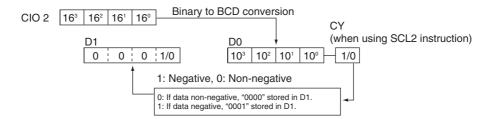
## (6) Programming with BCD Instruction



## (7) Programming with SCL2 Instruction



### Operation



#### 8-4-5 **Function Descriptions**

## **Two-decimal-place Mode**

If pin 2 on the DIP switch is turned ON, values are stored to two decimal places. In this case, temperature data is stored as 6-digit signed hexadecimal (binary) data with 4 digits in the integer portion and 2 digits after the decimal point. The actual data stored in memory is 100 times the actual value, i.e., the decimal point is not indicated. Methods for handling this data are described in this section.

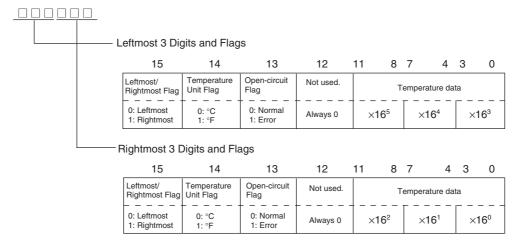


## **Additional Information**

When set to store values to two decimal places, temperature data as far as two digits after the decimal point is converted to 6-digit binary data, but the actual resolution is not 0.01°C (°F). For this reason, there may be skipping and inaccuracies in the first digit after the decimal point 0.1°C (°F). Treat any resolution above that specified for the normal data format as reference data.

## Temperature Data Partitioning and Structure

Temperature Data (Actual Temperature x 100 Binary)



Temperature Unit Flag: Open-circuit Flag:

Leftmost/Rightmost Flag: Indicates whether the leftmost or rightmost 3 digits are provided. Indicates whether the temperature is in °C or °F.

Turns ON (1) when an open-circuit is detected. The temperature data will be 7FF FFF if this flag is ON.

## Data Conversion Examples

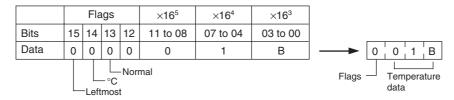
## Example 1

Temperature: 1,130.25°C

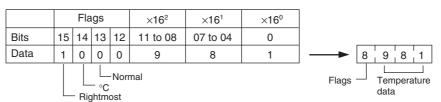
×100: 113025

Temperature Data: 01B981 (hexadecimal for 113025)

### **Leftmost 3 Digits and Flags**



### **Rightmost 3 Digits and Flags**



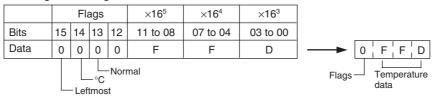
## **Example 2**

Temperature: -100.12°C

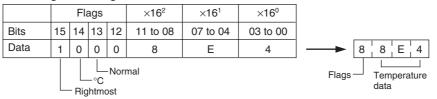
×100: -10012

Temperature Data: FFD8E4 (hexadecimal for -10012)

### Leftmost 3 Digits and Flags



### **Rightmost 3 Digits and Flags**



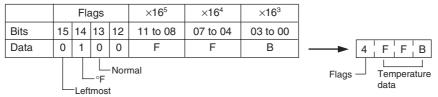
## Example 3

Temperature: -200.12°F

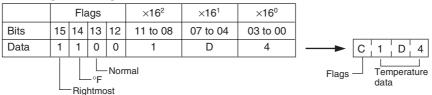
×100: -20012

Temperature Data: FFB1D4 (hexadecimal for -20012)

### Leftmost 3 Digits and Flags



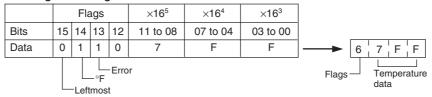
### **Rightmost 3 Digits and Flags**



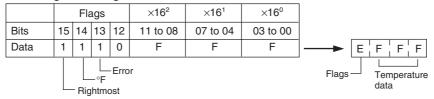
## Example 4

Temperature: Open circuit (°F) Temperature Data: 7FFFFF

#### **Leftmost 3 Digits and Flags**



#### **Rightmost 3 Digits and Flags**



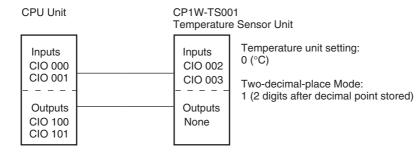


### **Additional Information**

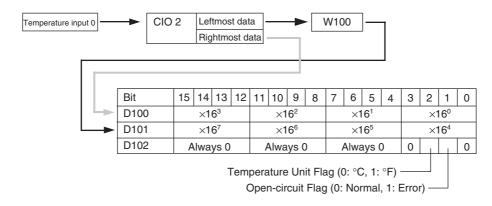
- Leftmost digits are stored in the lower memory addresses. Treat the data in the lower memory address as the leftmost digits when programming.
- Be sure that the data is read at least once every 125 ms to allow for the CPU Unit's cycle time and communications time. Correct data may not be obtained if the read cycle is greater than 125 ms.

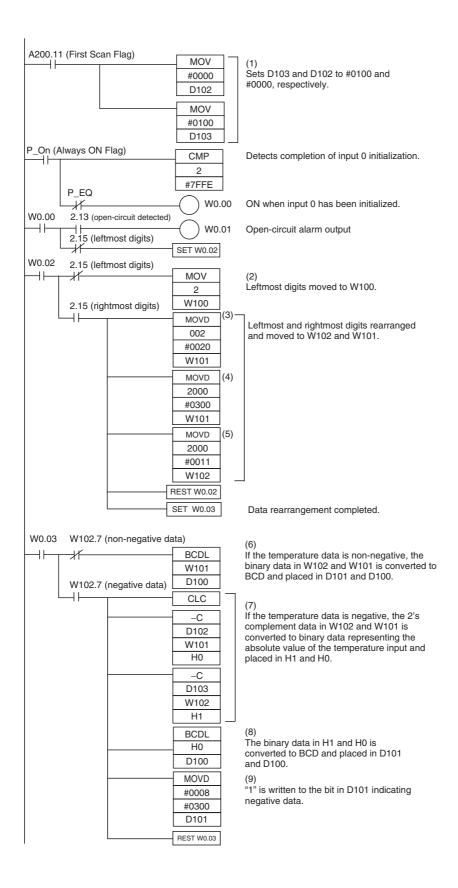
## Programming Example

The following programming example shows how to use 2-decimal-place Mode for the following PLC configuration.

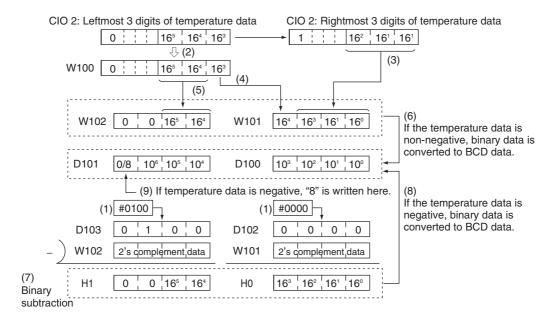


In this example, 100 times the temperature data for temperature input 0 (input to CIO 002) is stored in binary form in D100 to D102.





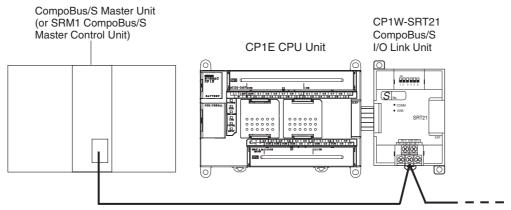
## **Description of Operation**



## CompoBus/S I/O Link Units 8-5

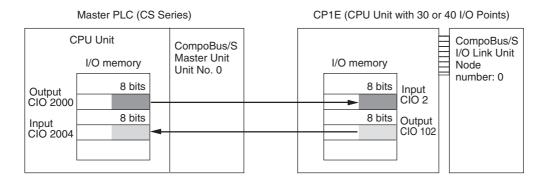
#### 8-5-1 **Overview**

The CP1E CPU Unit can function as a slave to a CompoBus/S Master Unit when a CP1W-SRT21 CompoBus/S I/O Link Unit is connected. The CompoBus/S I/O Link Unit establishes an I/O link of 8 inputs and 8 outputs between the Master Unit and the PLC.



