## CompoBus/S

## DATASHEETS

Connections to a Wider Range of Slaves Ensured by Upgraded Models


Note: 1. In high-speed communications mode, the maximum transmission distance is 100 m at a baud rate of 750 kbps . In long-distance communications mode (i.e., a newly available mode), the maximum transmission distance is 500 m at a baud rate of 93.75 kbps .
2. The SRT2-AD04 and SRT2-DA02 are available for 16 -bit synchronous communications.

## OmROn

## Master Control Unit

## Subminiature, Stand-alone Model with

## CompoBus/S Master and SYSMAC

Controller Functions

- Maximum number of Remote I/O points per Master: 256
- Maximum number of Slaves per Master: 32

■ Communications cycle time: 0.5 ms max. (at baud rate 750 kbps ).
■ Communications distance: Extended to 500 m max. (at baud rate 93.75 kbps ).

■ Additional instructions (PID, SCL, NEG, ZCP) ensure analog compatibility.


■ RS-232C port incorporated (SRM1-C02-V2).

## Ordering Information

| Specifications |  | Model |
| :--- | :--- | :--- |
| Built-in stand-alone controller functions | Without RS-232C | SRM1-C01-V2 |
|  | With RS-232C | SRM1-C02-V2 |

## Specifications

## - Master Specifications

| Number of I/O points | 256 points (128 inputs/128 outputs) <br> 128 points (64 inputs/64 outputs) <br> Selectable by DM setting. The default setting is 256 points. |
| :--- | :--- |
| Max. number of Slaves per Master | 256 points: 32 <br> 128 points: 16 |
| I/O words | Input words: 000 to 007 <br> Output words: 010 to 017 |
| Programming language | Ladder diagram |
| Types of instruction | 14 basic and 72 special instructions (123 instructions in total) |
| Execution time | LD instruction: <br> MOV instruction: $\quad 9.1 ~$ <br> $\mu \mathrm{~s}$ |
| Program capacity | 4,096 words |
| Data memory | $2,048+512$ (read-only) words |
| Timers/Counters | 128 timers/counters |
| Work bits | 640 bits |
| Memory backup | Flash memory (without battery): User programs <br> Super capacitor: Data memory (backed up for 20 days at an ambient temperature of 25 |
| Peripheral port | 1 point |
| RS-232C port | 1 point (SRM1-C02-V1 only) <br> Host Link, NT Link, 1:1 Link, or no protocol |
| Programming tool | Programming Consoles: CQM1-PRO01-E, C200H-PRO27-E <br> SYSMAC-CPT: WS01-CPTB1-E (CD-ROM/FD) <br> SYSMAC Support Software (MS-DOS version): C500-ZL3AT1-E |

Note: PID, SCL, NEG, and ZCP instructions are not supported by the SYSMAC-CPT.

## ■ Communications Specifications



Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The communications baud rate is switched using DM settings (default setting is $750,000 \mathrm{bps}$ ).

## - General Specifications

| Supply voltage | 24 VDC |
| :--- | :--- |
| Allowable supply voltage | 20.4 to 26.4 VDC |
| Power consumption | 3.5 W max. |
| Inrush current | 12.0 A max. |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $57 \mathrm{~Hz}, 0.075-\mathrm{mm}$ amplitude, 57 to 150 Hz, acceleration: $9.8 \mathrm{~m} / \mathrm{s}^{2}$ in $\mathrm{X}, \mathrm{Y}$, and Z <br> directions for 80 minutes each <br> (Time coefficient; 8 minutes $\times$ coefficient factor 10 = total time 80 minutes) |
| Shock resistance | $147 \mathrm{~m} / \mathrm{s}^{2}$ three times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ <br> Storage: $-20^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$ |
| Humidity | $10 \%$ to $90 \%$ (with no condensation) |
| Atmosphere | Must be free from corrosive gas. |
| Terminal screw size | M 3 |
| Power interrupt time | DC type: 2 ms min. |
| Weight | $150 \mathrm{~g} \mathrm{max}$. |

Nomenclature

SRM1-C01-V2


## Dimensions

Note: All units are in millimeters unless otherwise indicated.

## SRM1-C01/C02-V2



The above dimensions apply to the SRM1-C02-V2. The SRM-C01-V2 has no RS-232C port.

## OmROn

## Master Unit

## Master Unit for CS1, C200HX, C200HG, C200HE, and C200HS

- A maximum of 256 I/O points available.
- Connects to a maximum of 32 Slaves.

■ Communications cycle time: 0.5 ms max. (at baud rate 750 kbps ).
■ Communications distance: Extended to 500 m max. (at baud rate 93.75 kbps ).
■ Connection to Analog Terminals now supported.


## Ordering Information

| PC | Max. number of I/O points | Model |
| :--- | :--- | :--- |
| C200HX (-Z), C200HG (-Z), C200HE (-Z), <br> C200HS, CS1 | 256 points (128 inputs/128 outputs) | C200HW-SRM21-V1 |

## Specifications

## ■ Communications Specifications

| Communications method |  | CompoBus/S protocol |
| :---: | :---: | :---: |
| Coding method |  | Manchester coding method |
| Connection method |  | Multi-drop method and T-branch method (see note 1) |
| Communications baud rate |  | 750,000 bps, 93,750 bps (see note 2) |
| Communications cycle time | High-speed communications mode | 0.5 ms with 8 Slaves for inputs and 8 Slaves for outputs |
|  |  | 0.8 ms with 16 Slaves for inputs and 16 Slaves for outputs |
|  | Long-distance communications mode | 4.0 ms with 8 Slaves for inputs and 8 Slaves for outputs |
|  |  | 6.0 ms with 16 Slaves for inputs and 16 Slaves for outputs |
| Communications cable |  | 2-conductor VCTF cable ( $0.75 \times 20$ ) Dedicated flat cable |
| Communications distance | High-speed communications mode |  |
|  | Long-distance communications mode | VCTF cable:  <br> Main line length: 500 m max. <br> Branch line length: 6 m max. <br> Total branch line length: 120 m max. |
| Max. number of connecting nodes |  | 32 |
| Error control checks |  | Manchester code check, frame length check, and parity check |

Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The communications baud rate is switched with the DIP switch.

Unit Specifications

| Current consumption | 150 mA max. at 5 VDC |
| :--- | :--- |
| Number of I/O points | 256 points (128 inputs/128 outputs), 128 points (64 inputs/64 outputs) (switchable) |
| Number of occupied words | 256 points: 20 words (8 input words/8 output words, 4 status data) |
|  | 128 points: 10 words (4 input words/4 output words, 2 status data) |

Note: These flags use the AR area.

- Ratings

The ratings of the Unit are the same as those of the CS1, C200HX, C200HG, C200HE, and C200HS.

## Nomenclature



## Dimensions

Note: All units are in millimeters unless otherwise indicated.


## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.

## OmROn

## Master Unit

## Master Unit for CQM1

- A maximum of $128 \mathrm{I} / \mathrm{O}$ points available (Possible to set 32 , 64 , or 128 I/O points).
- Connects to a maximum of $16 / 32$ Slaves.
- Communications cycle time: 0.5 ms max. (at baud rate 750 kbps ).
- Communications distance: Extended to 500 m max. (at baud rate 93.75 kbps ).
■ Connection to Analog Terminals now supported.



## Ordering Information

| PC | Max. number of I/O points | Model |
| :---: | :---: | :---: |
| CQM1-series PC | 128 points (64 inputs/64 outputs) | CQM1-SRM21-V1 |

## Specifications

## - Communications Specifications

| Communications method |  | CompoBus/S protocol |
| :---: | :---: | :---: |
| Coding method |  | Manchester coding method |
| Connection method |  | Multi-drop method and T-branch method (see note 1) |
| Communications baud rate |  | $750,000 \mathrm{bps}, 93,750 \mathrm{bps}$ (see note 2) |
| Communications cycle time | High-speed communications mode | 0.5 ms with 8 Slaves for inputs and 8 Slaves for outputs |
|  |  | 0.8 ms with 16 Slaves for inputs and 16 Slaves for outputs |
|  | Long-distance communications mode | 4.0 ms with 8 Slaves for inputs and 8 Slaves for outputs |
|  |  | 6.0 ms with 16 Slaves for inputs and 16 Slaves for outputs |
| Communications cable |  | 2-conductor VCTF cable ( $0.75 \times 20$ ) Dedicated flat cable |
| Communications distance | High-speed communications mode | VCTF cable: <br> Main line length: $\quad 100 \mathrm{~m}$ max. <br> Branch line length: $\quad 3 \mathrm{~m}$ max. <br> Total branch line length: 50 m max. <br> Flat cable: <br> Main line length: $\quad 30 \mathrm{~m}$ max. <br> Branch line length: $\quad 3 \mathrm{~m}$ max. <br> Total branch line length: 30 m max. <br> (When flat cable is used to connect fewer than 16 Slaves, the main line can be up to 100 m long and the total branch line length can be up to 50 m .) |
|  | Long-distance communications mode | VCTF cable::  <br> Main line length: 500 m max. <br> Branch line length: 6 m max. <br> Total branch line length: 120 m max. |
| Max. number of connecting nodes |  | 32 |
| Error control checks |  | Manchester code check, frame length check, and parity check |

Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The communications baud rate is switched with the DIP switch.

## Unit Specifications

| Current consumption | 180 mA max. at 5 VDC |
| :---: | :---: |
| Number of I/O points | 128 points ( 64 inputs/64 outputs), 64 points ( 32 inputs/32 outputs), 32 points (16 inputs/16 outputs) (switchable) |
| Number of occupied words | 128 points: 4 input words/4 output words 64 points: 2 input words/2 output words 32 points: 1 input word/1 output word |
| PC | $\begin{aligned} & 128 \text { points: CQM1-CPU41-EV1/CPU42-EV1/CPU43-EV1/CPU44-EV1 } \\ & 64 \text { points: } \mathrm{CQM1-CPU11-E/CPU21-E/CPU41-EV1/CPU42-EV1/CPU43-EV1/CPU44-EV1} \\ & 32 \text { points: } \\ & \hline \end{aligned}$ |
| Number of points per node number | 4/8 points (switchable) |
| Max. number of Slaves per Master | 32 (4 points per node number) |
| Status data | Alarm terminal output |
| Weight | 200 g max. |
| Approved standards | UL 508 (E95399), CSA C22.2 No. 142 (LR51460) |

Alarm Output Specifications

| Maximum switching capacity | 2 A at 24 VDC |  |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| Minimum switching capacity | 10 mA at 5 VDC |  |  |  |  |  |  |
| Relay | $\mathrm{G} 6 \mathrm{D}-1 \mathrm{~A}$ |  |  |  |  |  |  |
| Minimum ON time | 100 ms |  |  |  |  |  |  |
| Circuit configuration |  |  |  |  |  |  |  |

## ■ Ratings

The ratings of the Unit are the same as those for the CQM1.

## Nomenclature

## Terminal block screws

These screws attach the terminal block. The terminal block can be removed when these screws are loosened.


## Dimensions

Note: All units are in millimeters unless otherwise indicated
CQM1-SRM21-V1


Note: Refer to the CQM1 Operation Manual for details on the dimensions when the Master Unit is installed in the PC's Backplane.

## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.

## OmROn

## SYSMAC Board

## SYSMAC C200HX/HG/HE and <br> CompoBus/S Master Functions Integrated into a Single PCB

■ Operates as a Programmable Controller to be built into personal computers.

- Programming is possible through Programming Devices like the programming on C200HX/HG.
- An optional Expansion Board is available for serial communications.

■ Dedicated library in C is available for control.
■ Driver for Windows use is available.
■ Connects to a maximum of three Expansion I/O Racks.

■ CompoBus/S Slave data is automatically read.

## Ordering Information

| PC | Max. number of I/O points | Model |
| :--- | :---: | :--- |
| C200HG-CPU43 | 256 points (128 inputs/128 outputs) | C200PC-ISA02-SRM |
| C200HX-CPU64 |  | C200PC-ISA12-SRM |

## Specifications

- Communications Specifications

| Communications method | CompoBus/S protocol |
| :---: | :---: |
| Coding method | Manchester coding method |
| Connection method | Multi-drop method and T-branch method (see note) |
| Communications baud rate | 750,000 bps |
| Communications cycle time | 0.5 ms with 8 Slaves for inputs and 8 Slaves for outputs 0.8 ms with 16 Slaves for inputs and 16 Slaves for outputs |
| Communications cable | 2-conductor VCTF cable ( $0.75 \times 20$ ) Dedicated flat cable |
| Communications distance | VCTF cable:  <br> Main line length: 100 m max. <br> Branch line length: 3 m max. <br> Total branch line length: 50 m max. <br> Flat cable:  <br> Main line length: 30 m max. <br> Branch line length: 3 m max. <br> Total branch line length: 30 m max.  <br> (When flat cable is used to connect fewer than 16 Slaves, the main line can be up to <br> 100 m long and the total branch line length can be up to 50 m. .)  |
| Max. number of connecting nodes | 32 |
| Error control checks | Manchester code check, frame length check, and parity check |

Note: A terminator must be connected to the point in the system farthest from the Master.