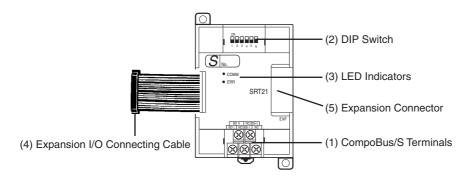
Special flat cable or VCTF cable

From the standpoint of the CP1E CPU Unit, the 8 input bits and 8 output bits allocated to the Compo-Bus/S I/O Link Unit are identical to input and output bits allocated to Expansion I/O Units even though the CompoBus/S I/O Link Unit does not control actual inputs and outputs, i.e., I/O is performed for I/O memory in the CPU Unit to which the CompoBus/S Master Unit is mounted.



#### 8-5-2 **Part Names and Functions**

CP1W-SRT21 CompoBus/S I/O Link Unit

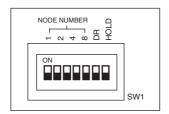


### (1)CompoBus/S Terminals

The following CompoBus/S terminals are provided: CompoBus/S communications data high/low terminals, NC terminals for communications power supply plus (+) and minus (-), and an NC terminal. (Power is supplied internally for this Unit, so the NC terminals for communications power supply can be used as relay terminals.)

### (2)DIP Switch

Used to specify the node number for the CompoBus/S I/O Link Unit.



Pin labels		Co	Contents				
1		Node Number		SV	V1		
2		Setting	8	4	2	1	
4		0	0	0	0	0	
8		1	0	0	0	1	
		2	0	0	1	0	
		3	0	0	1	1	
		4	0	1	0	0	
		5	0	1	0	1	
		6	0	1	1	0	
		7	0	1	1	1	
		8	1	0	0	0	
		9	1	0	0	1	
		10	1	0	1	0	
		11	1	0	1	1	
		12	1	1	0	0	
		13	1	1	0	1	
		14	1	1	1	0	
		15	1	1	1	1	
		1 = ON, 0 =	OF	F			
DR	ON	Long-distan	ce c	com	mur	nicat	ions mode *
	OFF	High-speed	con	nmu	nica	atior	is mode
HOLD	ON	Retain output	s af	er a	com	mur	nications error.
	OFF	Clear outputs	afte	er a c	omr	nuni	cations error.

<sup>\*</sup> The long-distance communications mode can be used only when one of the following Master Units is connected: C200HW-SRM21-V1, CQM1-SRM21-V1, or SRM1-C0□-V2.

## (3)LED Indicators

Used to show the CompoBus/S communications status.

Indicator	Name	Color	Meaning
COMM	Communications indicator	Yellow	ON: Communications in progress. OFF: Communications stopped or error has occurred.
ERR	Error indicator	Red	ON: A communications error has occurred. OFF: Indicates normal communications or stand-by.

### (4) Expansion I/O Connecting Cable

Connected to the expansion connector of a CP1E CPU Unit or an Expansion Unit or Expansion I/O Unit. The cable is provided with the CompoBus/S I/O Link Unit and cannot be removed.



### **Precautions for Safe Use**

Do not touch the cables during operation. Static electricity may cause operating errors.

### (5) Expansion Connector

Used to connect Expansion Units or Expansion I/O Units.

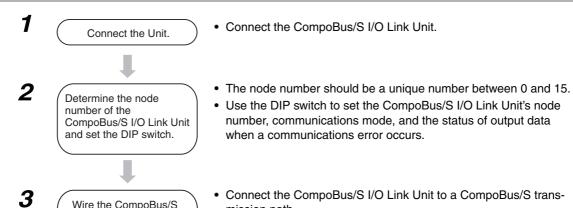
#### **Specifications** 8-5-3

Model	CP1W-SRT21		
Master/slave	CompoBus/S Slave		
Number of I/O points	8 input points, 8 output points		
Number of words allocated in CPU Unit I/O memory	1 input word, 1 output word		
Node number setting	Set using the DIP switch (Set before turning on the CPU Unit's power supply.)		

#### 8-5-4 **Flow of Operation**

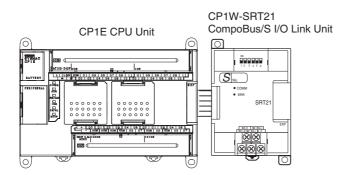
Wire the CompoBus/S

transmission path.



mission path.

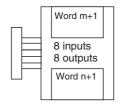
Connect the CompoBus/S I/O Link Unit to the CPU Unit.



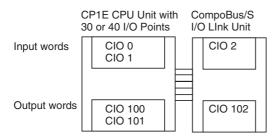
### I/O Words Allocation

I/O words are allocated to the CompoBus/S I/O Link Unit in the same way as to other Expansion Units and Expansion I/O Units, i.e., the next available input and output words are allocated. As shown below, when "m" is the last allocated input word and "n" is the last allocated output word, the CompoBus/S I/O Link Unit is allocated "m+1" as its input word and "n+1" as its output word.

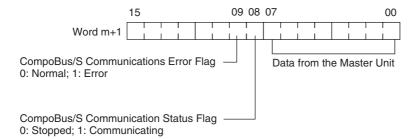
CompoBus/S I/O Link Unit



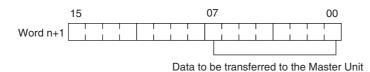
In the following example, a CompoBus/S I/O Link Unit is connected as the first Unit after the CP1E CPU Unit.



The input word (m+1) contains the data from the Master Unit and the CompoBus/S communications status.



Write the data to be transmitted to the Master Unit in the output word (n+1).





## **Precautions for Correct Use**

The 8 bits of I/O data are not always transmitted simultaneously.

- 8 bits of data transmitted from the Master CPU Unit at the same time will not always reach the CP1E CPU Unit.
- 8 bits of data transmitted from the CP1E CPU Unit at the same time will not always reach the Master CPU Unit simultaneously.

When the 8 bits of input data must be read together, modify the ladder program in the CPU Unit receiving the data. For example, read the input data twice in succession and accept the data only when the two values match.



## **Additional Information**

- Unused bits in the CompoBus/S I/O Link Unit's output words can be used as work bits.
- Unused bits in input word cannot be used as work bits.
- Determine the node number and make DIP switch settings.

### (1) Determining Node Number

- The CompoBus/S I/O Link Unit is a Slave Unit with 8 input bits and 8 output bits. The node number setting is made using the DIP switch; the inputs and outputs share the same node number.
- The range of possible node number settings is determined by the type of PLC the Master Unit is mounted to and the settings on the Master Unit. For details, refer to the CompoBus/S Operation Manual (Cat. No. W266).

## (2) Making DIP Switch Settings

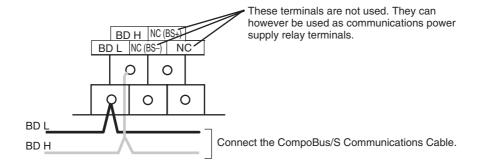
Use the DIP switch to set the CompoBus/S I/O Link Unit's node number, communications mode, and the status of output data when a communications error occurs.



### **Precautions for Correct Use**

Always turn OFF the power supply before changing the DIP switch settings.

Wire the CompoBus/S communications path.