## Unit Specifications

| Power supply voltage | 4.875 to 5.25 VDC |
| :--- | :--- |
| Current consumption | 0.5 A max. (see note 1) |
| Number of I/O points | 256 points (128 inputs/128 outputs), 128 points (64 inputs/64 outputs), (switchable) |
| Number of occupied words | 256 points: 20 words (8 input words, 8 output words, and 4 status data words) (see note 2) <br> 128 points: 10 words (4 input words, 4 output words, and 2 status data words) |
| Number of points per node number | 8 points |
| Max. number of Slaves per Master | 32 |
| Status data | Communications Error Flag and Active Slave Node (see note 2) |
| Weight | 200 g max. |

Note: 1. The current consumption will be 0.8 A max. if the Programming Console is connected through the optional Expansion Board.
2. The occupied words are in the IR area.

## I/O Link Unit

## I/O Link Unit for CPM2A/CPM1A

■ Operates as a Slave of the CompoBus/S Master Unit.

■ Exchanges eight inputs and eight outputs with the Master.

■ Approved by UL and CSA standards, and bears the CE marking.


## Ordering Information

- CPU Units

| I/O configuration | Power supply | Output method | Input | Output | Model |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 30-point I/O model | AC | Relay | 18 | 12 | CPM1A-30CDR-A* |
|  | DC | Relay |  |  | CPM1A-30CDR-D* |
|  |  | Transistor (sink) |  |  | CPM1A-30CDT-D |
|  |  | Transistor (source) |  |  | CPM1A-30CDT1-D |
|  | AC | Relay |  |  | CPM2A-30CDR-A |
|  | DC | Relay |  |  | CPM2A-30CDR-D |
|  |  | Transistor (sink) |  |  | CPM2A-30CDT-D |
|  |  | Transistor (source) |  |  | CPM2A-30CDT1-D |
| 40-point I/O model | AC | Relay | 24 | 16 | CPM1A-40CDR-A* |
|  | DC | Relay |  |  | CPM1A-40CDR-D* |
|  |  | Transistor (sink) |  |  | CPM1A-40CDT-D |
|  |  | Transistor (source) |  |  | CPM1A-40CDT1-D |
|  | AC | Relay |  |  | CPM2A-40CDR-A |
|  | DC | Relay |  |  | CPM2A-40CDR-D |
|  |  | Transistor (sink) |  |  | CPM2A-40CDT-D |
|  |  | Transistor (source) |  |  | CPM2A-40CDT1-D |
| 60-point I/O model | AC | Relay | 36 | 24 | CPM2A-60CDR-A |
|  | DC | Relay |  |  | CPM2A-60CDR-D |
|  |  | Transistor (sink) |  |  | CPM2A-60CDT-D |
|  |  | Transistor (source) |  |  | CPM2A-60CDT1-D |

Note: Models marked with asterisks do not bear CE markings.

## - Expansion Units

| Product | Number of connectable Units per CPU Unit | Output method | Input | Output | Model |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Expansion I/O Units | 3 max. (see note) | Relay | 12 | 8 | CPM1A-20EDR1 |
|  |  | Transistor (sink) |  |  | CPM1A-20EDT |
|  |  | Transistor (source) |  |  | CPM1A-20EDT1 |
|  |  | --- | 8 | -- | CPM1A-8ED |
|  |  | Relay | --- | 8 | CPM1A-8ER |
|  |  | Transistor (sink) | --- | 8 | CPM1A-8ET |
|  |  | Transistor (source) |  |  | CPM1A-8ET1 |
| Analog I/O Unit | 3 max. (see note) | Analog | 2 | 1 | CPM1A-MAD01 |
| CompoBus/S I/O Link Unit | 3 max. (see note) | --- | $8 \mathrm{I} / \mathrm{O}$ link points | $8 \mathrm{I} / \mathrm{O}$ link points | CPM1A-SRT21 |

Note: Only a single Unit will be connectable if the NT-AL001 is connected to the RS-232C port.

## Specifications

| Slave | CompoBus/S Slave |
| :--- | :--- |
| Number of I/O points | 8 inputs and 8 outputs |
| Number of occupied I/O memory <br> words of CPM2A | 1 input word and 1 output word (same as other Expansion Units in allocation) |
| Node address setting | DIP switch |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.

## CPM1A-SRT21



## Installation

## ■ Connection Examples



Note: A single CompoBus/S I/O Link Unit together with a maximum of two other Expansion I/O Units can be connected to the CPM1A or CPM2A CPU Unit.

## OmROn

## Transistor Remote Terminal

## Long-distance Communications

## Supported by SRT2 Models

## (Long-distance/High-speed

Communications Selection)
■ SRT1 models support high-speed communications only.
SRT2 models support long-distance communications and high-speed communications.
■ Ultra-compact at $80 \times 48 \times 50(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}) \mathrm{mm}$ for 4 -point and 8-point terminals and $105 \times 48 \times 50$ (W x $\mathrm{H} \times \mathrm{D}) \mathrm{mm}$ for 16 -point terminals.

- Two independent power supplies can be used because the I/O terminals are insulated from the internal circuits.

■ DIN track mounting and screw mounting are both supported.



## Ordering Information

| I/O classification | Internal I/O circuit common | I/O points | Rated voltage | I/O rated voltage | Model |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input | NPN (+ common) | 4 | 24 VDC | 24 VDC | SRT1-ID04 |
|  | PNP (- common) |  |  |  | SRT1-ID04-1 |
| Output | NPN (- common) |  |  |  | SRT1-OD04 |
|  | PNP (+ common) |  |  |  | SRT1-OD04-1 |
| Input | NPN (+ common) | 8 |  |  | SRT2-ID08 |
|  | PNP (- common) |  |  |  | SRT2-ID08-1 |
| Output | NPN (- common) |  |  |  | SRT2-OD08 |
|  | PNP (+ common) |  |  |  | SRT2-OD08-1 |
| Input | NPN (+ common) | 16 |  |  | SRT2-ID16 |
|  | PNP (- common) |  |  |  | SRT2-ID16-1 |
| Output | NPN (- common) |  |  |  | SRT2-OD16 |
|  | PNP (+ common) |  |  |  | SRT2-OD16-1 |

Note: For more details about connections supported by the Master Unit, refer to page 2.

## Specifications

## - Ratings

Inputs

| Input current | 6 mA max./point |
| :--- | :--- |
| ON delay time | 1.5 ms max. |
| OFF delay time | 1.5 ms max. |
| ON voltage | 15 VDC min. between each input terminal and V |
| OFF voltage | 5 VDC max. between each input terminal and V |
| OFF current | 1 mA max. |
| Insulation method | Photocoupler |
| Input indicators | LED (yellow) |

## Outputs

| Rated output current | $0.3 \mathrm{~A} /$ point |
| :--- | :--- |
| Residual voltage | 0.6 V max. |
| Leakage current | 0.1 mA max. |
| Insulation method | Photocoupler |
| Output indicators | LED (yellow) |

## ■ Characteristics

| Communications power supply voltage | 14 to 26.4 VDC |
| :---: | :---: |
| I/O power supply voltage | 24 VDC ${ }^{+10 \% /-15 \%}$ |
| I/O power supply current | 1 A max. |
| Current consumption (see note) | 50 mA max. at 24 VDC |
| Connection method | Multi-drop method and T-branch method Secondary branches cannot be connected to T-branch lines. |
| Connecting Units | 4-point and 8-point Terminals: 16 Input Terminals and 16 Output Terminals per Master 16-point Terminals: <br> 8 Input Terminals and 8 Output Terminals per Master |
| Dielectric strength | 500 VAC for 1 min (1-mA sensing current between insulated circuits) |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |
| Shock resistance | Malfunction: $200 \mathrm{~m} / \mathrm{s}^{2}$ <br> Destruction: $300 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions |
| Terminal strength | No damage when 50 N pull load was applied for 10 s |
| Screw tightening torque | 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $\quad 0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) Storage: $\quad-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: 35\% to 85\% |
| Weight | 4-point and 8-point Terminals: 80 g max. 16-point Terminals: $\quad 110 \mathrm{~g}$ max. |
| Approved standards (4/8 points) | UL 508, CSA C22.2 No. 14 |

Note: The above current consumption is the value with all 4 and 8 and 16 points turned ON excluding the current consumption of the external sensor connected to the input Remote Terminal and the current consumption of the load connected to the output Remote Terminal.

Nomenclature


Used for node number setting and holding or clearing outputs for communications error. Refer to the Compobus/S Operation Manual (W266) for details on DIP switch settings.


Node Number Settings
Indicators

| Indicator | Display | Color | Meaning |
| :---: | :---: | :---: | :---: |
| PWR | Lit | Green | The communications power supply is ON. |
|  | Not lit |  | The communications power supply is OFF. |
| COMM | Lit | Yellow | Normal communications |
|  | Not lit |  | A communications error has occurred or the Unit is in standby status. |
| ERR | Lit | Red | A communications error has occurred. |
|  | Not lit |  | Normal communications or the Unit is in standby status. |
| 0 to 7 | Lit | Yellow | The corresponding I/O signal is ON. |
|  | Not lit |  | The corresponding I/O signal is OFF. |

Output HOLD/CLEAR Mode

| Mode | Pin 1 | Setting |
| :--- | :--- | :--- |
| HOLD | ON | Output status is maintained. |
| CLEAR | OFF | Output status is cleared when a communications error occurs. |

Note: 1. Pin 1 is factory-set to OFF.
2. This function is available to Output Terminals only.

Node Number Settings

| Node number | Pin 3 | Pin 4 | Pin 5 | Pin 6 |
| :---: | :---: | :---: | :---: | :---: |
|  | 8 | 4 | 2 | 1 |
| 0 | OFF | OFF | OFF | OFF |
| 1 | OFF | OFF | OFF | ON |
| 2 | OFF | OFF | ON | OFF |
| 3 | OFF | OFF | ON | ON |
| 4 | OFF | ON | OFF | OFF |
| 5 | OFF | ON | OFF | ON |
| 6 | OFF | ON | ON | OFF |
| 7 | OFF | ON | ON | ON |
| 8 | ON | OFF | OFF | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | ON | OFF | ON | OFF |
| 11 | ON | OFF | ON | ON |
| 12 | ON | ON | OFF | OFF |
| 13 | ON | ON | OFF | ON |
| 14 | ON | ON | ON | OFF |
| 15 | ON | ON | ON | ON |

Note: 1. The node number is factory-set to 0.
2. For node number settings, refer to the CompoBus/S Operation Manual (W266).

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT1-ID04 (-1) SRT1-OD04 (-1) SRT2-ID08 (-1) SRT2-OD08 (-1)


Mounting Holes


## SRT2-ID16 (-1) <br> SRT2-OD16 (-1)



Mounting Holes


## Installation

## - Internal Circuit Configuration



## SRT2-ID08

SRT2-ID08-1


SRT2-OD08


SRT2-ID16


SRT2-OD16


## ■ External Connections (NPN Models)

## Input

Three-wired Sensors
SRT1-ID04 with NPN Output


SRT2-ID08 and SRT2-ID16 with NPN Output


Two-wired Sensors
SRT1-ID04


Output
SRT1-OD04


- Terminal Arrangement and I/O Device Connection Example (PNP Models)

Note: The connections examples shown are for PNP models.
Input


■ External Connections (PNP Models)

Input
Three-wired Sensors
SRT1-ID04-1 with NPN Output


Two-wired Sensors SRT1-ID04-1


## Output

SRT1-OD04


SRT2-ID08-1 and SRT2-ID16-1 with NPN Output


SRT2-ID08-1 and SRT2-ID16-1


SRT2-OD08-1 and SRT2-ID16-1


■ Terminal Arrangement and I/O Device Connection Example (PNP Models)
Note: The connections examples shown are for NPN models.
Input


Output

SRT1-OD04-1


## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.

For general precautions refer to page 72 .

## OmROn

## Remote I/O Terminal

## Models with 3-tier Terminals (16 Points)

 are Added to the Remote I/O Terminal
## Series.

## Six Models are Available Depending on the NPN or PNP Configuration, Input Points, I/O Points, or Output Points.

■ Incorporates easy-to-wire terminals each connecting to a single wire.

- Reduces designing and wiring effort.
- Incorporates a removable circuit block of cassette construction.