# **Appendices**

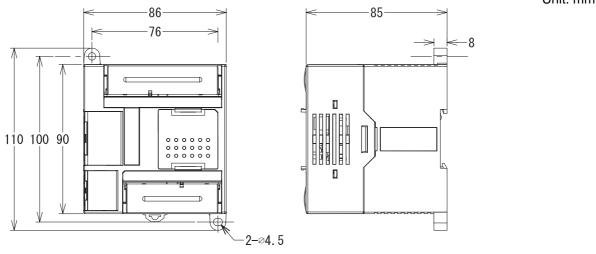
<b>A-1</b>	Dimen	sions	. A-2
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	A-1-2	Option Boards	A-3
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	A-2-4	Serial Communications	. A-23
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## **A-1** Dimensions

## A-1-1 CPU Units

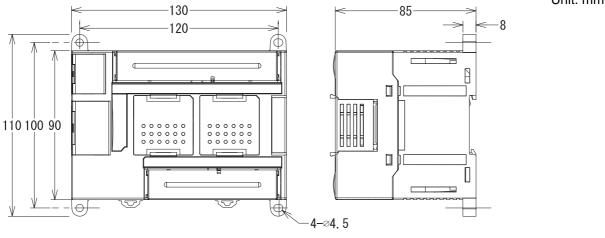
## CPU Units with 20 I/O Points (CP1E-□20D□□-□)

Unit: mm

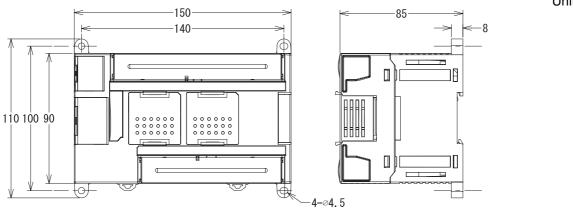


## CPU Units with 30 I/O Points (CP1E-□30D□□-□)

Unit: mm



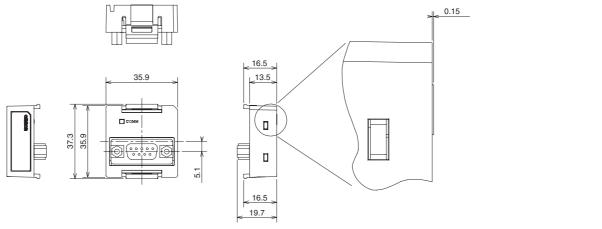
## CPU Units with 40 I/O Points (CP1E-□40D□□-□)



#### A-1-2 **Option Boards**

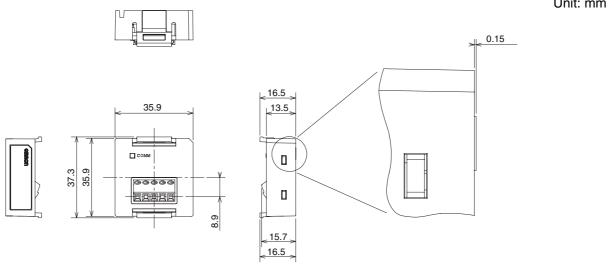
## CP1W-CIF01 RS-232C Option Board

Unit: mm

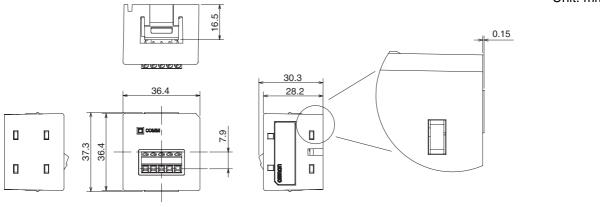


## CP1W-CIF11 RS-422A/485 Option Board

Unit: mm



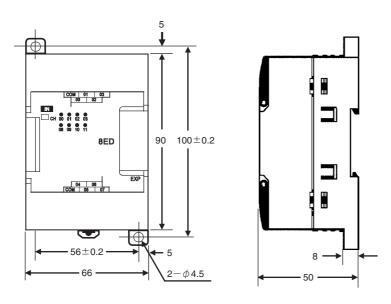
## CP1W-CIF12 RS-422A/485 Option Board



## A-1-3 Expansion I/O Units

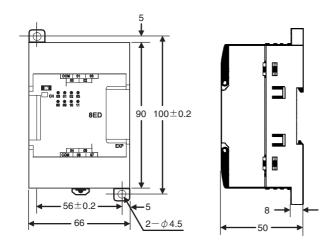
## CP1W-8ED Expansion I/O Unit with 8 Input Points

Unit: mm

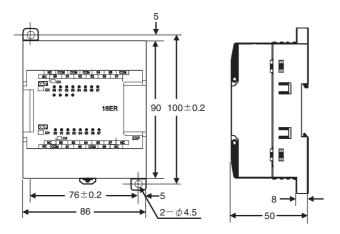


## CP1W-8E□ Expansion I/O Units with 8 Output Points

Unit: mm

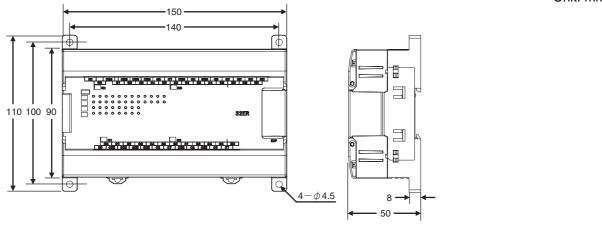


## CP1W-16E□□ Expansion I/O Units with 16 Output Points



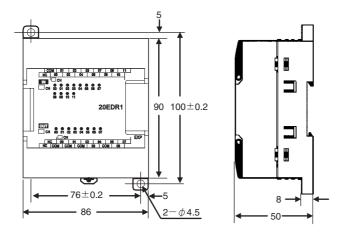
## CP1W-32ER/ET/ET1 Expansion I/O Units with 32 Output Points

Unit: mm

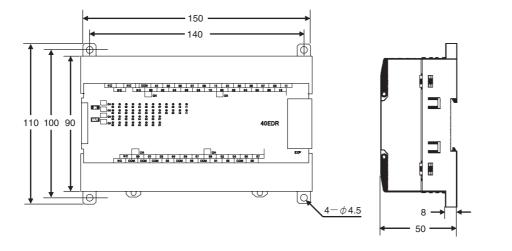


## CP1W-20ED□□ Expansion I/O Units with 20 I/O Points

Unit: mm



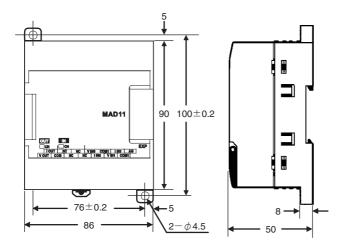
## **CP1W-40ED**□□ Expansion I/O Units with 40 I/O Points



## A-1-4 Expansion Units

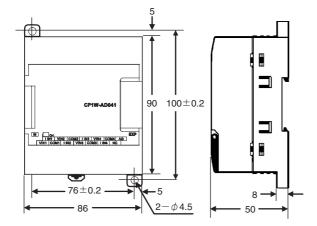
## CP1W-MAD11 Analog I/O Units

Unit: mm

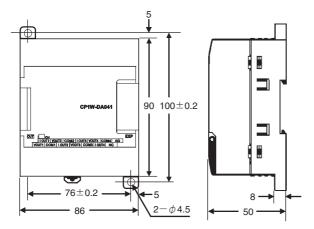


## **CP1W-AD041 Analog Input Unit**

Unit: mm

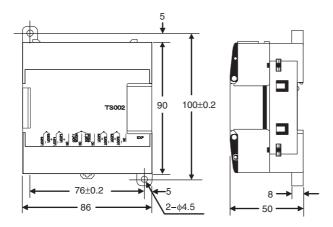


## **CP1W-DA041 Analog Output Unit**

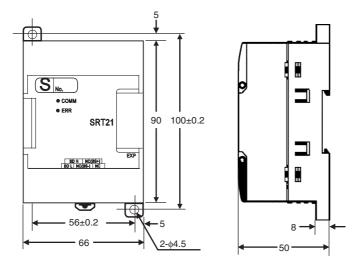


## **CP1W-TS**□□□ Temperature Sensor Units

Unit: mm



## CP1W-SRT21 CompoBus/S I/O Link Unit



## **A-2** Wiring Diagrams

## A-2-1 CPU Units

## **CPU Unit with 20 I/O Points**

## Input Wiring Diagram

## Output Wiring Diagram

## All Models

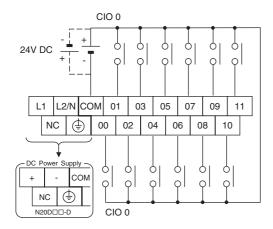
**AC Power Supply** 

CP1E-E20DR-A

CP1E-N20D□□-A

**DC Power Supply** 

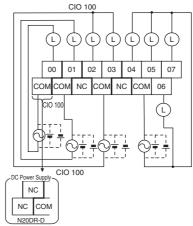
CP1E-N20D□□-D



## Relay Outputs

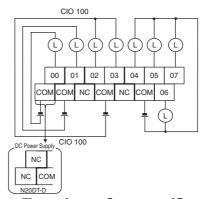
CP1E-E20DR-A

CP1E-N20DR-□



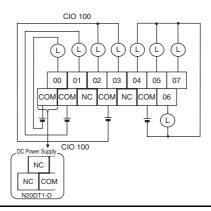
## Transistor Outputs (Sinking)