## Ordering Information

| I/O classification | Internal I/O circuit common | I/O points | I/O connection method | Model |
| :---: | :---: | :---: | :---: | :---: |
| Digital input | NPN (+ common) | 16 | M3 terminal block | SRT1-ID16T |
|  | PNP (- common) |  |  | SRT1-ID16T-1 |
| Digital I/O | NPN (+ common) |  |  | SRT1-MD16T |
|  | PNP (- common) |  |  | SRT1-MD16T-1 |
| Digital output | NPN (- common) |  |  | SRT1-OD16T |
|  | PNP (+ common) |  |  | SRT1-OD16T-1 |

## Specifications

■ Ratings
Inputs

| Input current | 6 mA max./point at 24 V and 3 mA min./point at 17 V |
| :--- | :--- |
| ON delay time | 1.5 ms max. |
| OFF delay time | 1.5 ms max. |
| ON voltage | NPN: 15 VDC min. between V terminals and each input terminal <br> PNP: 15 VDC min. between G terminals and each input terminal |
| OFF voltage | NPN: 5 VDC max. between V terminals and each input terminal <br> PNP: 5 VDC max. between G terminals and each input terminal |
| OFF current | 1 mA max. |
| Insulation method | Photocoupler |

## Outputs

| Rated output current | $0.5 \mathrm{~A} \mathrm{max} / point$. |
| :--- | :--- |
| Residual voltage | 1.2 V max. |
| ON delay time | 0.5 ms max. |
| OFF delay time | 1.0 ms max. |
| Leakage current | 0.1 mA max. |
| Insulation method | Photocoupler |

## - Characteristics

| Communications power supply <br> voltage | 14 to 26.4 VDC |
| :--- | :--- |
| I/O power supply voltage | $24 \mathrm{VDC}+10 \% /-15 \%$ |
| I/O power supply current | 4 A max./common |
| Current consumption (see note) | 50 mA max. at 24 VDC |
| Connection method | Multi-drop method and T-branch method <br> Secondary branches cannot be connected to T-branch lines. |
| Dielectric strength | 500 VAC between insulated circuits |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0-\mathrm{mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}$ |
| Shock resistance | 200 m/s ${ }^{2}$ |
| Mounting strength | No damage with 100 N pull load applied in all directions. |
| Terminal strength | No damage with 100 N pull load applied |
| Screw tightening torque | 0.3 to $0.5 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ |
| Storage: $-25^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ |  |
| Ambient humidity | Operating: $25 \%$ to $85^{\circ} \%$ (with no condensation) |
| Weight | 300 g max. |

Note: The above current consumption is the value with all points turned ON excluding the current consumption of the external sensor connected to the input Remote Terminal and the current consumption of the load connected to the output Remote Terminal.

## Nomenclature



## Address Setting Switch

| Node address | Setting (Hex) |
| :--- | :--- |
| 0 | 0 |
| 1 | 1 |
| 2 | 2 |
| 3 | 3 |
| 4 | 4 |
| 5 | 5 |
| 6 | 6 |
| 7 | 7 |


| Node address | Setting (Hex) |
| :--- | :--- |
| 8 | 8 |
| 9 | 9 |
| 10 | A |
| 11 | B |
| 12 | C |
| 13 | D |
| 14 | E |
| 15 | F |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT1-ID16T (-1)
SRT1-MD16T (-1)
SRT1-OD16T (-1)


## Installation

## ■ Internal Circuit Configuration



## ■ External Connections



## OmROn

## Relay-mounted Remote Terminal

## Ultra-miniature 8-point and 16-point <br> Relay-mounted Terminals

- Ultra-compact
(8-point models: $101 \times 51 \times 51 \mathrm{~mm}(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$;
16-point models: $156 \times 51 \times 51 \mathrm{~mm}(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$ )
- Power MOS FET Relay and Relay models.

■ DIN track mounting and screw mounting are available.


## Ordering Information

| Classification | I/O points | Rated voltage | Relay coil rating | Model | Applicable relay |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Relay output | 8 points | 24 VDC | 24 VDC | SRT1-ROC08 | G6D-1A |
|  | 16 points |  |  | SRT2-ROC16 |  |
| Power MOS FET relay output | 8 points |  |  | SRT1-ROF08 | G3DZ-2R6PL |
|  | 16 points |  |  | SRT2-ROF16 |  |

Note: For details about connections to the Master Unit, refer to page 2.

## Specifications

## ■ Ratings

Relay Output

| Item | SRT1-ROC08, SRT2-ROC16 |
| :--- | :--- |
| Applicable relay | G6D-1A (one for each output point) |
| Rated load | 3 A at 250 VAC, 3 A at 30 VDC (resistive load) |
| Rated carry current | 3 A (see note 1) |
| Max. contact voltage | $250 \mathrm{VAC}, 30 \mathrm{VDC}$ |
| Max. contact current | 3 A |
| Max. switching capacity | 730 VA (AC), 90 W (DC) |
| Min. permissible load (see note 2) | 10 mA at 5 VDC |
| Life expectancy | Electrical: 100,000 operations min. (rated load, at 1,800 operations/h) <br> Mechanical: 20,000,000 operations min. (at 18,000 operations/h) |

Note: 1. The maximum permissible current of COM0 to COM7 is 3 A.
2. This value fulfills the $P$ reference value of opening/closing at a rate of 120 times per min (ambient operating environment and determination criteria according to JIS C5442).
Power MOS FET Relay Output

| Item | SRT1-ROF08, SRT2-ROF16 |
| :--- | :--- |
| Applicable relay | G3DZ-2R6PL (one for each output point) |
| Load voltage | 3 to $264 \mathrm{VAC}, 3$ to 125 VDC |
| Load current | $100 \mu \mathrm{~A}$ to 0.3 A |
| Inrush current | $6 \mathrm{~A}(10 \mathrm{~ms})$ |

- Characteristics

| Power supply voltage | 24 VDC +10\%/-15\% |
| :---: | :---: |
| Current consumption (see note) | 350 mA max. at 24 VDC |
| Connection method | Multi-drop method and T-branch method Secondary branches cannot be connected to T-branch lines. |
| Connecting Units | 8-point Units: 16 per Master 16-point Units: 8 per Master |
| Dielectric strength | 2,000 VAC for 1 min ( $1-\mathrm{mA}$ sensing current) between all output terminals and power supply, between communication terminals, and between contacts of different polarities <br> 500 VAC for 1 min ( $1-\mathrm{mA}$ sensing current) between all output terminals and power supply, between communication terminals, and between all power supply terminals and communications terminals |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 0.75-\mathrm{mm}$ double amplitude |
| Shock resistance | Malfunction: $100 \mathrm{~m} / \mathrm{s}^{2}$ Destruction: $300 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions |
| Terminal strength | No damage when 50 N pull load was applied for 10 s |
| Screw tightening torque | 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $\quad 0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) Storage: $\quad-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ |
| Weight | 8-point models: 145 g max., 16-point models: 240 g max. |
| Approved standards | UL 508, CSA C22.2 No. 14 |

Note: The above current consumption is a value with all the points turned ON including the current consumption of the G6D coil for the Remote Output Terminal.

Nomenclature
SRT2-ROC16 SRT2-ROF16


Note: Always turn off the Unit before changing DIP switch settings.

## SRT1-ROC08

SRT1-ROF08 Mounting Holes


Output HOLD/CLEAR Mode

| Mode | Pin 1 | Setting |
| :--- | :--- | :--- |
| HOLD | ON | Output status is maintained when a communications error occurs. |
| CLEAR | OFF | Output status is cleared when a communications error occurs. |

Note: 1. Pin 1 is factory-set to OFF.
2. This function is available to the Output Terminal only.

## Node Number Settings

| Node number | Pin 3 | Pin 4 | Pin 5 | Pin 6 |
| :---: | :---: | :---: | :---: | :---: |
|  | 8 | 4 | 2 | 1 |
| 0 | OFF | OFF | OFF | OFF |
| 1 | OFF | OFF | OFF | ON |
| 2 | OFF | OFF | ON | OFF |
| 3 | OFF | OFF | ON | ON |
| 4 | OFF | ON | OFF | OFF |
| 5 | OFF | ON | OFF | ON |
| 6 | OFF | ON | ON | OFF |
| 7 | OFF | ON | ON | ON |
| 8 | ON | OFF | OFF | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | ON | OFF | ON | OFF |
| 11 | ON | OFF | ON | ON |
| 12 | ON | ON | OFF | OFF |
| 13 | ON | ON | OFF | ON |
| 14 | ON | ON | ON | OFF |
| 15 | ON | ON | ON | ON |

Note: 1. The node number is factory-set to 0 .
2. For node number setting, refer to the CompoBus/S Operation Manual (W266).

## Dimensions

Note: All units are in millimeters unless otherwise indicated.


SRT2-ROC16 SRT2-ROF16


## Installation

## ■ Internal Circuit Configuration

SRT1-ROC08 SRT2-ROC16


Note: The G3DZ-2R6PL Power MOS FET Relay is inserted into this portion of the SRT1-ROF08 and SRT2-ROF16.

## ■ External Connections



## ■ Terminal Arrangement and I/O Device Connection Example

## Output



Note: 1. Dotted lines indicate internal connections.
SRT1-ROC08 and SRT1-ROF08 have the 0 to 7 and COM0 to COM3 terminals only.
2. The above is a connection example of the SRT2-ROC16 with G6D Relays mounted. G3DZ Power MOS FET Relays are mounted to the SRT1-ROF08 and SRT2-ROF16.

## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.
Refer to page 72 for details.

## Connector Terminal

## Compact Connector Terminals Save Wiring Effort and Enable Long-distance Communications

■ Long-distance or high-speed communications mode is selectable.

■ Incorporates I/O connectors making it possible to minimize the size.

- I/O connectors save wiring effort.

■ Flexible DIN track mounting is possible through a DIN track attachment.

■ Eight-point sensor connector models and 16-point MIL connector models are the same size.


## ■ Features

Vertical or horizontal DIN track mounting according to the available space is possible
Saves space and easily connects to other devices without wiring effort.


## Ordering Information

| I/O classification | Internal I/O circuit common | I/O points | I/O connection method | Model |
| :---: | :---: | :---: | :---: | :---: |
| Digital input | NPN (+ common) | 8 | Sensor connector | SRT2-VID08S |
|  | PNP (- common) |  |  | SRT2-VID08S-1 |
| Digital output | NPN (- common) |  |  | SRT2-VOD08S |
|  | PNP (+ common) |  |  | SRT2-VOD08S-1 |
| Digital input | NPN (+ common) | 16 | MIL connector | SRT2-VID16ML |
|  | PNP (- common) |  |  | SRT2-VID16ML-1 |
| Digital output | NPN (- common) |  |  | SRT2-VOD16ML |
|  | PNP (+ common) |  |  | SRT2-VOD16ML-1 |
| Mounting hook A |  |  |  | SRT2-ATT01 |
| Mounting hook B |  |  |  | SRT2-ATT02 |

Note: For details about connecting the SRT2-VID or SRT2-VOD to the Master Unit, refer to page 2.

## Specifications

## ■ Ratings

Inputs

| Item | SRT2-VID08S <br> SRT2-VID08S-1 | SRT2-VID16ML <br> SRT2-VID16ML-1 |
| :--- | :--- | :--- |
| Input current | 6 mA max./point at 24 V, 3 mA max./point at 17 V |  |
| ON delay time | $1.5 \mathrm{~ms} \mathrm{max}$. |  |
| OFF delay time | 1.5 ms max. |  |
| ON voltage | 15 VDC min. (Between each input terminal and V: NPN. Between each input and G: PNP.) |  |
| OFF voltage | 5 VDC max. (Between each input terminal and V: NPN. Between each input and G: PNP.) |  |
| OFF current | 1 mA max. | 12 |
| Insulation method | Photocoupler | 16 points/common, 1 circuit |
| Maximum number of inputs | 8 | 8 points/common, 1 circuit |
| Number of circuits |  |  |

## Outputs

| Item | SRT2-VID08S <br> SRT2-VID08S-1 | SRT2-VID16ML <br> SRT2-VID16ML-1 |
| :--- | :--- | :--- |
| Rated output current | $0.3 \mathrm{~A} /$ point | 0.3 A/point (2-A common) (See note.) |
| Residual voltage | 1.2 V max. |  |
| ON delay time | 0.5 ms max. |  |
| OFF delay time | 1.5 ms max. |  |
| Leakage current | 0.1 mA max. | 16 points/common, 1 circuit |
| Insulation method | Photocoupler | 8 points/common, 1 circuit |
| Number of circuits | 8 |  |

Note: When using V/G terminals in an MIL connector, ensure that the current per terminal for the V/G terminals does not exceed 1 A .

- Characteristics

| Communications power supply <br> voltage | 14 to 26.4 VDC |
| :--- | :--- |
| I/O power supply voltage | 20.4 to $26.4 \mathrm{VDC}(24 \mathrm{VDC}+10 \% /-15 \%)$ |
| I/O power supply current | Sensor connector: 2.4 A max., MIL connector: 2.0 A max. |
| Current consumption (see note) | 50 mA max. at 24 VDC |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0-\mathrm{mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}$ (50 m/s ${ }^{2}$ for SRT2-ATT02) |
| Shock resistance | $200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Dielectric strength | 500 VAC (between insulated circuits) |
| Ambient temperature | Operating: $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: $-25^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ |
| Ambient humidity | Operating: $25 \%$ to $85 \%$ (with no condensation) <br> Storage: $25 \%$ to $85 \%$ |
| Mounting strength | No damage when 100 N pull load was applied in all directions (40 N load for SRT2-ATT02) |
| Terminal strength | No damage when the following loads were applied: <br> Communications connector: 100 N <br> Sensor connector: 40 N <br> MIL connector: 100 N |
| Screw tightening torque | Communications connector: $0.25 \mathrm{~N} \cdot \mathrm{~m}$ |
| Node address setting | Settings made at DIP switch (set before supplying power for Slave communications) |
| Weight | Approx. $75 \mathrm{~g} \mathrm{max}$. |

Note: The above current consumption is the value with all points turned ON excluding the current consumption of the external sensor connected to the input Remote Terminal and the current consumption of the load connected to the output Remote Terminal.

Nomenclature

SRT2-VID08S/SRT2-VID08S-1


Indicators

| Indicator | Name | Color | Display | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power | Green | Lit | The communications power supply is ON. |
|  |  |  | Not lit | The communications power supply is OFF. |
| СомM | Communications | Yellow | Lit | Normal communications |
|  |  |  | Not lit | A communications error has occurred or the Unit is in standby status. |
| ERR | Communications error | Red | Lit | A communications error has occurred. |
|  |  |  | Not lit | Normal communications or the Unit is in standby status. |
| 0 to 7 <br> (for <br> 8 -point <br> 1/0) <br> 0 to 15 <br> (for <br> 16-point <br> 1/0) | Input (output) | Yellow | Lit | The corresponding I/O signal is ON . |
|  |  |  | Not lit | The corresponding I/O signal is OFF. |

Output HOLD/CLEAR Mode Setting Output HOLD/CLEAR Mode

| SW8 (HOLD) | Setting |
| :--- | :--- |
| OFF | Output status is cleared. |
| ON | Output status is maintained. |

Communications Mode Setting
Communications Mode

| SW7 (HOLD) | Setting |
| :--- | :--- |
| OFF | High-speed communications mode |
| ON | Long-distance communications mode |

Reserved for System Use (Always OFF)
Node Address Setting
Node Number Settings

| Node number | Pin 4 | Pin 3 | Pin 2 | Pin $\mathbf{1}$ |
| :--- | :--- | :--- | :--- | :--- |
|  | 8 |  |  | $\mathbf{1}$ |
| 0 | OFF | OFF | OFF | OFF |
| 1 | OFF | OFF | OFF | ON |
| 2 | OFF | OFF | ON | OFF |
| 3 | OFF | OFF | ON | ON |
| 4 | OFF | ON | OFF | OFF |
| 5 | OFF | ON | OFF | ON |
| 6 | OFF | ON | ON | OFF |
| 7 | OFF | ON | ON | ON |
| 8 | ON | OFF | OFF | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | ON | OFF | ON | OFF |
| 11 | ON | OFF | ON | ON |
| 12 | ON | ON | OFF | OFF |
| 13 | ON | ON | OFF | OFF |
| 14 | ON | ON | ON | OFF |
| 15 | ON | ON | ON | ON |

Note: Be sure to perform settings with the Slave power supply OFF.

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT2-VID08S
SRT2-VID08S-1
SRT2-VOD08S
SRT2-VOD08S-1


SRT2-VID16ML
SRT2-VID16ML-1
SRT2-VOD16ML
SRT2-VOD16ML-1


SRT2-ATT01


## SRT2-ATT02



## Installation

## ■ Internal Circuit Configuration



SRT2-VOD16ML


SRT2-VID08S-1


SRT2-VOD08S-1


SRT2-VID16ML-1


SRT2-VOD16ML-1


## ■ Terminal Arrangement and I/O Device Connection Examples

## SRT2-VID08S



SRT2-VID16ML


SRT2-VID08S-1

(ㄷ) (1) (3)
(ㄷ) (1) (2)
(ㄷ(1)(:)
SRT2-VID16ML-1


SRT2-VOD08S

(ㄷ) (3)
(ㄷ) (2)
(®)(2):
SRT2-VOD16ML


SRT2-VOD08S-1


SRT2-VOD16ML-1


Note: 1. $V$ terminals and $G$ terminals are respectively connected internally.
When supplying power for I/O from communications connectors, power can be supplied to the sensor output devices from $V$ and $G$ terminals.
2. When using an inductive load (solenoid, valve etc.), either use one with an internal reverse electromotive force absorption diode or attach a diode externally.

## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.
Refer to page 72 for common precautions.

## Communications Connector Pin Arrangement



The following solderless terminals are recommended.

- Manufacturer: Weidmuller


Two-wire insertion (Part No. 901851)


The following product is a dedicated tool.

- Manufacturer: Weidmuller PZ1.5 Crimper (Part No. 900599)


## Sensor Connector Pin Arrangement

SRT2-VID08S/VID08S-1


SRT2-VOD08S/VOD08S-1


| Model | Cable conductor size |
| :--- | :--- |
| XS8A-0441 | 0.3 to $0.5 \mathrm{~mm}^{2}$ |
| XS8A-0442 | 0.14 to $0.2 \mathrm{~mm}^{2}$ |

Note: The XS8A-0441 or XS8A-0442 Connector is not provided with the SRT-VID or SRT2-VOD. Place an order for the connector separately.
Calculate the cable conductor size as follows.
The following information is given on each sensor cable:
Cable dia. (Number of conductors/Conductor dia.)
Conductor size $\left(\mathrm{mm}^{2}\right)=$
(Conductor dia./2) ${ }^{2} \times \pi \times$ Number of conductors
Example: E3S-A
4 dia. (18/0.12)
Conductor size $\left(\mathrm{mm}^{2}\right)=(0.12 / 2)^{2} \times 3.14 \times 18 \square 0.20$
The conductor size is $0.2 \mathrm{~mm}^{2}$. Therefore, use the XS8A-0442.

## MIL Connector Pin Arrangement

## SRT2-VID16ML/VID16ML-1

| Function | Pin No. |  |  |
| :---: | :---: | :---: | :---: |
| IN0 | 20 | Function | Pin No. |
| IN1 | 18 | 19 | IN8 |
| IN2 | 16 | 17 | IN9 |
| IN3 | 14 | 15 | IN10 |
| IN4 | 12 | 13 | IN11 |
| IN5 | 10 | 11 | IN12 |
| IN6 | 8 | 9 | IN13 |
| IN7 | 6 | 7 | IN14 |
| G | 4 | 5 | IN15 |
| V | 2 | 3 | G |
|  |  | 1 | V |

SRT2-VOD16ML/VOD16ML-1

| Function | Pin No. |  |  |
| :---: | :---: | :---: | :---: |
| OUTO | 20 | Function | Pin No. |
| OUT1 | 18 | 19 | OUT8 |
| OUT2 | 16 | 17 | OUT9 |
| OUT3 | 14 | 15 | OUT10 |
| OUT4 | 12 | 13 | OUT11 |
| OUT5 | 10 | 11 | OUT12 |
| OUT6 | 8 | 9 | OUT13 |
| OUT7 | 6 | 7 | OUT14 |
| G | 4 | 5 | OUT15 |
| V | 2 | 3 | G |
|  |  | 1 | V |

Note: 1. No cable connector is provided. Order the connector separately.

- Applicable Connector XG4M-2030-T
- Applicable Connector Cables G79-O50C G79-O25C G79-I50C G79-I25C

2. Refer to the following table for ordering information on the applicable Cables.

## Applicable Cables

| Connectable product | Model |  | Applicable Cable |
| :---: | :---: | :---: | :---: |
| I/O Block | $\begin{aligned} & \text { G7TC-OC16 } \\ & \text { G7TC-OC08 } \\ & \text { G7TC-ID16-5 } \\ & \text { G7TC-IA16-5 } \end{aligned}$ | $\leftrightarrow$ | G79-O50C (L = 500 mm ) |
|  | G7VC Series G70A Series G70D Series |  | G79-O25C (L = 250 mm ) |
| Connector-Terminal Conversion Unit | XW2B Series |  |  |
| Digital Display Unit | M7F |  |  |
| I/O Block | $\begin{aligned} & \text { G7TC-ID16 } \\ & \text { G7TC-IA16 } \\ & \text { G7TC-OC16-1 } \end{aligned}$ | $\leftrightarrow$ | G79-I50C (L = 500 mm ) |
|  |  |  | G79-I25C (L = 250 mm ) |

## omROn

## Sensor Terminal

Connector Connection Models that
Allows Easy Connection to Sensors and Output Devices

■ Sensors with easy-to-wire connectors are easily attached or detached.

■ Connects to 2-wired sensors.

- Remote teaching of the Sensor Terminal is possible with the PC by using output signals of the Sensor Terminal.

■ DIN track mounting and screw mounting are available.


## Ordering Information

| Classification | Internal I/O circuit common | I/O points | Model |
| :--- | :--- | :--- | :--- |
| For input | NPN (- common) | 8 input points | SRT1-ID08S |
| For I/O | NPN (- common) | 4 input/4 output points | SRT1-ND08S |
| For output | NPN (- common) | 8 output points | SRT1-OD08S |

## Specifications

■ Ratings
Input

| Item | $\quad$ SRT1-ID08S/-ND08S |
| :--- | :--- |
| Input current | 10 mA max./point |
| ON delay time | 1 ms max. |
| OFF delay time | 1.5 ms max. |
| ON voltage | 12 VDC min. between each input terminal and $\mathrm{V}_{\mathrm{CC}}$, the external sensor power supply |
| OFF voltage | 4 VDC max. between each input terminal and $\mathrm{V}_{\mathrm{CC}}$, the external sensor power supply |
| OFF current | 1 mA max. |
| Insulation method | Photocoupler |
| Input indicator | LED (yellow) |

Output

| Item | $\quad$ SRT1-ND08S | SRT1-OD08S |
| :--- | :--- | :--- |
| Rated output current | $20 \mathrm{~mA} /$ point | $30 \mathrm{~mA} / \mathrm{point}$ |
| Residual voltage | 1 V max. | 0.6 V max. |
| ON delay time | 1 ms max. | --- |
| OFF delay time | $1.5 \mathrm{~ms} \mathrm{max}$. | --- |
| Leakage current | 0.1 mA max. |  |
| Insulation method | Photocoupler |  |
| Output indicator | LED (yellow) |  |

## ■ Characteristics

| Communications power supply <br> voltage (see note 1) | 14 to 26.4 VDC |
| :--- | :--- |
| Current consumption (see note 2) | 50 mA max. at 24 VDC |
| Connection method | Multi-drop method and T-branch method <br> Secondary branches cannot be connected to T-branch lines. |
| Dielectric strength | 500 VAC for $1 \mathrm{~min}(1-\mathrm{mA}$ sensing current between insulated circuits) |
| Noise immunity | Power supply normal: $\pm 600 \mathrm{~V}$ for 10 minutes with a pulse width of 100 ns to $1 \mu \mathrm{~s}$ <br> Power supply common: $\pm 1,500 \mathrm{~V}$ for 10 minutes with a pulse width of 100 ns to $1 \mu \mathrm{~s}$ |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |
| Shock resistance | Malfunction: $200 \mathrm{~m} / \mathrm{s}^{2}$ <br> Destruction: $300 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting method | M4 screw mounting or $35-\mathrm{mm}$ DIN track mounting |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions (except the DIN track <br> directions and a pulling force of 10 N |
| Terminal strength | No damage when 50 N pull load was applied for 10 s in all directions <br> Tighten each screw to a torque of 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: $-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85^{\circ} \%$ |
| Weight | SRT1-ID08S/OD08S: 100 g max., SRT1-ND08S: 80 g max. |

Note: 1. The communications power supply voltage must be 20.4 to 26.4 VDC if the Unit is connected to 2-wired proximity sensors.
2. The above current consumption is a value with all the points turned OFF excluding the current consumption of the sensor connected to the Sensor Terminal.