CP1E-N20DT-□



## Transistor Outputs (Sourcing)

CP1E-N20DT1-□



## **CPU Units with 30 I/O Points**

**Input Wiring Diagram** 

## All Models

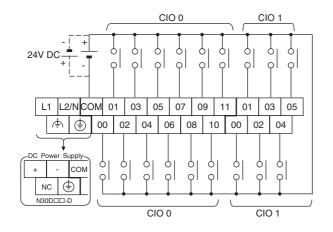
**AC Power Supply** 

CP1E-E30DR-A

CP1E-N30D□□-A

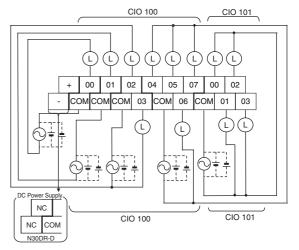
DC Power Supply

CP1E-N30D□□-D



## Relay Outputs

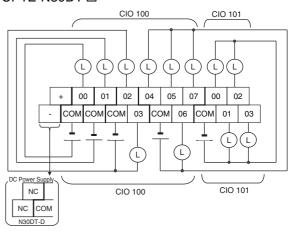
CP1E-□30DR-□



**Output Wiring Diagram** 

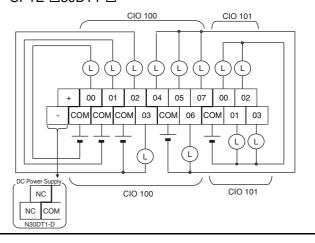
## Transistor Outputs (Sinking)

CP1E-N30DT-□

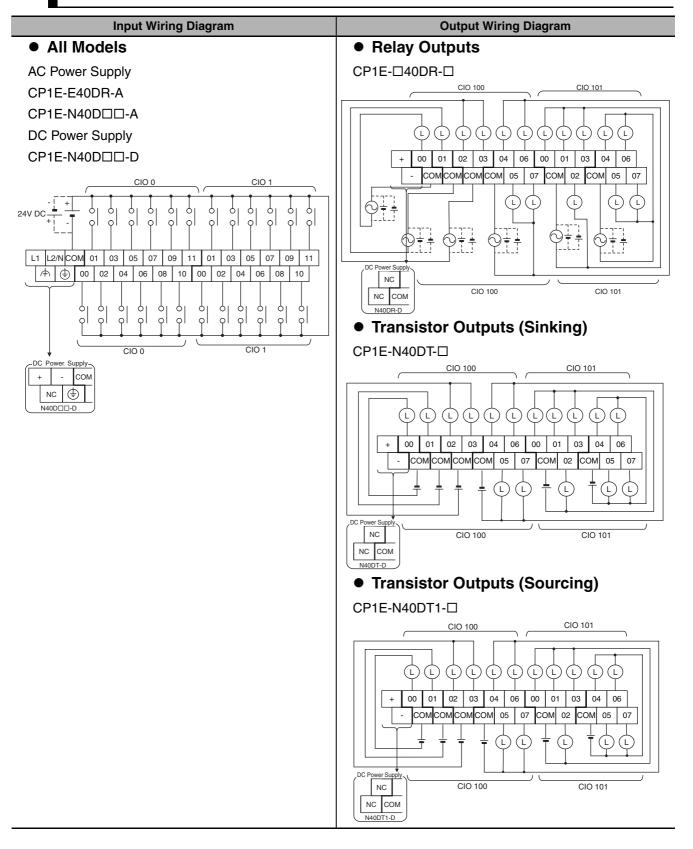


## Transistor Outputs (Sourcing)

CP1E-□30DT1-□



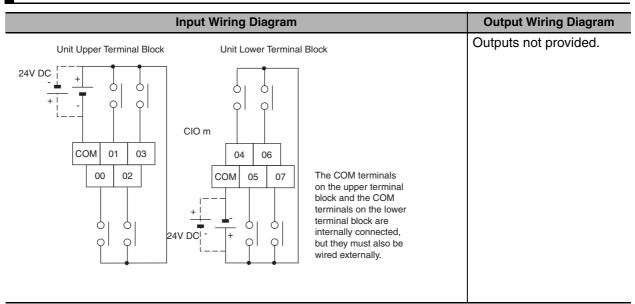
## **CPU Units with 40 I/O Points**



#### A-2-2 **Expansion I/O Units**

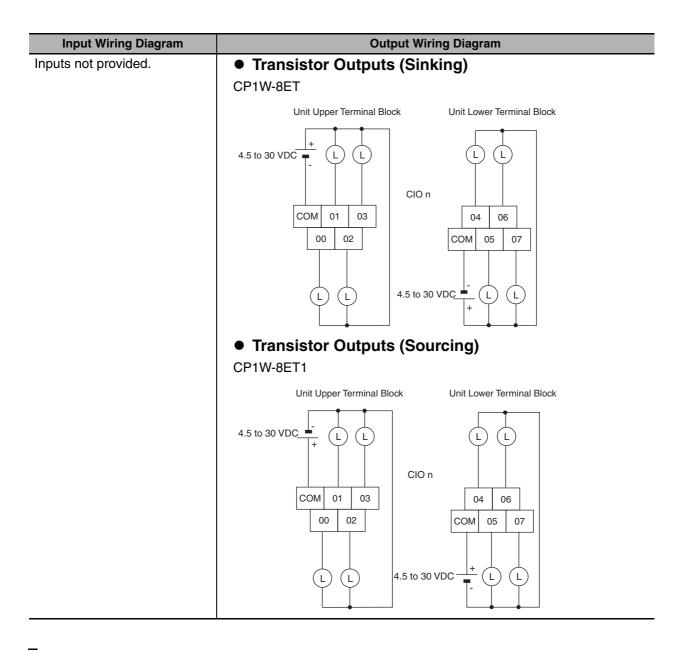
The first input word allocated to the Expansion I/O Unit is shown as CIO m and the first output word is shown as CIO n.

## **8-point Input Unit**

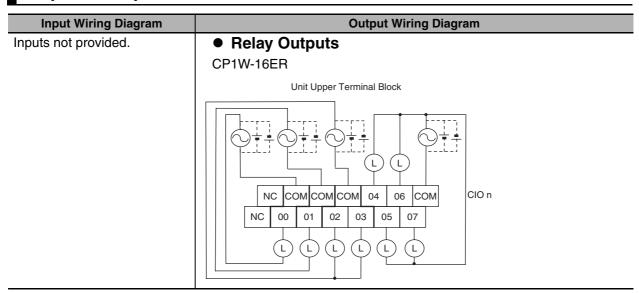


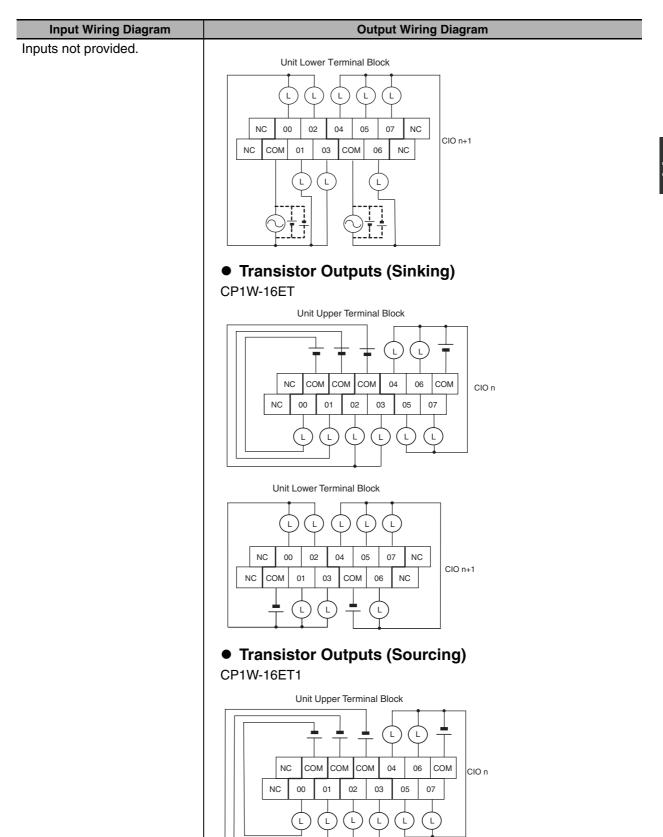
## 8-point Output Units

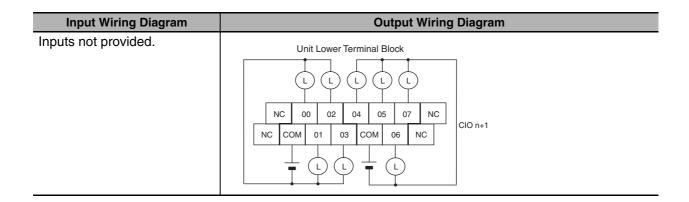
Input Wiring Diagram	Output Wiring Diagram
nputs not provided.	Relay Outputs  CP1W-8ER
	Unit Upper Terminal Block  24V DC  COM 01 03  O0 02  COM 05 07  24V DC  L  L  L  L  L  L  L  L  L  L  L  L  L



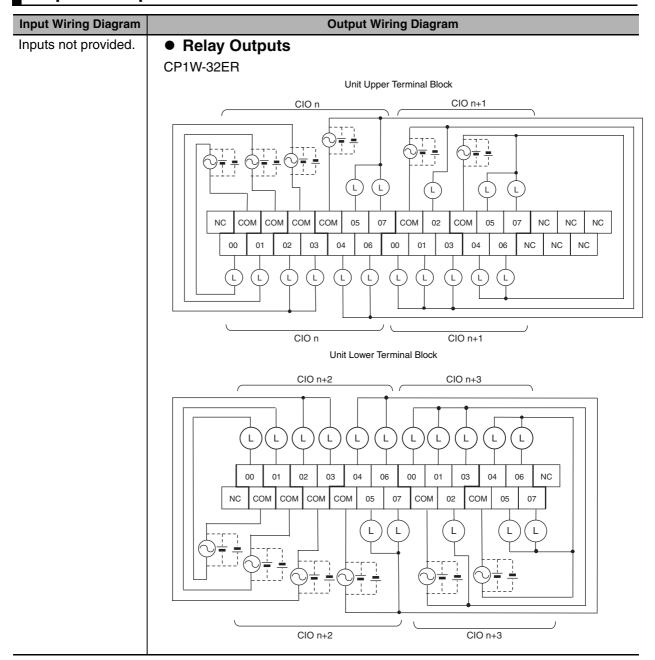
## **16-point Output Units**



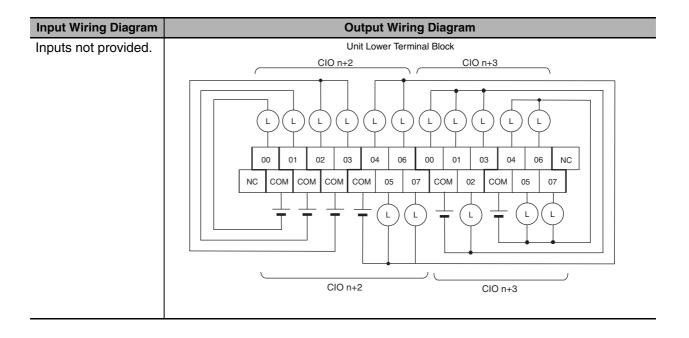




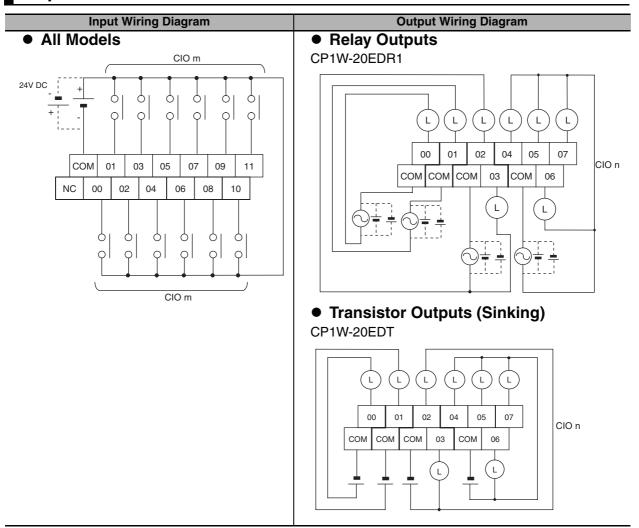
## 32-point Output Units

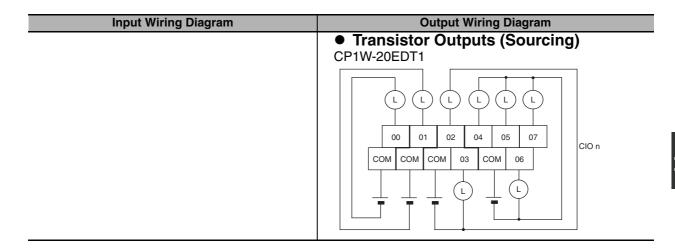


#### **Output Wiring Diagram Input Wiring Diagram** • Transistor Outputs (Sinking) Inputs not provided. CP1W-32ET Unit Upper Terminal Block CIO<sub>n</sub> CIO n+1 NC сом СОМ сом СОМ СОМ NC 00 01 02 03 06 00 01 03 04 NC (L) CIO n CIO n+1 Unit Lower Terminal Block CIO n+2 CIO n+3 L L L L L L 02 03 04 06 00 NC сом сом сом 05 07 СОМ 02 COM L L CIO n+2 CIO n+3 Transistor Outputs (Sourcing) CP1W-32ET1 Unit Upper Terminal Block CIO n CIO n+1 СОМ сом сом 05 02 СОМ 07 NC NC NC СОМ 07 СОМ 05 01 03 06 00 01 03 06 NC NC 00 04 04 (L)(L) ( L ) CIO n CIO n+1

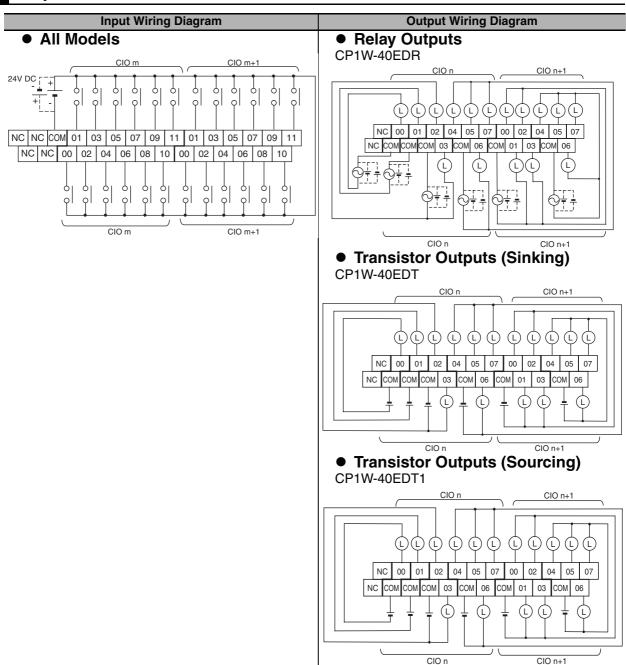


## 20-point I/O Units





## 40-point I/O Units

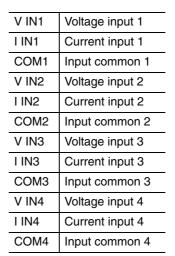


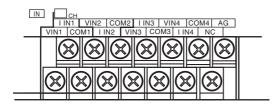
## A-2-3 Expansion Units

## **CP1W-AD041 Analog Input Unit**

#### **Wiring Diagrams**

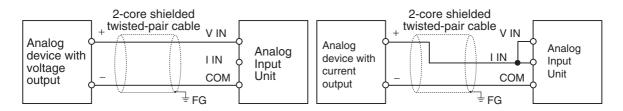
#### Input Terminal Arrangement



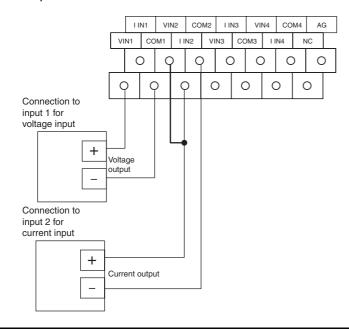


Note For current inputs, short V IN1 to I IN1, V IN2 to I IN2, V IN3 to I IN3, and V IN4 to I IN4.