- External Sensor Power Supply

| Power supply voltage | 13.5 to 26.4 VDC |
| :--- | :--- |
| Current consumption | 500 mA max. in total |

## Nomenclature



## Indicators

| Indicator | Name | Display | Color | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Lit | Green | The communications power supply is ON. |
|  |  | Not lit |  | The communications power supply is OFF. |
| COMM | Communication | Lit | Yellow | Normal communications |
|  |  | Not lit |  | A communications error has occurred or the Unit is in standby status. |
| ERR | Communication error | Lit | Red | A communications error has occurred. |
|  |  | Not lit |  | Normal communications or the Unit is in standby status. |
| 0 to 3 <br> (4 inputs/outputs) 0 to 7 (8 inputs) | Input | Lit | Yellow | The corresponding input is ON. |
|  |  | Not lit |  | The corresponding input is OFF or the Unit is in standby status. |
| 0 to 3 <br> (4 inputs/outputs) | Output | Lit | Yellow | The corresponding output is ON. |
|  |  | Not lit |  | The corresponding output is OFF or the Unit is in standby status. |

## Switch Setting

All pins are factory-set to OFF.


Pin 5 (Reserved)
Always set pin 5 to OFF.
Output HOLD/CLEAR Mode (SRT-ND16S)

| HOLD | Function |
| :--- | :--- |
| OFF | Output status is cleared when a <br> communications error occurs. |
| ON | Output status is maintained when a <br> communications error occurs. |

Node Number Settings

| Node number | 1 | $\mathbf{4}$ |  |  |
| :--- | :--- | :--- | :--- | :--- |
| 0 | OFF | OFF | $\mathbf{4}$ |  |
| 1 | ON | OFF | OFF | OFF |
| 2 | OFF | ON | OFF | OFF |
| 3 | ON | ON | OFF | OFF |
| 4 | OFF | OFF | OFF | OFF |
| 5 | ON | OFF | ON | OFF |
| 6 | OFF | ON | ON | OFF |
| 7 | ON | ON | ON | OFF |
| 8 | OFF | OFF | OFF |  |
| 9 | ON | OFF | OF | ON |
| 10 | ON | ON | OFF | ON |
| 12 | OFF | ON | OFF | OF |
| 13 | ON | OFF | ON | ON |
| 14 | OFF | OFF | ON | ON |
| 15 | ON | ON | ON | ON |

SRT1-OD08S


Switch Setting
All pins are factory-set to OFF.


Mounting Hook
Used when mounting the Unit to a DIN track.

Pin 5 (Reserved)
Always set pin 5 to OFF.
Output HOLD/CLEAR Mode (SRT-ND16S)

| HOLD | Function |
| :--- | :--- |
| OFF | Output status is cleared when a <br> communications error occurs. |
| ON | Output status is maintained when a <br> communications error occurs. |

## Node Number Settings

| Node number | 4 | 3 | 2 | 1 |
| :---: | :---: | :---: | :---: | :---: |
| 0 | OFF | OFF | OFF | OFF |
| 1 | OFF | OFF | OFF | ON |
| 2 | OFF | OFF | ON | OFF |
| 3 | OFF | OFF | ON | ON |
| 4 | OFF | ON | OFF | OFF |
| 5 | OFF | ON | OFF | ON |
| 6 | OFF | ON | ON | OFF |
| 7 | OFF | ON | ON | ON |
| 8 | ON | OFF | OFF | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | ON | OFF | ON | OFF |
| 11 | ON | OFF | ON | ON |
| 12 | ON | ON | OFF | OFF |
| 13 | ON | ON | OFF | ON |
| 14 | ON | ON | ON | OFF |
| 15 | ON | ON | ON | ON |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.


## SRT1-ND08S





Mounting Holes


## SRT1-OD08S



Cable Connector for SRT1-OD08S

| Applicable conductor size $\left(\mathbf{m m}^{\mathbf{2}}\right)$ | Model |
| :--- | :--- |
| 0.3 to 0.5 | XS8A-0441 |
| 0.14 to 0.2 | XS8A-0442 |
| 0.3 to 0.5 | XS8B-0443 |

XS8A-044 $\square$
(Cable Connector)


XS8B-0443 (Relay Socket)


Calculate the cable conductor size as explained below.
The following information is given on each sensor cable:
Cable dia. (Number of conductors/Conductor dia.)
Conductor size $\left(\mathrm{mm}^{2}\right)=(\text { Conductor dia. } / 2)^{2} \times \pi \times$ Number of conductors
Example: E3S-A
4 dia. (18/0.12)
Conductor size $\left(\mathrm{mm}^{2}\right)=(0.12 / 2)^{2} \times 3.14 \times 18 \square 0.20$
The conductor size is $0.2 \mathrm{~mm}^{2}$. Therefore, use the XS8A-0442.

## Installation

## ■ Internal Circuit Configuration



SRT1-ND08S


## SRT1-OD08S



## ■ External Connections

## SRT1-ID08S

Three-wired Sensor
Two-wired Sensor


## SRT1-ND08S

Sensor with Teaching Function Sensor with External Diagnostic function
Sensor with Bank-switching Function


■ Terminal Arrangement and I/O Device Connection Example

Input
SRT1-ID08S

I/O
SRT1-ND08S


CompoBus/S
communica-

(Sensor with Teaching Function, Sensor with External Diagnostic function, Sensor with Bank-switching Function)

Output
SRT1-OD08S


## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.

## General Safety Precautions

## Installation Environment

Do not install the Unit in the following places.

- Places with water, oil, or chemical sprayed on the Unit.
- Places with rapid temperature changes.
- Places with high humidity resulting in condensation.
- Places with intense electric and magnetic fields.
- Places with excessive vibration or shock.


## Wiring

To prevent inductive noise, do not wire power lines or high-tension lines along with or near the cables.
Make sure that the polarity of each terminal is correct.
Make sure that the communications path and power line are connected correctly.
Secure the cables properly. Do not pull the cables with strong force, otherwise the cables may be disconnected from the terminals or connectors of the Unit.
Do not touch the Unit when the Unit is used in places with high ambient temperatures because the surface temperature of the Unit may be high.
Do not use paint thinner to clean the surface of the Unit, otherwise the surface will be damaged or discolored.

## Correct Use

Use the Unit under its rated conditions.
Mount the Unit with M4 screws or to DIN tracks securely.
Typical Causes of Communications Errors

- The cables are not connected correctly.
- The node number setting is incorrect.
- The baud rate setting is incorrect.
- There is a strong noise source, such as an inverter motor, near the Unit. Install the Unit as far as possible from the noise source or shield the noise source.


## Others

Use OMRON's XS8A-0441 or XS8A-0442 Connectors with the Unit.
Insert each connector into the Unit until the connector snaps in place. Make sure that terminal number 1 of the connector is on the lock lever side when inserting the connector.
Refer to the CompoBus/S Operation Manual (W266) for wiring the Unit.

## OmROn

## Sensor Amplifier Terminal

## Snap On to Connect and <br> Save Wiring Effort

- The 4-channel fiber photoelectric amplifiers in Terminals with connectors offer a low cost and space savings.
- The product lineup included Terminal Block Units for easy connection to sensors with amplifiers, limit switches, etc.
■ Connect to up to eight channels of sensors by using Expansion Blocks.



## - Features

Low Cost and Space Savings with
Four-channel Fiber Connectors

Just Snap On to Connect


## Connector Units

Fiber connector (1 channel)


Fiber connector (4 channels)


Terminal Block Unit


Various input units can be connected.

Photoelectric sensor


Proximity sensor

Basic switch and limit switch


## Ordering Information

CompoBus/S Sensor Amplifier Terminals

| Classification | I/O points |  |
| :--- | :--- | :--- |
| Communications | 4 | SRT1-TID04S |
|  |  | SRT1-TKD04S |
|  | Expansion |  |
|  |  | SRT1-XID04S |

## Connector Units

| Classification | Specifications | Model |
| :--- | :--- | :--- |
| E3X-N Connector Type | General-purpose, 1 channel | E3X-NT16 |
|  | Multi-functional, 1 channel | E3X-NT26 |
|  | Long distance, high accuracy, 1 channel | E3X-NH16 |
|  | Multi-functional, 4 channels | E3X-NM16 |
| Terminal Block Unit | One input point | E39-JID01 |

## Specifications

## ■ Characteristics

CompoBus/S Sensor Amplifier Terminals

| Item | Communication Terminals |  | Expansion Terminals |  |
| :---: | :---: | :---: | :---: | :---: |
| Model | SRT1-TID04S | SRT1-TKD04S | SRT1-XID04S | SRT1-XKD04S |
| Communications power supply voltage | 14 to 26.4 VDC (See note 1) |  | --- | --- |
| I/O points | 4 input points |  |  |  |
| Connected sensors | Total of four E3X-NT $\square 6$ or E39-JID01 <br> (See note 2) | One E3X-NM16 (See note 2) | Total of four E3X-NT $\square 6$ or E39-JID01 | One E3X-NM16 |
| Current consumption | 60 mA max. (See note 3) |  | 10 mA max. (See note 3) |  |
| Dielectric strength | 500 VAC for 1 min (1-mA sensing current between insulated circuits) |  |  |  |
| Noise immunity | Power supply normal: $\pm 600 \mathrm{~V}$ for 10 minutes with a pulse width of 100 ns to $1 \mu \mathrm{~s}$ Power supply common: $\pm 1,500 \mathrm{~V}$ for 10 minutes with a pulse width of 100 ns to $1 \mu \mathrm{~s}$ |  |  |  |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |  |  |  |
| Shock resistance | Malfunction: $\quad 200 \mathrm{~m} / \mathrm{s}^{2}$Destruction: $\quad 300 \mathrm{~m} / \mathrm{s}^{2}$ |  |  |  |
| Mounting method | M4 screw mounting or 35-mm DIN track mounting |  |  |  |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions (except the DIN track directions and a pulling force of 10 N |  |  |  |
| Terminal strength | No damage when 49 N pull load was applied for 10 s in all directions. Tighten each screw to a torque of 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$. |  |  |  |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) Storage: $\quad-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |  |  |  |
| Ambient humidity | Operating: 35\% to 85\% |  |  |  |
| Weight | 70 g max. | 65 g max . | 45 g max . | 35 g max . |

Note: 1. The communications power supply voltage must be 20.4 to 26.4 VDC if the Terminal is connected to 2 -wired proximity sensors.
2. When adding Connector Units, use SRT1-XID04S or SRT1-XKD04S.
3. The value doesn't include the current consumption of Connector Units.

## With E3X-N Connectors

| Model | E3X-NH16 | E3X-NT16 | E3X-NT26 | E3X-NM16 |
| :---: | :---: | :---: | :---: | :---: |
| Current consumption | 75 mA max. | 50 mA max. |  | 150 mA |
| Response time | 1 ms max. ( 4.0 ms max. when connected to the SRM1- $\square \square$ D04S) | $500 \mu$ S max. (2.0 ms max. when connected to the SRT1- $\square \square$ D04S) |  |  |
| Timer function | Not available |  | OFF-delay timer (fixed to 40 ms ) |  |
| Remote teaching input | Not available |  | Available (Remote teaching disabled) |  |
| Indicator | Orange LED: Lit during output operation Green LED: Lit with stable light reception or no light |  |  |  |
| Teaching confirmation function | Indicators (red/green LED) and buzzer |  |  |  |
| Output | Light ON and Dark ON switch selectable |  |  |  |
| Ambient illumination | Sunlight: 10,000 lux max.; incandescent lamp: 3,000 lux max. |  |  |  |
| Insulation resistance | $20 \mathrm{M} \Omega$ max. (at 500 VDC ) |  |  |  |
| Dielectric strength | 1,000 VAC at $50 / 60 \mathrm{~Hz}$ for 1 min |  |  |  |
| Vibration resistance | Destruction: 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |  |  |  |
| Shock resistance | Destruction:500 m/s ${ }^{2}$ |  |  |  |
| Mounting method | Connector connection to the SRT1- $\square \square \mathrm{D} 04 \mathrm{~S}$ |  |  |  |
| Mounting strength | No damage when 49 N pull load was applied for 10 s in all directions |  |  |  |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) Storage: $\quad-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |  |  |  |
| Ambient humidity | Operating: 35\% to 85\% |  |  |  |
| Weight | 30 g max. | 30 g max. | 30 g max. | 60 g max . |

Terminal Block Units

| Model | E39-JID01 |
| :---: | :---: |
| Input current | 10 mA max. |
| ON voltage | 12 VDC min. between input terminal and external sensor power supply |
| OFF voltage | 4 VDC max. between input terminal and external sensor power supply |
| OFF current | 1 mA max. |
| ON delay time | 1 ms max . (connected to SRT1- $\square \square \mathrm{D} 04 \mathrm{~S}$ ) |
| OFF delay time | $1.5 \mathrm{~ms} \mathrm{max}$. (connected to SRT1- $\square \square \mathrm{D} 04 \mathrm{~S}$ ) |
| Input indicators | LED (Orange) |
| External sensor current capacity | 50 mA max. |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |
| Shock resistance | Malfunction: $\quad 200 \mathrm{~m} / \mathrm{s}^{2}$ Destruction: $\quad 300 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting method | M4 screws or 35-mm DIN track mounting |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions (except the DIN track directions and a pulling force of 10 N |
| Terminal strength | No damage when 49 N pull load was applied for 10 s in all directions. Tighten each screw to a torque of 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$. |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) Storage: $\quad-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: 35\% to 85\% |
| Weight | 25 g max. |

## Nomenclature

## SRT1-TID04S <br> SRT1-TKD04S



Indicators

| Indicator | Name | Display | Color | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Lit | Green | The communications power supply is ON. |
|  |  | Not lit |  | The communications power supply is OFF. |
| COMM | Communications | Lit | Yellow | Normal communications. |
|  |  | Not lit |  | A communications error has occurred or the Unit is in standby status. |
| ERR | Communications error | Lit | Red | A communications error has occurred. |
|  |  | Not lit |  | Normal communications or the Unit is in standby status. |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT1-TID04


Mounting Holes


SRT1-XID04S


## SRT1-TKD04S



SRT1-XKD04S


Mounting Holes



E3X-NT $\square 6$


## E3X-NH16



Threshold indicators


E39-JID01


## Installation

- Internal Circuit Configuration E39-JID01



## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Terminal.
Refer to page 72 for precautions common to all SRT1 Terminals.