### Wiring Methods



#### Example:



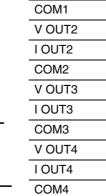
## CP1W-DA041 Analog Output Unit

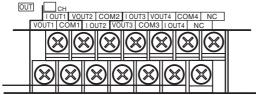
#### **Wiring Diagrams**

V OUT1

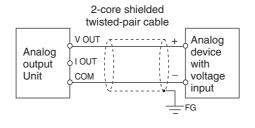
I OUT1

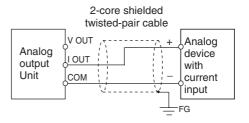
### Output Terminal Arrangement





### Wiring Methods





Voltage output 1

Current output 1

Output common 1

Voltage output 2

Current output 2

Voltage output 3

Current output 3

Voltage output 4

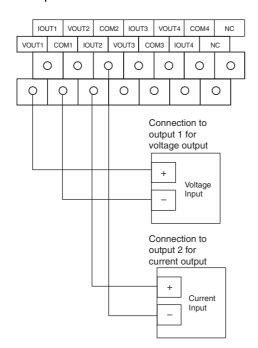
Current output 4

Output common 4

Output common 3

Output common 2

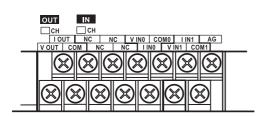
#### Example:



## CP1W-MAD11 Analog I/O Unit

#### **Wiring Diagrams**

### • I/O Terminal Arrangement

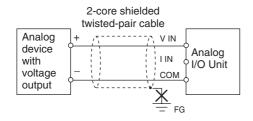


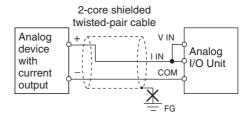
V OUT	Voltage output
I OUT	Current output
COM	Output common
V INO	Voltage input 0
I INO	Current input 0
COM0	Input common 0
V IN1	Voltage input 1
I IN1	Current input 1
COM1	Input common 1

Note For current inputs, short V IN0 to I IN0 and V IN1 to I IN1.

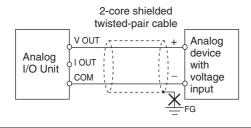
### Wiring Methods

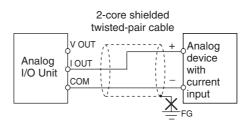
Wiring Analog Inputs





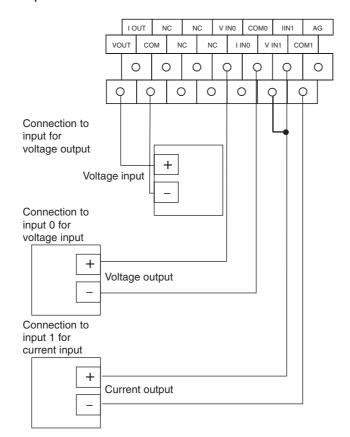
• Wiring Analog Outputs





#### **Wiring Diagrams**

#### Example:



## CP1W-TS001/TS002/TS101/TS102 Temperature Sensor Units

#### **Wiring Diagrams**

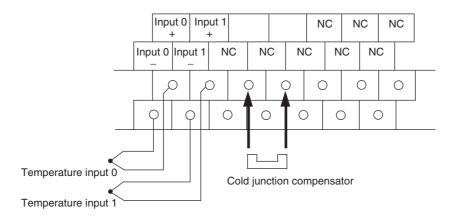
### Connecting a Thermocouple

• CP1W-TS001

One or two K or J thermocouples can be connected to the CP1W-TS001.

Both of the thermocouples must be of the same type and the same input range must be used for each.

Example:



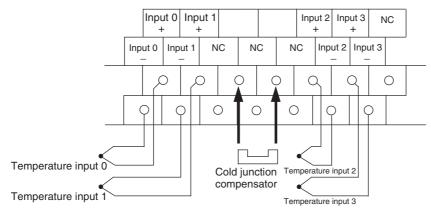
#### **Wiring Diagrams**

#### CP1W-TS002

One to four K or J thermocouples can be connected to the CP1W-TS002.

All of the thermocouples must be of the same type and the same input range must be used for each.

#### Example:

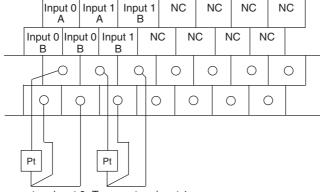


### Connecting a Platinum Resistance Thermometer

#### CP1W-TS101

One or two Pt or JPt platinum resistance thermometers can be connected to the CP1W-TS101. Both of the thermometers must be of the same type and the same input range must be used for each.

#### Example:

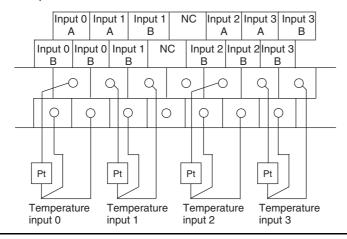


Temperature input 0 Temperature input 1

#### • CP1W-TS102

One to four Pt or JPt platinum resistance thermometers can be connected to the CP1W-TS102. All of the thermometers must be of the same type and the same input range must be used for each.

#### Example:



## CP1W-SRT21 CompoBus/S I/O Link Unit

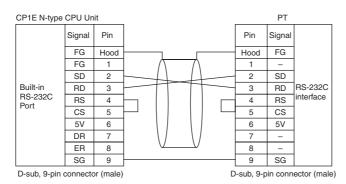
#### Wiring Diagrams These terminals are not used. They can however be used as communications power BD H NC (BS+) supply relay terminals. BD L NC (BS-) NC 0 0 0 BD L Connect the CompoBus/S Communications Cable. BD H

#### **Serial Communications** A-2-4

## Wiring Examples for PTs Using NT Link

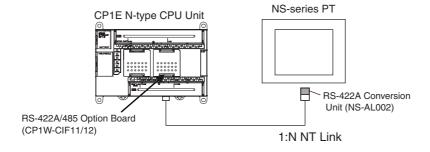
- Connecting a PT and a PLC 1:1 with RS-232C Ports
  - Communications Mode: 1:N NT Link, N = 1 only
  - OMRON Cables with Connectors: XW2Z-200T (2 m)

XW2Z-500T (5 m)

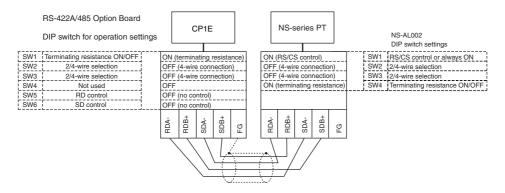


### Connecting a PT and a PLC with 1:N NT Link and RS-422A/485 Ports Using 4-wire, RS-422A Communications

Communications mode: 1:N NT Link, N = 1 only



### Wiring Example

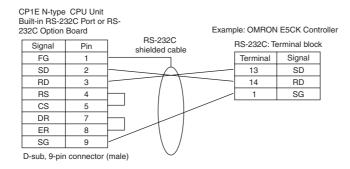


## No-protocol Communications

#### Connecting RS-232C Ports 1:1

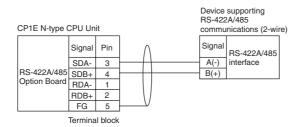
• Communications Mode: No-protocol

Example: Connections to E5CK Controller



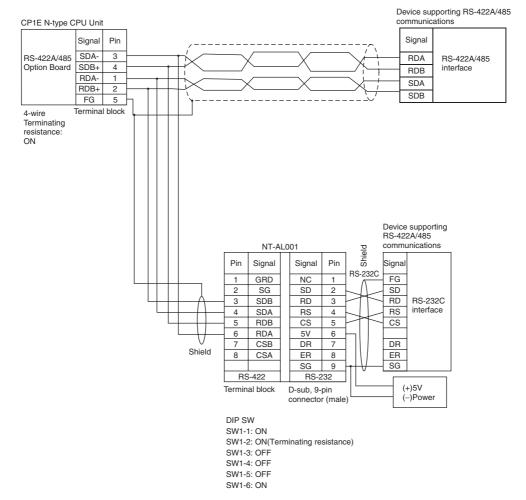
### Connecting RS-422A/485 Ports 1:1 with 2-wire Connections