## General Safety Precautions

## Connector Units

Use only the Connector Units listed in this data sheet for the Sensor Amplifier Units.

## E39-JID01 Terminal Block Unit

Do not apply any voltage to the Terminal Block Unit.

## Correct Use

## Expanding Sensor Amplifier Terminals

1. Remove the cover from the side of the SRT1-T $\square$ D04S. (See Figure 1.)
2. When the cover is removed, you can see the expansion connector inside.
3. Connect this expansion connector to the connector located on the side of the SRT1-X $\square$ D04S. (See Figure 2.)


Figure 1


Figure 2

## Attaching and Removing Connector Units

(SRT1-TID04S, SRT1-XID04S, E3X-NT $\square 6$, E39-JID01)

## Attaching Connector Units

1. Hook Section A of the Connector Unit onto Section B of the Sensor Amplifier Terminal.
2. Push in the Connector Unit until Section C locks inside Section D of the Sensor Amplifier Terminal.


Bottom View


## Removing Connector Units

1. While pushing Section D, pull the Connector Unit in direction E.
2. When Section D releases from the lock, the Connector Unit can be removed.


## Attaching or Removing Connector Unit

## (SRT1-TKD04S, SRT1-XKD04S, E3X-NM16)

## Attaching Connector Unit

1. Hook Section A of the Connector Unit onto Section B of the Sensor Amplifier Terminal.
2. Push in the Connector Unit until Section C locks inside Section D of the Sensor Amplifier Terminal.


## Removing Connector Unit

1. While pushing Section D, pull the Connector Unit in direction E.
2. When Section D releases from the lock, the Connector Unit can be removed.


## Channel Numbers

Channel numbers 1 to 4 of the E3X-NM16 correspond to contact numbers 0 to 3 of the SRT1-TKD04S, and to contact numbers 4 to 7 of the SRT1-XKD04S.

## OmROn

## Analog Input Terminal

## Compact Analog Input Model is the <br> Same Shape as 16-point Remote I/O Terminals

- Allows flexible input point settings up to a maximum of four points.
■ Resolution: 1/6,000
■ Takes only 1 ms to exchange each input point.
- Wide input ranges available.

■ $105 \times 48 \times 50(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$


## Ordering Information

| Classification | I/O points | Model |
| :--- | :--- | :--- |
| Analog Input Terminal | 1 to 4 (selectable with DIP switch) | SRT2-AD04 |

Note: For details about connecting the SRT2-AD04 to the Master Unit. Refer to page 2.

## Specifications

## - Ratings

Input

| Item | Voltage input | Current input |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| Max. signal input | $\pm 15 \mathrm{~V}$ | $\pm 30 \mathrm{~mA}$ |  |  |  |
| Input impedance | $1 \mathrm{M} \Omega \mathrm{max}$. | Approx. $250 \Omega$ |  |  |  |
| Resolution | $1 / 6,000$ (FS) | $\pm 0.4 \% \mathrm{FS}$ |  |  |  |
| Total <br> accuracy | $\mathbf{2 5}{ }^{\circ} \mathbf{C}$ | $\pm 0.3 \% \mathrm{FS}$ |  |  |  |
|  | $\mathbf{- 1 0}$ to $\mathbf{5 5}{ }^{\circ} \mathbf{C}$ | $\pm 0.6 \% \mathrm{FS}$ |  |  |  |
| Conversion time | $4 \mathrm{~ms} / 4$ points, $3 \mathrm{~ms} / 3$ points, $2 \mathrm{~ms} / 2$ points, and $1 \mathrm{~ms} / 1$ point |  |  |  |  |
| Dielectric strength |  |  |  |  | 500 VAC for 1 min between communications power supply, analog input, and communications terminals (see note) |

Note: There is no insulation between analog inputs.

## ■ Characteristics

| Communications power supply voltage | 14 to 26.4 VDC (possible to provide through dedicated flat cable) |
| :--- | :--- |
| Current consumption | 100 mA max. |
| Connection method | Multi-drop method and T-branch method <br> Secondary branches cannot be connected to T-branch lines. |
| Dielectric strength | 500 VAC (between insulated circuits) |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0-\mathrm{mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}$ |
| Shock resistance | $200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting strength | No damage with 100 N pull load applied in all directions. |
| Terminal strength | No damage with 100 N pull load applied |
| Screw tightening torque | 0.3 to $0.5 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ |
| Storage: $-25^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ |  |
| Ambient humidity | Operating: $25^{\circ} \%$ to $85 \%$ (with no condensation) |
| Weight | Approx. 120 g |

## Nomenclature

SRT2-AD04


Indicators

| Indicator | Name | Color | Display | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Green | Lit | The communications power supply is ON. |
|  |  |  | Not lit | The communications power supply is OFF. |
| COMM | Communication | Yellow | Lit | Normal communications |
|  |  |  | Not lit | A communications error has occurred or the Unit is in standby status. |
| ERR | Communication error | Red | Lit | A communications error has occurred. |
|  |  |  | Not lit | Normal communications or the Unit is in standby status. |
| U.ERR | Unit error | Red | Lit | An error has occurred in the Unit. |
|  |  |  | Not lit | Normal communications or the Unit is in standby status. |

DIP Switch (SW101)
(Open cover to access.)

$\longrightarrow \mathrm{ON}$

| Pin 1 | Pin 2 | Input points |
| :--- | :--- | :--- |
| OFF | OFF | 4 points (default setting) |
| OFF | ON | 3 points (inputs 0 to 2 enabled) |
| ON | OFF | 2 points (inputs 0 and 2 enabled) |
| ON | ON | 1 point (input 0 enabled) |


| Pin 3 | Communications mode |
| :--- | :--- |
| OFF | High-speed communications (default setting) |
| ON | Long-distance communications |


| Pin 4 | Be sure to turn OFF. |
| :--- | :--- |


| Pin No. | Node address |
| :---: | :--- |
| Pin 5 | $2^{3}$ |
| Pin 6 | $2^{2}$ |
| Pin 7 | $2^{1}$ |
| Pin 8 | $2^{0}$ |

The default setting is for all of these pins to be OFF.

DIP Switch (SW102)
(Open cover to access.)



| Pin 1 | Pin 2 | Pin 3 | Range for inputs 0, 1 |
| :--- | :--- | :--- | :--- |
| Pin 4 | Pin 5 | Pin 6 | Range for inputs 2, 3 |
| OFF | OFF | OFF | 0 to $5(\mathrm{~V})$ (default setting) |
| ON | OFF | OFF | 1 to $5(\mathrm{~V})$ |
| OFF | ON | OFF | 0 to $10(\mathrm{~V})$ |
| ON | ON | OFF | -10 to $10(\mathrm{~V})$ |
| OFF | OFF | ON | 4 to $20(\mathrm{~mA})$ |
| ON | OFF | ON | 0 to $20(\mathrm{~mA})$ |
| Do not make any settings other than the ones listed above. |  |  |  |


| Pin 7 | Mean value processing |
| :--- | :--- |
| OFF | Without mean value processing (default setting) |
| ON | With mean value processing (mean for 8 operations) |


| Pin 8 | Be sure to turn OFF. |
| :--- | :--- |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.

## SRT2-AD04



## Installation

- Internal Circuit Configuration



## - Terminal Arrangement

## SRT2-AD04

| $\begin{gathered} \mathrm{BD} \\ \mathrm{H} \\ \hline \end{gathered}$ |  | BS | AG | V0 |  | V1 + |  |  |  | + | 13 <br> + |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BD | BS | NC | AG | 0- | NC | 1- | NC | 2- | NC | 3 |  |

Note: When the input is current input, short-circuit the " $V+$ " terminals and the " $\mathrm{I}+$ " terminals. When short-circuiting, use the short-circuiting tool provided as an accessory.

## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using
the Unit.
For details about general precautions, refer to page 72.

## Connections to the Master Unit

Connections cannot be made to the following Master Units. If the fol-
lowing Master Units are connected, incorrect data may be trans-
ferred.
C200HW-SRM21 (-V1 and later versions supported)
CQM1-SRM21 (-V1 and later versions supported)
SRM1-C0 $\square$, SRM1-C0 $\square-\mathrm{V} 1$ (-V2 and later versions supported)
C200PC-ISA $\square 2-$ SRM
3G8B3-SRM0 $\square$
SDD-CS1 (made by NKE Ltd.)

## OmROn

## Analog Output Terminal

## Compact Analog Output Model is the <br> Same Shape as 16 -point Remote I/O Terminals

■ Two output points or 1 output point is selectable.
■ Resolution: 1/6,000
■ $105 \times 48 \times 50(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$


## Ordering Information

| Classification | I/O points | Model |
| :--- | :--- | :--- |
| Analog Output Terminal | 1 or 2 (selectable with DIP switch) | SRT2-DA02 |

Note: For details about connecting the SRT2-DA02 to the Master Unit, refer to page 2.

## Specifications

## ■ Ratings

Output

| Item | $\quad$ Voltage output | Current output |
| :--- | :--- | :--- |
| External output permissible <br> load resistance | $5 \mathrm{k} \Omega \mathrm{min}$. | $600 \Omega$ max. |
| Output impedance | $0.5 \Omega \mathrm{max}$. | --- |
| Resolution | $1 / 6,000$ (FS) |  |
| Total <br> accuracy | $\mathbf{2 5}{ }^{\circ} \mathbf{C}$ | $\pm 0.4 \% \mathrm{FS}$ |
|  | $\mathbf{- 1 0}$ to $\mathbf{5 5}{ }^{\circ} \mathbf{C}$ | $\pm 0.8 \% \mathrm{FS}$ |
| Conversion time | $2 \mathrm{~ms} / 2$ points and $2 \mathrm{~ms} / 1$ point |  |
| Dielectric strength | 500 VAC for 1 min between communications power supply, analog output, and communications terminals (see note) |  |

Note: There is no insulation between analog outputs.
■ Characteristics

| Communications power supply voltage | 14 to 26.4 VDC (power supply possible from dedicated flat cable) |
| :--- | :--- |
| Current consumption (see note) | 170 mA max. |
| Connection method | Multi-drop method and T-branch method <br> Secondary branches cannot be connected to T-branch lines. |
| Dielectric strength | 500 VAC (between insulated circuits) |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0-\mathrm{mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}$ |
| Shock resistance | $200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting strength | No damage when 100 N pull load was applied in all directions |
| Terminal strength | No damage when 100 N pull load was applied |
| Screw tightening torque | 0.3 to $0.5 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ <br> Storage: $-25^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ <br> Ambient humidity <br> Opeight Operating: $25^{2}$ to $85 \%$ (with no condensation) |

Note: The above current consumption is the value with all points turned ON excluding the current consumption of the external load.

Nomenclature
SRT2-DA02


Indicators

| Indicator | Name | Color | Display | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Green | Lit | The communications power supply is ON. |
|  |  |  | Not lit | The communications power supply is OFF. |
| COMM | Communication | Yellow | Lit | Normal communications |
|  |  |  | Not lit | A communications error has occurred or the Unit is in standby status. |
| ERR | Communication error | Red | Lit | A communications error has occurred. |
|  |  |  | Not lit | Normal communications or the Unit is in standby status. |
| U.ERR | Unit error | Red | Lit | An error has occurred in the Unit. |
|  |  |  | Not lit | A communications error has occurred or the Unit is in standby status. |

DIP Switch (SW101)
(Open cover to access.)