• Communications Mode: No-protocol



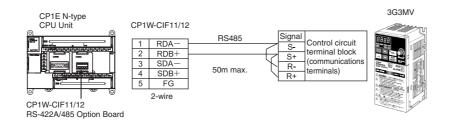
### Connecting RS-422A/485 Ports 1:1 with 4-wire Connections

• Communications Mode: No-protocol



## **Modbus-RTU Easy Master Function**

• Communications mode: Modbus-RTU Easy Master

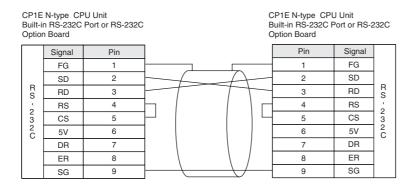


### Serial PLC Links

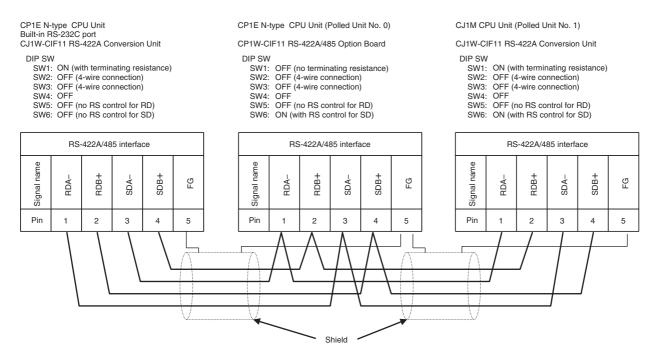
• Communications mode: Serial PLC Link (Master) or Serial PLC Link (Slave)

#### Connection with RS-232C Ports

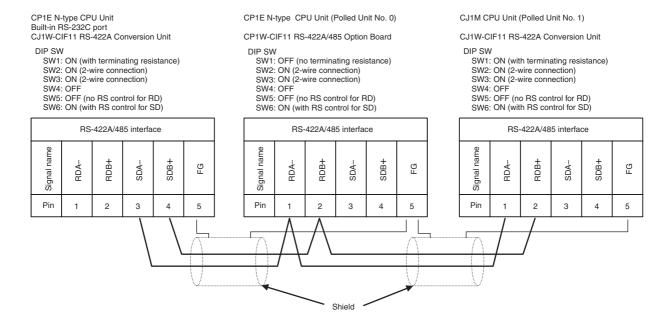
RS-232C connection is also possible when using a Serial PLC Link to connect two CP1E N-type CPU Units.



• Wiring Example Using RS-422A/485 Ports with RS-422A, 4-wire Connections



### • Wiring Example Using RS-422A/485 Ports with RS-485, 2-wire Connections



# A-3 Wiring for Serial Communications

## A-3-1 Recommended RS-232C Wiring

## **Recommended RS-232C Wiring**

We recommend the following wiring method for the RS-232C, especially in environments prone to noise

- 1 Use shielded twisted-pair cables for the communications cables.
  - Recommended RS-232C Cables

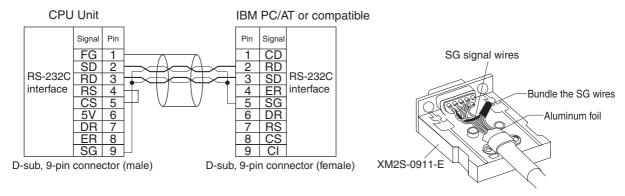
Model numbers	Manufacturer
UL2464 AWG28x5P IFS-RVV-SB (UL product)	Fujikura Ltd.
AWG28x5P IFVV-SB (non-UL product)	
UL2464-SB (MA) 5Px28AWG (7/0.127) (UL product)	Hitachi Cable,
CO-MA-VV-SB 5Px28AWG (7/0.127) (non-UL product)	Ltd.

- 2 Combine a signal wire and SG (signal ground) wire in a twisted-pair cable.
  At the same time, bundle the SG wires at the connectors on Option Board and the remote device.
- **3** Connect the shield of the communications cable to the hood (FG) of the RS-232C connector on the Option Board.

At the same time, ground the ground terminal (GR) of the CPU Unit to 100  $\Omega$  or less.

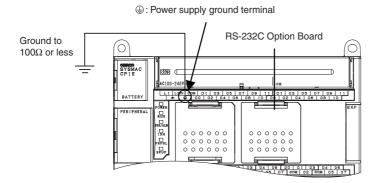
#### Connection Example

Example: Twisted-pair Cable Connecting SD-SG, and RD-SG Terminals in Host Link Mode



Note The hood (FG) is internally connected to the ground terminal (GR) on the CPU Unit.

Therefore, the FG is grounded by grounding the power supply ground terminal (GR). Although there is conductivity between the hood (FG) and pin 1 (FG), connect the shield to both the hood and pin 1 to reduce the contact resistance between the shield and FG and thus provide better noise resistance.



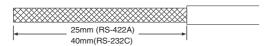
## **Wiring Connectors**

Use the following steps to wire connectors.

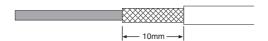
See the following diagrams for the length of the cable portion to be cut in each step.

### Shield Connected to Hood (FG)

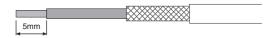
- 1 Cut the cable to the required length.
- **2** Remove the specified length of the sheath from the cable using a knife. Be careful not to scratch the braided shield.



**3** Trim off the braided shield using scissors.



4 Remove the insulation from each conductor using a stripper.



**5** Fold back the braided shield.

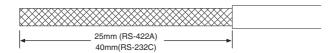


**6** Wrap aluminum foil tape around the folded shield.



### Shield Not Connected to Hood (FG)

- **1** Cut the cable to the required length.
- 2 Remove the specified length of the sheath from the cable using a knife. Be careful not to scratch the braided shield.



 $oldsymbol{3}$  Trim off all the braided shield using scissors.



4 Remove the insulation from each conductor using a stripper.

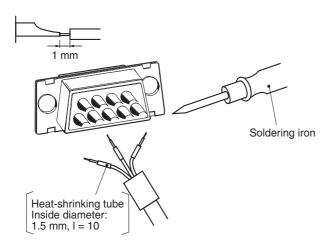


**5** Wrap adhesive tape around the conductor from which the braided shield was removed.

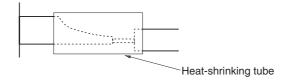


### Soldering

- **1** Place a heat-shrinking tube on each conductor.
- **2** Temporarily solder each conductor to the corresponding connector terminals.
- **3** Completely solder each conductor.

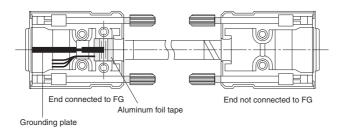


4 Return the heat-shrinking tube to the soldered portion, then heat the tube to shrink it in place.



### Assembling Connector Hood

Assemble the connector hood as shown below.



## A-3-2 Recommended RS-422A/485 Wiring

Use the following wiring methods for RS-422A/485 to maintain transmission quality.

- **1** Always use shielded twisted-pair cables as communications cables.
  - Recommended RS-422A/485 Cables

Model numbers	Manufacturer
CO-HC-ESV-3P×7/0.2	Hirakawa Hewtech Corp.

Connect the shield of the communications cable to the FG terminal on the RS-422A/485 Option Board.

At the same time, ground the ground terminal (GR) of the CPU Unit to 100  $\Omega$  or less.



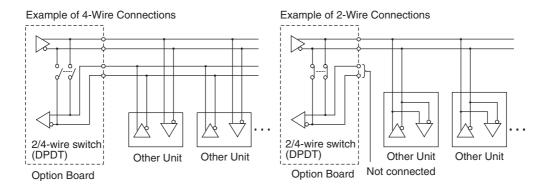
#### **Precautions for Correct Use**

Always ground the shield only at the RS-422A/485 Option Board end. Grounding both ends of the shield may damage the device due to the potential difference between the ground terminals.

#### Connection Examples

#### 2-Wire and 4-Wire Transmission Circuits

The transmission circuits for 2-wire and 4-wire connections are different, as shown in the following diagram.



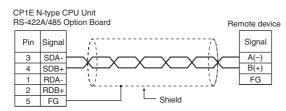


### **Precautions for Correct Use**

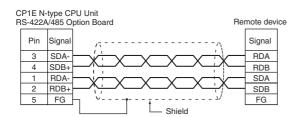
Use the same type of transmission circuit (2-wire or 4-wire) for all nodes. Do not use 4-wire connections when the 2/4-wire switch on the Board is set to 2-wire.

#### Wiring Example: 1:1 Connections

• Two-wire Connections



· Four-wire Connections



## A-3-3 Converting the Built-in RS-232C Port to RS-422A/485

Use one of the following Conversion Units to convert a built-in RS-232C port to an RS-422A port for a CP1E N-type CPU Unit.

- CJ1W-CIF11 RS-422A Conversion Unit Maximum distance: 50 m, convertible to RS-422A or RS-485.
- NT-AL001 RS-232C/RS-422A Conversion Unit: Maximum distance: 500 m, convertible to RS-422A only.

### CJ1W-CIF11 RS-422A Conversion Unit

The CJ1W-CIF11 RS-422A Conversion Unit is used to convert an RS-232C port to RS-422A/485. It is directly connected to the built-in RS-232C port of the CP1E N-type CPU Unit.

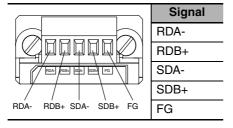
The Conversion Unit is not insulated, so the maximum distance for RS-422A/485 is 50 m.

#### Appearance



## Electrical Specifications

• RS-422A/485 Terminal Block



#### RS-232C Connector

RS-232C port	Connector pin	Pin	Signal
al	arrangement	1	FG
+5V 6 ——	O 1 FG O 2 RD	2	RD
-7 — O -8 — O	0 3 SD	3	SD
SG(0V) 9 0 4 C	0 1 100	4	CS
	3113	5	RS
		6	+5V
		7,8	NC
		9	SG(0V)
		Hood	NC*

<sup>\*</sup> The hood and the connector hood to which it is connected will have the same electrical potential.

### DIP Switch for Operation Settings

Pin	Setting	ON	OFF
1	Terminating resistance selection	Terminating resistance connected (both ends of transmission path)	Terminating resistance not connected
2	2-wire or 4-wire selection*1	2-wire connections	4-wire connections
3	2-wire or 4-wire selection*1	2-wire connections	4-wire connections
4	Not used.	-	-
5	RS control selection for RD*2	RS control enabled	RS control disabled (Data always received.)
6	RS control selection for SD*3	RS control enabled	RS control disabled (Data always sent.)

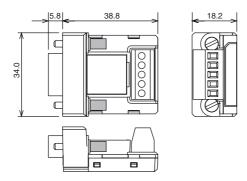
<sup>\*1</sup> Set both pins 2 and 3 to either ON (2-wire) or OFF (4-wire).

<sup>\*2</sup> To disable the echo-back function, set pin 5 to ON (RS control enabled).

<sup>\*3</sup> When connecting to a device on the N side in a 1: N connection with the 4-wire method, set pin 6 to ON (RS control enabled).

Also, when using 2-wire connections, set pin 6 to ON (RS control enabled).

#### Dimensions



## NT-AL001 RS-232C/RS-422A Conversion Unit

The NT-AL001 RS-232C/RS-422A Conversion Unit is used to connect a device with RS-232C terminals to a device with RS-422A terminals.

A cable is used to connect the built-in RS-232C port of the CP1E N-type CPU Unit.

The Conversion Unit is insulated, so the maximum distance for RS-422A is 500 m.

#### Appearance



### DIP Switch Setting

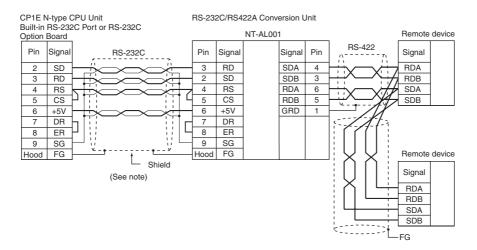
The NT-AL001 RS-232C/RS-422A Conversion Unit has a DIP switch for setting RS-422A/485 communications conditions.

When connecting the Serial Communications Option Board, refer to the DIP switch settings shown in the following table.

Pin	Function	Factory setting
1	Not used. (Leave set to ON.)	ON
2	Built-in terminating resistance setting	ON
	ON: Connects terminating resistance, OFF: Disconnects terminating resistance	
3	2/4-wire setting	OFF
4	2-wire: Set both pins to ON, 4-wire: Set both pins to OFF	OFF
5	Transmission mode setting*	ON
6	Constant transmission: Set both pins to OFF. Transmission performed when CS signal in RS-232C interface is at high level: Set pin 5 to OFF and pin 6 to ON. Transmission performed when CS signal in RS-232C interface is at low level: Set pin 5 to ON and pin 6 to OFF.	OFF

<sup>\*</sup> When connecting to a CP-series CPU Unit, turn OFF pin 5 and turn ON pin 6.

### Application Example

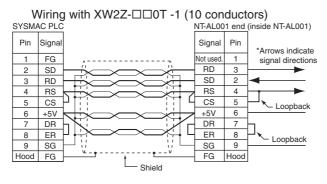


Note The following cables can be used for this connection.

It is recommended that one of these cables be used to connect the RS-232C port on the Option Board to the NT-AL001 RS-232C/RS-422 Conversion Unit.

Length	Model numbers
70cm	XW2Z-070T-1
2m	XW2Z-200T-1

### Wiring for the Recommended Cables (XW2Z-070T-1 or XW2Z-200T-1)



**Note** The hood (FG) is internally connected to the ground terminal (GR) on the CPU Unit. Therefore, FG is grounded by grounding the ground terminal (GR) on the power supply terminal block.



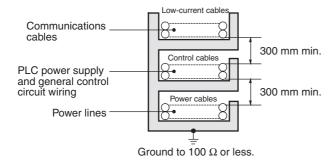
#### **Precautions for Correct Use**

- The XW2Z-□□0T-1 Connecting Cables for the NT-AL001 Link Adapter uses special wiring for the DS and RS signals.
  - Do not use these signals with other devices.
  - Connecting this cable to other devices can damage them.
- Always turn ON the terminating resistance if the node is at the end of the RS-422A/485 transmission path.

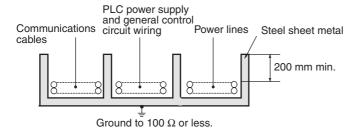
### A-3-4 Reducing Electrical Noise for External Wiring

Observe the following precautions when wiring communications cables.

- When multi-conductor signal cable is being used, avoid combining I/O wires and other control wires in the same cable.
- If wiring racks are parallel, allow at least 300 mm between them.



• If the I/O wiring and power cables must be placed in the same duct, they must be shielded from each other using grounded steel sheet metal.



## **A-4 Expansion Specifications of External Power Supply**

When using the external power supply for AC-power-supply CPU Units, the external power supply for the AC-power-supply CPU Units with 30 or 40 I/O Points (CP1E-DDDDD-A) can be used beyond 300mA within the capacity range of the power supply built in the CPU Units.

Calculate the usable capacity of external power supply according to the following example.

#### Calculation Example of the Capacity Limit of External Power Supply

#### • Example 1

	CPU Unit	Expansion (I/O) Units				
	CPO OIIII	1st unit	2nd unit	3rd unit	Total	Limit
	CP1E-N40DR-A	CP1W-DA041	CP1W-DA041	CP1W-DA041		
5V	0.21A	0.08A	0.08A	0.08A	0.45A	≤1.2A
24V	0.09A	0.124A	0.124A	0.124A	0.462A	≤0.7A
Power consumption	5V×0.45A=2.25W 24V×0.462A=11.08	38W		Total: 13.338W	≤18.5W	
Usable capacity of external power supply	18.5W(Total of usa 5.162W/24V=0.215	•	mption)–13.338V	V=5.162W	0.215A	≤0.7A

### • Example 2

	CPU Unit	Expansion (I/O) Units				
	CPO OIIII	1st unit	2nd unit	3rd unit	Total	Limit
	CP1E-N40DR-A	CP1W-20EDT	None	None		
5V	0.21A	0.130A	0.0A	0.0A	0.34A	≤1.2A
24V	0.09A	0.0A	0.0A	0.0A	0.09A	≤0.7A
Power consumption	5V×0.34A=1.70W 24V×0.09A=2.16W					≤18.5W
Usable capacity of external power supply	18.5W(Total of usa 14.64W/24V=0.610	•	mption)–3.86W=	14.64W	0.610A	≤0.7A

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