SW1 SW2 SW3 SW4
SW5
SW6
SW7
SW8
$\longrightarrow \mathrm{ON}$

DIP Switch (SW102)
(Open cover to access.)



| Pin 1 | Pin 2 | Pin 3 | Range for output 0 |
| :--- | :--- | :--- | :--- |
| Pin 4 | Pin 5 | Pin 6 | Range for output 1 |
| OFF | OFF | OFF | 0 to $5(\mathrm{~V})$ (default setting) |
| ON | OFF | OFF | 1 to $5(\mathrm{~V})$ |
| OFF | ON | OFF | 0 to $10(\mathrm{~V})$ |
| ON | ON | OFF | -10 to $10(\mathrm{~V})$ |
| OFF | OFF | ON | 4 to $20(\mathrm{~mA})$ |
| Do not make any settings other than the ones listed above. |  |  |  |


| Pin 7 | Pin 8 | Output during communications error |
| :--- | :--- | :--- |
| OFF | OFF | Clear at the output lower limit when <br> communications error occurs. (default <br> setting) |
| OFF | ON | Clear at the output upper limit when <br> communications error occurs. |
| ON | OFF | Clear at the output lower limit when <br> communications error occurs (however, if <br> the range is -10 to 10 V, the output will be <br> 0). |
| ON | ON | Output held when communications error <br> occurs. |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.

## SRT2-DA02



Installation

- Internal Circuit Configuration

SRT2-DA02


## ■ Terminal Arrangement

SRT2-DA02


## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.
For details about general precautions, refer to page 72.

## Connections to the Master Unit

Connections cannot be made to the following Master Units. If the following Master Units are connected, incorrect data may be transferred.
C200HW-SRM21 (-V1 and later versions supported)
CQM1-SRM21 (-V1 and later versions supported)
SRM1-C0 $\square$, SRM1-C0 $\square-\mathrm{V} 1$ (-V2 and later versions supported)
C200PC-ISA $\square 2$-SRM
3G8B3-SRM0 $\square$
SDD-CS1 (made by NKE Ltd.)

## omROn

## Remote I/O Module

## Module Type that Allows PCB Mounting

■ Compact size at $60 \times 16 \times 35(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$
■ Lineup now includes the 16-point input model and 16-point output model.


## Ordering Information

| I/O classification | Internal I/O circuit <br> common | I/O points | Rated voltage | I/O rated voltage | Model |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Input | NPN (+ common) | 16 | 24 VDC | 24 VDC | SRT1-ID16P |
| Output | NPN (- common) |  |  |  | SRT1-OD16P |

## Specifications

## ■ Ratings

Input (SRT1-ID16P)

| Input current | 2 mA max./point |
| :--- | :--- |
| ON delay time | 1.5 ms max. |
| OFF delay time | 1.5 ms max. |
| ON voltage | 15 VDC min. between each input terminal and BS+ terminal |
| OFF voltage | 5 VDC max. between each input terminal and BS + terminal |

Output (SRT1-OD16P)

| Rated output current | $0.2 \mathrm{~A} /$ point, $0.6 \mathrm{~A} /$ common |
| :--- | :--- |
| Residual voltage | 0.6 V max. between each output terminal and G terminal at 0.2 A |
| Leakage current | 0.1 mA max. between each output terminal and G terminal at 24 VDC |

## ■ Characteristics

| Communications power supply <br> voltage | 20.4 to 26.4 VDC |
| :--- | :--- |
| I/O power supply voltage | $24 \mathrm{VDC}+10 \% /-15 \%$ |
| Current consumption (see note) | 60 mA max. |
| Connection method | Multi-drop method and T-branch method <br> Secondary branches cannot be connected to T-branch lines. |
| Connecting Units | 8 Input Terminals and 8 Output Terminals per Master |
| Dielectric strength | 500 VAC for 1 min (1-mA sensing current between insulated circuits) |
| 5-V output current | 20 mA max. $5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ ) |
| LED drive current (COMM, ERR) | 10 mA max. (5 VDC) |
| SW carry current <br> (ADR0 to 3, HOLD) | 1 mA max. |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: $-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85^{\circ} \%$ |
| Weight | 35 g max. |

Note: The above current consumption is the value with all points turned ON excluding the current consumption of the external sensor connected to the input model and the current consumption of the load connected to the output model.

## Dimensions

Note: All units are in millimeters unless otherwise indicated.

## SRT1-ID16P SRT1-OD16P




No cumulative tolerance allowed

## Installation

## ■ Internal Circuit Configuration



## ■ External Connections

## Input Module (SRT1-ID16P)



Node Number Settings and Output HOLD/CLEAR Mode


Note: NC in parentheses is for the Input Modules.
Note: Refer to the CompoBus/S Operation Manual (W266) for details on the switch.

SRT1-OD16P


Output Module (SRT1-OD16P)


Indicators


R: LED current limiting resistor
LED1: LED for COMM
LED2: LED for ERR
The maximum current for LED1 and 2 is 10 mA .

The 5-V Output Terminals have positive power supplies (maximum output current of 20 mA ) for the ERR and COMM LEDs. Recommended LED colors are red for ERR and yellow for COMM.

## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.
Refer to page 72 for precautions common to all SRT1 Terminals.

## Correct Use

## Noise Protection Circuit

Add the following protection circuit if noise is generated from the power supply, input section, or output section.

## Power Supply Noise Protection Circuit



L: Coil for the common mode Install the coil near the SRT1

## Input Section Noise Protection Circuit



C: $\quad 0.1 \mu \mathrm{~F}$ min.
R: Resistor for limiting current to PC
PC: Photocoupler

Output Section Noise Protection Circuit


| $V_{1}$ and $V_{2}:$ | Power supply. |
| :--- | :--- |
| $R:$ | Resistor for limiting current to PC |
| PC: | Photocoupler |

## 5-V Output Terminals

The 5-V Output Terminals have positive power supplies (maximum output current of 20 mA ) for the ERR and COMM LED. Use them as shown below. Recommended LED colors are red for ERR and yellow for COMM.

Wiring Method


R: LED current limiting resistor
LED1: LED for COMM
LED2: LED for ERR
The maximum current for the LED1 and 2 is 10 mA .

## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Terminal.
The following precautions are the same for all SRT1 Terminals. Refer also to the precautions specified for individual Terminals.

## General Safety Precautions

## Wiring

Turn OFF the Unit before wiring the Unit and do not remove the terminal block cover or touch the terminal block while the Unit is turned ON, otherwise an electric shock may occur.
Do not impose any voltage other than the rated voltage on the input terminal. Doing so may result in damage to the Unit or cause the Unit to malfunction.

## Relay I/O Type

SRT1-ROC08 and SRT2-ROC16
Do not connect the Unit to loads operating at any voltage or consuming a total current exceeding the permissible switching voltage or current of the Unit. Doing so may result in the faulty insulation, contact weld, or faulty contact of the relays, or damage to the relays, or cause the relays to malfunction or burn.
The life of a relay varies with the switching condition. Test the relays under the actual operating conditions before using the relays within the permissible switching frequency. The use of deteriorated relays may result in the faulty insulation of the relays or cause the relays to burn.
Do not use the Unit in places with inflammable gas. Doing so may result in a fire or explosion due to the heat of the relays or a spark from the relays when they are switched.
Transistor, Power MOS FET, and SSR I/O Types SRT1-OD04, SRT2-OD08, SRT2-OD16, SRT1-OD16P, SRT1-ROF08, and SRT2-ROF16
Do not connect the Unit to loads consuming a total current exceeding the rated output current of the Unit. Doing so may damage the output element and a short or open-circuit malfunction may result.
If the Unit is connected to a DC inductive load, connect a diode to the Unit to protect the Unit from counter-electromotive voltage, otherwise the counter-electromotive voltage may damage the output element and a short or open-circuit malfunction may result.

## Correct Use

## Replacing Relays

Use the relay removal tool to the left of the screw terminals to replace relays.
Turn OFF the Unit to replace relays, otherwise an electric shock may occur or the Unit may malfunction.

## Installation Environment

Do not install the Unit in the following places. Doing so may result in damage to the Unit or cause the Unit to malfunction.

- Places with direct sunlight.
- Places with ambient temperature ranges not within $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$.
- Places with rapid temperature changes resulting in condensation or relative humidity ranges not within $10 \%$ to $90 \%$.
- Places with corrosive or inflammable gas.
- Places with excessive dust, salinity, or metal powder.
- Places with vibration or shock affecting the Unit.
- Places with water, oil, or chemical sprayed on the Unit.


## Screw Tightening Torques

Tighten all screws of the Unit properly, otherwise the Unit may malfunction.

- Tighten each terminal screw to a torque of 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}(6.2$ to $12.0 \mathrm{kgf} \cdot \mathrm{cm})$.
- Tighten each mounting screw to a torque of 0.6 to $0.98 \mathrm{~N} \cdot \mathrm{~m}(6.2$ to $10.0 \mathrm{kgf} \bullet \mathrm{cm})$.



## Cleaning

Use alcohol or benzine to clean the surface of the Unit. Do not use paint thinner to clean the surface, otherwise the surface will be damaged or discolored.

## Handling

Do not drop the Unit or shock or vibrate the Unit excessively. Doing so may result in damage to the Unit or cause the Unit to malfunction.

## Disassembling, Repairing, and Modifying

Do not disassemble, repair, or modify the Unit, otherwise an electric shock may occur or the Unit may malfunction.

## Position Driver

## Advanced Servodrivers with Positioner Functions

## DIO and CompoBus/S Models are Newly Added

- Servodriver and positioner are combined into one Unit.
- Conventional U-series, U-series UE type, H -series, and M -series AC Servomotors can be used.
- Feeder control/DTP control and single operation/ automatic incremental/continuous operation are available.



## Ordering Information

| Specifications |  | Model |  |
| :--- | :--- | :--- | :--- |
| CompoBus/S models | For 200-VAC input | 6 A | FND-X06H-SRT |
|  | 12 A | FND-X12H-SRT |  |
|  | 25 A | FND-X25H-SRT |  |
|  | 50 A | FND-X50H-SRT |  |
|  | For 100-VAC input | 6 A | FND-X06L-SRT |
|  |  | 12 A | FND-X12L-SRT |

Note: For details, refer to OMNUC FND-X-series User's Manual (I524).

## Specifications

## ■ General Specifications

| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ <br> Storage: $-10^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Ambient humidity | Operating: $35 \%$ to $90 \%$ (with no icing) <br> Storage: $35 \%$ to $90 \%$ (with no icing) |
| Operating atmosphere | No corrosive gases |
| Dielectric strength | $1,500 \mathrm{VAC}_{\mathrm{RMS}}$ for 1 min at $50 / 60 \mathrm{~Hz}$ |
| Insulation resistance | $5 \mathrm{M} \Omega$ min. (at 500 VDC ) between power input terminals and between the power terminal and <br> the case |
| Vibration resistance | 10 to 150 Hz in $\mathrm{X}, \mathrm{Y}$, and Z directions with $0.10-\mathrm{mm}$ single amplitude; acceleration: $9.8 \mathrm{~m} / \mathrm{s}^{2}$ <br> max.; time coefficient: $8 \mathrm{~min} ; 4$ sweeps |
| Shock resistance | $98 \mathrm{~m} / \mathrm{s}^{2}$ max., three times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |
| Degree of protection | Built into panel (IP00) |

## Performance Specifications

| Model (see note 1) |  | FND-X06H-SRT | FND-X12H-SRT | FND-X25H-SRT | FND-X06L-SRT | FND-X12L-SRT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Continuous output current (0-P) |  | 2.0 A | 4.8 A | 8.0 A | 2.0 A | 3.0 A |
| Momentary maximum output current (0-P) |  | 6.0 A | 12 A | 25 A | 6.0 A | 12 A |
| Input power supply |  | Single-phase 200/240 VAC (170 to 264 V) $50 / 60 \mathrm{~Hz}$ |  |  | Single-phase 100/115 VAC (85 to$127 \text { V) } 50 / 60 \mathrm{~Hz}$ |  |
| Position/speed feedback | U Series (INC) | Optical Incremental encoder, 2,048 pulses/revolution |  |  |  |  |
|  | U Series (ABS) | Optical Absolute encoder, 1,024 pulses/revolution |  |  |  |  |
|  | U-UE Series | Optical Incremental encoder, 1,024 pulses/revolution |  |  |  |  |
|  | H Series | Magnetic Incremental encoder, 2,000 pulses/revolution |  |  |  |  |
|  | M Series | Resolver, absolute accuracy $0.18^{\circ}$ max.; ambient temperature $25^{\circ}$ |  |  |  |  |
| Applicable load inertia | U Series (INC) | Maximum of 30 times motor's rotor inertia |  | Maximum of 20 times motor's rotor inertia | Maximum of 30 times motor's rotor inertia |  |
|  | U Series (ABS) | Maximum of 20 times motor's rotor inertia |  | Maximum of 18 times motor's rotor inertia | Maximum of 20 times motor's rotor inertia |  |
|  | U-UE Series | Maximum of 30 times motor's rotor inertia |  | Maximum of 20 times motor's rotor inertia | Maximum of 30 times motor's rotor inertia |  |
|  | H Series | Maximum of 10 times motor's rotor inertia |  |  |  |  |
|  | M Series | Maximum of 10 times motor's rotor inertia |  |  |  |  |
| Inverter method |  | PWM method based on IGBT |  |  |  |  |
| PWM frequency |  | 10 kHz |  |  |  |  |
| Weight |  | Approx. 1.5 kg |  | Approx. 2.5 kg | Approx. 1.5 kg |  |
| Frequency response (speed control) |  | 100 Hz (at a load inertia equivalent to motor's rotor inertia) |  |  |  |  |
| Position loop gain |  | 1 to 200 (rad/s) |  |  |  |  |
| Feed forward |  | 0\% to $200 \%$ of speed reference |  |  |  |  |
| Pulse rate |  | 1/32,767 = (pulse rate $1 /$ pulse rate 2) $=32,767 / 1$ |  |  |  |  |
| Positioning completion width |  | 1 to 32,767 (pulses) <br> U Series (INC): 8,192 pulses/revolution; U Series (ABS): 4,096 pulses/revolution; <br> M Series 24,000 pulses/revolution |  |  |  |  |
| Acceleration/Deceleration time |  | 0 to 9,999 (ms); acceleration and deceleration times set separately. Two types can be set for each. S-curve acceleration/deceleration function available (filter time constant: 0.00 to 32.76 s). |  |  |  |  |
| Sequence input |  | 19 pts. (limit inputs, origin proximity, RUN command, START, alarm reset, origin search, JOG operation, teaching, point selection, position data, deceleration stop) <br> Photocoupler input: 24 VDC, 8 mA <br> External power supply: $24 \mathrm{VDC} \pm 1 \mathrm{~V}, 150 \mathrm{~mA}$ min. |  |  |  |  |
| Sequence output |  | 15 pts. (brake output, READY, origin search completion, origin, teaching, motor running, positioning completion, alarm, point output, position selection, speed selection) Open collector output: 24 VDC, 40 mA |  |  |  |  |
| Monitor output (See note 2.) | Speed monitor | $3 \mathrm{~V} /$ motor's rated speed (output accuracy: approx. $\pm 10 \%$ ) |  |  |  |  |
|  | Current monitor | $3 \mathrm{~V} /$ motor's maximum current (output accuracy: approx. $\pm 10 \%$ ) |  |  |  |  |
| Regenerative absorption capacity |  | $13 \mathrm{~W}+17 \mathrm{~J}$ | $24 \mathrm{~W}+17 \mathrm{~J}$ | $37 \mathrm{~W}+22 \mathrm{~J}$ | $13 \mathrm{~W}+17 \mathrm{~J}$ | $17 \mathrm{~W}+17 \mathrm{~J}$ |
| Protective functions |  | Overcurrent, overvoltage, voltage drop, resolver disconnection, power status error, clock stopped, overcurrent (soft), speed amp saturation, motor overload, temporary overload, resolver error, speed over, error counter over, parameter setting error, software limit over, coordinate counter over, overrun, encoder disconnection, encoder communications error, absolute encoder backup error, absolute encoder checksum error, absolute encoder absolute error, absolute encoder over speed, encoder data not transmitted, BCD data error, present value undetermined, PTP data not set |  |  |  |  |

Note: 1. When using the 100-VAC-input Position Drivers in combination with the U-series or U-series UE type models, use 200-VAC Servomotors (-HA, -TA , or -H models).
2. For the monitor output, the monitor items and voltage polarity can be set by parameter UP-25 (monitor output selection).

## Dimensions

Note: All units are in millimeters unless otherwise indicated.

## 200-VAC FND-X06H-SRT/-X12H-SRT

100-VAC FND-X06L-SRT/-X12L-SRT


## 200-VAC FND-X25H-SRT



- Position Drivers

| Item | Model | Continuous output current (0-P) | Momentary maximum output current (0-P) | Input power supply | Inverter method | $\begin{gathered} \text { PWM } \\ \text { fre- } \\ \text { quency } \end{gathered}$ | Weight |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 200-VAC input | FND-X06H-SRT | 2.0 A | 6.0 A | Single-phase 200/240 VAC (170 to 264 V ) $50 / 60 \mathrm{~Hz}$ | PWM method based on IGBT | $\begin{aligned} & \hline 10 \\ & \mathrm{kHz} \end{aligned}$ | Approx. <br> 1.5 kg |
|  | FND-X12H-SRT | 4.8 A | 12 A |  |  |  |  |
|  | FND-X25H-SRT | 8.0 A | 25 A |  |  |  | Approx. 2.5 kg |
| 100-VAC input | FND-X06L-SRT | 2.0 A | 6.0 A | Single-phase 100/115 VAC (85 |  |  | Approx. <br> 1.5 kg |
|  | FND-X12L-SRT | 3.0 A | 12 A | $\begin{aligned} & \text { to } 127 \mathrm{~V} \text { ) } \\ & 50 / 60 \mathrm{~Hz} \end{aligned}$ |  |  |  |

## Peripheral Devices

## Connectors, Cables, and

Terminal-block Terminator

Dedicated Flat Cable Allows<br>Communication Path Extension and<br>T-branching with Ease

Ordering Information

| Product | Model | Specification |  |
| :--- | :--- | :--- | :--- |
| Branch Connector | SCN1-TH4 | --- |  |
| Extension Connector |  |  |  |
| Connector Terminator |  |  |  |
| Communications Cable |  | SCN1-TH4E |  |

Note: Branch Connectors and Extension Connectors are sold in blocks of 10 Units.

## Specifications

## ■ Ratings/Characteristics

| Rated current | 4 A |
| :--- | :--- |
| Contact resistance | $20 \mathrm{~m} \Omega \mathrm{max}$. |
| Insulation resistance | $1,000 \mathrm{M} \Omega \mathrm{min}$. (at 500 VDC$)$ |
| Withstand voltage | $1,000 \mathrm{VAC}$ for 1 min, leakage current: 1 mA max. |
| Cable pulling strength | $50 \mathrm{~N}(5.1 \mathrm{kgf}) \mathrm{min}$. |
| Operating temperature | $-20^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |

## - Materials

| Housing | PA66 resin (UL94V-2) <br> Branching and extension: Gray <br> Cover <br> Terminator: Black |
| :--- | :--- |
| Contact | Phosphor bronze and nickel base, tin plated |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.

## SCN1-TH4 Branch Connector

 SCN1-TH4E Extension Connector


SCN1-TH4T Connector Terminator



## SRS1-T Terminal-block Terminator



## Mounting Holes



## Precautions

Refer to the CompoBus/S Operation Manual (W266) before using the Unit.

## Correct Use

The SCN1-TH4, SCN1-TH4E, and SCN1-TH4T are dedicated connectors for CompoBus/S. Always use dedicated CompoBus/S cables with these connectors.
Do not locate the cables in places where excessive force may be imposed on the connectors of the cables such as an area where cables may entangle feet.
These connectors cannot be reused once they have been attached to cables. Use new connectors if they were not attached to cables properly.
Refer to the CompoBus/S Operation Manual (W266) to assemble the connectors.

## Ordering Information

Note: Abbreviations for standards: U: UL, C: CSA, CE: EC Directive

| Product | Appearance | Model | Specifications | Standards |
| :---: | :---: | :---: | :---: | :---: |
| Master Control Units |  | SRM1-C01-V2 | Stand-alone model with built-in controller functions (without RS-232C) | UL <br> CSA <br> CE <br> (see note 2) |
|  |  | SRM1-C02-V2 | Stand-alone model with built-in controller functions and RS-232C |  |
| Master Units |  | C200HW-SRM21-V1 | For C200HX (-ZE), C200HG (-ZE), C200HE (-ZE), and C200HS |  |
|  |  | CQM1-SRM21-V1 | For CQM1 |  |
| SYSMAC Boards |  | C200PC-ISA02-SRM C200PC-ISA12-SRM | For $\mathrm{C} 200 \mathrm{HX} / \mathrm{HG} / \mathrm{HE}$ | --- |
| I/O Link Unit |  | CPM1A-SRT21 | 8 inputs 8 outputs | UL <br> CSA <br> CE <br> (see <br> note 2) |
| Remote Terminals (Transistor Models) |  | SRT1-ID04 <br> SRT1-ID04-1 <br> SRT2-ID08 <br> SRT2-ID08-1 <br> SRT2-ID16 <br> SRT2-ID16-1 <br> SRT1-OD04 <br> SRT1-OD04-1 <br> SRT2-OD08 <br> SRT2-OD08-1 <br> SRT2-OD16 <br> SRT2-OD16-1 | 4 transistor input (NPN) <br> 4 transistor inputs (PNP) <br> 8 transistor inputs (NPN) <br> 8 transistor inputs (PNP) <br> 16 transistor inputs (NPN) <br> 16 transistor inputs (PNP) <br> 4 transistor outputs (NPN) <br> 4 transistor outputs (PNP) <br> 8 transistor outputs (NPN) <br> 8 transistor outputs (PNP) <br> 16 transistor outputs (NPN) <br> 16 transistor outputs (PNP) |  |
| Remote Terminals (M3 Terminal Block Models) |  | SRT1-ID16T <br> SRT1-ID16T-1 <br> SRT2-MD16T <br> SRT2-MD16T-1 <br> SRT2-OD16T <br> SRT2-OD16T-1 | 16 transistor inputs (NPN) 16 transistor inputs (PNP) 16 transistor I/O points (NPN) 16 transistor I/O points (PNP) 16 transistor outputs (NPN) 16 transistor outputs (PNP) | CE (see note 2) |
| Remote Terminals (Relay-mounted Models) |  | SRT2-ROC08 <br> SRT2-ROC16 <br> SRT2-ROF08 <br> SRT2-ROF16 | 8 relay outputs <br> 16 relay outputs <br> 8 power MOS FET relay outputs <br> 16 power MOS FET relay outputs | UL CSA CE (see note 2) |
| Connector Terminals |  | SRT2-VID08S <br> SRT2-VID08S-1 <br> SRT2-VOD08S <br> SRT2-VOD08S-1 <br> SRT2-VID16ML <br> SRT2-VID16ML-1 <br> SRT2-VOD16ML <br> SRT2-VOD16ML-1 <br> SRT2-ATT01 <br> SRT2-ATT02 | 8 transistor input (NPN) <br> 8 transistor inputs (PNP) <br> 8 transistor outputs (NPN) <br> 8 transistor outputs (PNP) <br> 16 transistor inputs (NPN) <br> 16 transistor inputs (PNP) <br> 16 transistor outputs (NPN) <br> 16 transistor outputs (PNP) <br> Mounting hook A <br> Mounting hook B | CE (see note 2) |
| Sensor Terminals |  | SRT1-ID08S SRT1-ND08S SRT1-OD08S | 8 inputs (NPN) <br> 4 automatic teaching points (NPN) <br> 8 outputs | --- |


| Product | Model | Specifications |
| :--- | :--- | :--- | :--- | :--- |
| Sensor Amplifier Terminals |  | SRT1-TID04S <br> SRT1-TKD04S <br> dor CompoBus/S |
| SRT1-XID04S |  |  |
| SRT1-XKD04S |  |  |

Note: 1. Refer to the C200HS Catalog (P32).
Refer to the C200HX/C200HG/C200HE (-ZE) Catalog

## 2. Information on EC Directives

Individual OMRON products that comply with EC Directives conform to the common emission standards of EMC Directives. However, the emission characteristics of these products installed on customers' equipment may vary depending on the configuration, wiring, layout, and other conditions of the control panel used. For this reason, customers are requested to check whether the emission characteristics of the entire machine or equipment comply with the EMC Directives.

## Model Number Legend



1. Communications Mode

1: High-speed communications mode
2: High-speed/Long-distance communications mode
2. I/O Module Replacement

None: Impossible
R: Possible (Relays and power MOS FET relays)
3. I/O Specifications

I: Input
O: Output
N : Input and output (with remote teaching)
AD: Analog input
DA: Analog output
4. $I / O$ Voltage Specifications

D: DC
C: AC/DC (contact type)
F: AC/DC (power MOS FET type)
5. I/O Points

04: 4 points
08: 8 points
16: 16 points
6. I/O Connection Method

None: Screw terminals
S: Connector
P: PCB terminals
7.

None: NPN
-1: PNP

Notes:

